

Newsvendor under Mean-Variance Ambiguity and Misspecification

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Consider a newsvendor problem with an unknown demand distribution. When addressing the issue of distributional uncertainty, we distinguish ambiguity under which the newsvendor does not differentiate demand distributions of common distributional characteristics (*e.g.*, mean and variance) and misspecification under which such characteristics might be misspecified (due to, *e.g.*, estimation error and/or distribution shift). The newsvendor hedges against ambiguity and misspecification by maximizing the worst-case expected profit regularized by a distribution's distance to an ambiguity set of distributions with some specified characteristics. Focusing on the popular mean-variance ambiguity set and optimal-transport cost for the misspecification, we show that the decision criterion of misspecification aversion possesses insightful interpretations as distributional transforms and convex risk measures. We derive the closed-form optimal order quantity that generalizes the solution of the seminal Scarf model under only ambiguity aversion. This highlights the impact of misspecification aversion: the optimal order quantity under misspecification aversion can decrease as the price or variance increases, reversing the monotonicity of that under only ambiguity aversion. Hence, ambiguity and misspecification, as different layers of distributional uncertainty, can result in distinct operational consequences. We quantify the finite-sample performance guarantee, which consists of two parts: the in-sample optimal value and the out-of-sample effect of misspecification that can be decoupled into estimation error and distribution shift. This theoretically justifies the necessity of incorporating misspecification aversion in a non-stationary environment, which is also well demonstrated in our experiments with real-world retailing data. Our framework can be extended to consider multiple products, distributional characteristics specified via optimal transport, and misspecification measured by ϕ -divergence.

Key words: newsvendor, model misspecification, moment condition, optimal transport, performance guarantee.

1. Introduction

Newsvendor model, as a building block for dealing with uncertain demand in operations management, has found its successful applications in various domains, including inventory management (Chen et al. 2007, Berling and Martínez-de-Albéniz 2011, Donohue et al. 2018), revenue manage-

ment (Besbes et al. 2018), capacity planning (Simchi-Levi and Wei 2015), and healthcare (Olivares et al. 2008), to name a few. When the true demand distribution is fully known, the celebrated *critical fractile* determines an optimal order quantity that maximizes the expected profit. In practice, however, the newsvendor often faces incomplete knowledge about the demand distribution. Hence, it is often difficult (if not impossible) to precisely articulate the true demand distribution, causing a commonly known issue of demand *ambiguity* to the newsvendors.

A natural way to mitigate demand ambiguity is to utilize only partial distributional characteristics available for decision-making. In this vein, mean and variance—arguably two of the most widely used and easy-to-estimate statistics that capture the key *location* and *dispersion* characteristics of the underlying distribution respectively—have been employed. This can be traced back to the seminal work of Scarf (1958) that considers an *ambiguity-averse* newsvendor model maximizing the worst-case expected profit over an ambiguity set of probability distributions with the same mean and variance.¹ In essence, with such a mean-variance ambiguity set, the newsvendor specifies her belief about the (true) demand distribution via an approximation by using mean and variance characteristics. This is also well statistically justified,² especially in the context of the newsvendor problem, by noting that the single-dimensional demand distribution’s quantile (*i.e.*, the critical-fractile solution) can be largely characterized by the mean and variance statistics, or even *perfectly* determined under many common distributions (*e.g.*, elliptical, uniform, and exponential, see Meyer 1987). This also underpins the implication that solutions of the ambiguity-averse and nominal ambiguity-neutral models characterized by the same mean and variance can share several key features in operational properties: for instance, the order quantity increases in price (see Sections 2 and 4.2 for more details). Apart from the newsvendor problem (Perakis and Roels 2008, Han et al. 2014), the mean-variance ambiguity set has been studied in stochastic optimization (Popescu 2007), and used in various applications, including recent literature on decision theory (Müller et al. 2022), mechanism design/pricing (Carrasco et al. 2018, Chen et al. 2022), and risk management (Li et al. 2018, Nguyen et al. 2021).

However, in many practical situations, it is still challenging to accurately estimate the mean and variance of the demand. For instance, in retailing industries (*e.g.*, E-commerce, grocery and supermarket), more and more commodities are of ever shorter life cycles (Calvo and Martínez-de Albéniz 2016, Sun et al. 2021), and many enterprises lack the resources for effective data collection and

¹ A more general version of the Scarf model allows the mean and variance to be uncertain and to vary within some predetermined intervals, which turns out to be equivalent to the Scarf model characterized by the predetermined lower bound of mean and upper bound of variance (see Natarajan et al. 2011 or Remark 1).

² It is well known that under mild conditions, a probability distribution can be *uniquely* determined by all integer-order moments (Durrett 2019), among which the first two moments are the most commonly used ones.

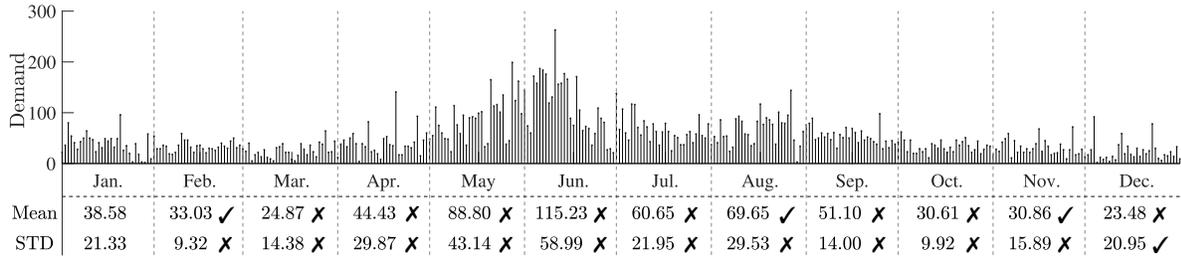


Figure 1 Daily demand of a product of drinking water over one year with monthly mean and standard deviation (STD). The sign ‘✓’ (resp., ‘✗’) means that the monthly mean or STD falls in (resp., does not fall in) the 95% confidence interval estimated with the demand data in the preceding month. Notably, in only 2 out of 11 (resp., 1 out of 11) instances, the mean (resp., variance) falls within the confidence interval.

Notes. The confidence intervals on the mean and variance are constructed leveraging the t -statistic and χ^2 -statistic, respectively, without knowing the true values of mean and variance.

analysis, especially for new products (Saghafian and Tomlin 2016, Feiler and Tong 2022). Therefore, insufficient historical data—even when the underlying demand process is stationary—can result in non-negligible *estimation error* that challenges the newsvendors’ decision under demand ambiguity. On the other hand, the uncertainty is exacerbated when the underlying demand process becomes non-stationary, due to, for instance, the complicated (time-varying) determinants for the demand (Keskin and Zeevi 2017, Keskin et al. 2022). This can lead to *distribution shift*—the future demand distribution is different from the past³—under which the mean and variance characteristics can constantly change over time, making them difficult to estimate from historical data. In Figure 1, we illustrate that even the confidence interval of either mean or variance may depreciate in a non-stationary demand environment. In sum, either estimation error or distribution shift can lead to the mean and variance parameters being *misspecified*, and consequently, the optimal order quantity prescribed under ambiguity (in the Scarf model) may perform inexpertly. This is known as *model misspecification* in economics and statistics (Hansen 2014, Hansen and Miao 2018). In our context, it refers to the possibility that the true demand distribution may not reside in the ambiguity set with the same distributional characteristics as specified (*e.g.*, mean and variance in the Scarf model); see Figure 2 for an illustration.

The above discussion motivates us to caution against the potential issue of model misspecification in the fundamental newsvendor problem. To this end, we introduce a misspecification-averse (and ambiguity-averse) newsvendor model, which is well supported by a recent axiomatic framework (Cerrea-Vioglio et al. 2023, Hansen and Sargent 2023) that unifies behavioral decision criteria

³ The phenomenon of distribution shift, in statistical learning, also refers to situations where the training and testing samples are governed by different distributions (see, *e.g.*, Quiñonero-Candela et al. 2008).

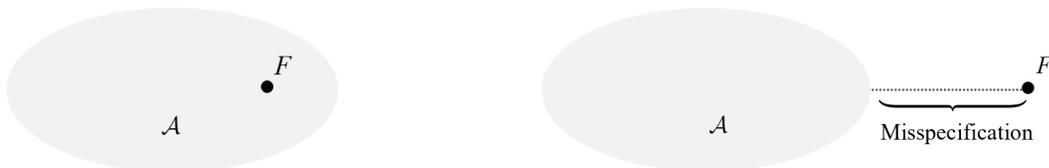


Figure 2 *Left:* The true demand distribution F resides in the ambiguity set \mathcal{A} , and the newsvendor faces only ambiguity. *Right:* The true demand distribution resides out of the ambiguity set, and hence, the newsvendor faces both ambiguity and misspecification.

that are averse to either ambiguity or misspecification. In particular, we distinguish the ambiguity under which the newsvendor does *not* differentiate demand distributions of common distributional characteristics (*e.g.*, mean and variance) and misspecification under which such characteristics might be misspecified (due to, *e.g.*, estimation error and/or distribution shift as discussed before). The newsvendor hedges against ambiguity and misspecification by maximizing the worst-case expected profit regularized by a distribution’s distance to an ambiguity set of distributions with some specified characteristics. We investigate—from decision-criterion, operational, and statistical perspectives—how misspecification aversion may affect the newsvendor’s decision and what is the rationale behind the misspecification aversion.

1.1. Summary of Main Contributions

Introducing misspecification upon ambiguity. We investigate the fundamental newsvendor problem under a *structured* decision-under-uncertainty framework that distinguishes the ambiguity and misspecification. We focus on the mean-variance information for characterizing the ambiguity and optimal-transport cost for quantifying the misspecification, respectively, and investigate the rationale behind the misspecification aversion that differentiates from the ambiguity aversion of the seminal Scarf framework. We extend our modeling on the ambiguity of demand distribution via bounding its statistical distance to a reference distribution, misspecification aversion upon ambiguity-aversion is then equivalent to a stronger misspecification aversion to a nominal ambiguity-neutral model under the reference distribution (Section 6.2). We also extend to consider other statistical distances (specifically, ϕ -divergence) to measure the misspecification (Section 6.3). These, together with misspecification aversion to the mean-variance ambiguity set, achieve a comprehensive inspection of newsvendor under ambiguity and misspecification.

Decision-criterion interpretations. We investigate and interpret the decision criterion of misspecification aversion by leveraging a decision-analysis vehicle of *distributional transform* (Liu et al. 2021). We show that the decision criterion of the newsvendor under ambiguity and misspecification is essentially a worst-case *transformed* expected profit with each distribution *within* the ambiguity set being transformed—via a *transform function* determined by the index of misspecification

aversion and the newsvendor’s profit function—to another one possibly *beyond* the ambiguity set (Theorem 1). In particular, the misspecification aversion, along the distributional transform, is *fully* encoded in the transform function identified. In addition, the decision criterion can also be interpreted as a worst-case *convex risk measure* generated by the distributional transform and the original criterion as expected profit. In particular, a stronger aversion to misspecification leads to a higher level of “risk” in view of the generated risk measure.

Analytical optimal solutions. We analytically derive the optimal order quantity of newsvendor under ambiguity and misspecification (Theorem 2), which generalizes that of the seminal Scarf model under ambiguity aversion alone. The analytical solution enables us to analyze the optimal order quantity’s sensitivity to cost structure (*i.e.*, price and cost) and distributional characteristics (*i.e.*, mean and variance) to understand the impact and rationale of misspecification aversion. In particular, while it is *always* optimal to order *more* as price increases under ambiguity aversion, it turns out that ordering *less* instead can be optimal as the price increases under misspecification aversion, *ceteris paribus* (Proposition 3). Likewise, in the case of high-profit margin, while it is optimal to order *more* as variance increases under ambiguity aversion, ordering *less* can be optimal as the variance increases under misspecification aversion, *ceteris paribus* (Proposition 4). These observations reveal that ambiguity and misspecification, as different layers of distributional uncertainty, can result in *distinct* operational consequences, and therefore should be distinguished in the modeling. Furthermore, we extend to derive the analytical optimal order quantities of multiple products under a sum-of-variance constraint, which *unifies* the ambiguity-averse and misspecification-averse single-product model, ambiguity-averse multi-product model, and the Scarf model (Theorem 5).

Performance guarantee. We establish the finite-sample performance guarantee of the optimal solution that decouples the mixing effect of estimation error and distribution shift in the misspecification statistically (Theorem 3). In particular, the estimation error is related to the distance between the data-generating distribution and the estimated mean-variance ambiguity set, and it *diminishes* as the sample size approaches infinity; while the distribution shift, captured by the distance between the data-generating distribution and the out-of-sample distribution, is *independent* of the sample size. This theoretically justifies the *rationale* of incorporating misspecification aversion in a non-stationary environment, which is also well demonstrated in our experiments with real-world retailing data.

1.2. Related Works

Our work is related to the following streams of literature.

Newsvendor with moment condition. Since the pioneering work of Scarf (1958), various studies have employed the moment condition to specify the ambiguity-averse newsvendor model

with limited demand information. For instance, building on the results of Scarf (1958), Gallego and Moon (1993) extend to consider a multi-product newsvendor problem based on *marginal* mean-and-variance information under a budget constraint. Natarajan et al. (2011) generalize the Scarf model by allowing the mean and variance to be uncertain and to vary within some predetermined intervals. This formulation turns out to be equivalent to the Scarf model characterized by the lower bound of mean and the upper bound of variance. Zhu et al. (2013) focus on minimizing the worst-case regret under known mean and variance of the random demand. In addition to ambiguity aversion, Han et al. (2014) incorporate risk aversion into the newsvendor problem, where the risk is captured by the standard deviation of the newsvendor's profit. Given the mean and variance of the demand, they develop a closed-form solution for the risk-averse (and ambiguity-averse) newsvendor. Apart from mean and variance, other moment information has also been considered in ambiguity-averse newsvendor problems. We refer to Perakis and Roels (2008) for structural information such as median, unimodality, and symmetry, to Ardestani-Jaafari and Delage (2016) for first-order partial moments, to Natarajan et al. (2018) for asymmetry based on second-order partitioned statistics, and to Das et al. (2021) for the t -th ($t \geq 1$) moment that can capture heavy-tailed demand distributions. Govindarajan et al. (2021) shift the focus to the inventory pooling problem where the ambiguity set is specified by mean and covariance (see also Hanasusanto et al. 2015) and characterize the closed-form solution of the two-location model.

Newsvendor with statistical distance. Another stream of the ambiguity-averse newsvendor model is based on ambiguity sets specified through the closeness to a reference distribution in terms of a certain statistical distance. For instance, Rahimian et al. (2019) delve into the total variation distance and obtain an insightful closed-form solution. Based on the Wasserstein distance, Chen and Xie (2021) adopt the minimax regret decision criterion in the presence of both demand and yield randomness, and they show that the optimal order quantity can be determined via an efficient golden section search. Fu et al. (2021) and Zhang et al. (2023) further leverage side information from explanatory features, and derive a closed-form solution based on the JW discrepancy measure and an optimal analytical ordering policy based on the Wasserstein distance, respectively. In this work, we also consider the possibility that the misspecification may arise from such ambiguity-averse newsvendor models with statistical distance (Theorem 6).

Model misspecification. Statisticians and econometricians have long grappled with the challenge of addressing uncertainty in decision-making, which is categorized as risk, ambiguity, and misspecification (see, *e.g.*, Hansen 2014, Hansen and Sargent 2022). Several noteworthy contributions have been made, which, from many angles, shed light on the interplay between the different layers of uncertainty. From the empirical perspective, Aydogan et al. (2023) provide experimental

Literature	Ambiguity Set		Misspecification	Performance Guarantee	Sensitivity Analysis	Multiple Products
	Moment Condition	Statistical Distance				
Scarf (1958)	✓	—	—	—	✓	—
Gallego and Moon (1993)	✓	—	—	—	✓	✓
Perakis and Roels (2008)	✓	—	—	—	✓	—
Natarajan et al. (2011)	✓	—	—	—	✓	—
Zhu et al. (2013)	✓	—	—	—	✓	—
Han et al. (2014)	✓	—	—	—	✓	—
Hanasusanto et al. (2015)	✓	—	—	—	—	✓
Ardestani-Jaafari and Delage (2016)	✓	—	—	—	—	✓
Natarajan et al. (2018)	✓	—	—	—	✓	✓
Rahimian et al. (2019)	—	✓	—	—	✓	—
Chen and Xie (2021)	—	✓	—	—	—	—
Das et al. (2021)	✓	—	—	—	—	—
Govindarajan et al. (2021)	✓	—	—	—	✓	✓
Fu et al. (2021)	—	✓	—	✓	✓	—
Zhang et al. (2023)	—	✓	—	✓	—	—
Our Work	✓	✓	✓	✓	✓	✓

Table 1 Position of our work in the related literature of newsvendor under demand-distribution uncertainty.

evidence for the role of model misspecification in decision-making under uncertainty. Their work establishes a compelling case for recognizing a distinct behavioral impact among risk, ambiguity, and misspecification, illuminating the nuanced facets of decision theory. From the theoretical perspective, [Cerreia-Vioglio et al. \(2023\)](#) propose an innovative axiomatic framework that unifies the behavioral decision criteria on the aversion to ambiguity and/or misspecification. From the operational perspective, [De Meyer et al. \(2002\)](#) delineate four types of uncertainty in project management, namely variation, foreseen uncertainty, unforeseen uncertainty, and chaos. The latter two align closely with the notions of ambiguity and misspecification, respectively. There are also nascent works investigating the issue of model misspecification in revenue management, such as misspecified demand function ([Nambiar et al. 2019](#)) and misspecified choice model ([Chen et al. 2023](#)). Rooted in the domain of optimization under uncertainty, the studies of [Delage and Ye \(2010\)](#) and [Wiesemann et al. \(2014\)](#) allow for variation in the moment information or the probabilities of specific events, while the works of [Ben-Tal et al. \(2017\)](#), [Liu et al. \(2023\)](#), and [Long et al. \(2023\)](#) propose paradigms that mitigate the violation of uncertainty-involved constraints when the distribution of uncertainty does not reside in the pre-specified ambiguity set.

Table 1 positions our work in the related literature of newsvendor under demand-distribution uncertainty. Our work contributes to the extant literature by introducing misspecification upon ambiguity in the fundamental newsvendor problem via a structured decision-under-uncertainty framework. We delve into the decision criterion of misspecification aversion and reveal its insightful

distributional-transform and convex-risk-measure interpretations. We further derive the closed-form optimal order quantity with implications from sensitivity analysis and establish the finite-sample performance guarantee. We also extend our framework to multiple products, distributional characteristics specified via optimal transport, and misspecification measured by ϕ -divergence.

1.3. Notation

We denote by \mathcal{P} (resp., \mathcal{M}_+) the set of probability measures (resp., non-negative measures) supported on \mathbb{R}_+ , and \mathcal{P}_0 the set of probability measures supported on \mathbb{R} . We use $\tilde{v} \sim F$ to signify a random variable \tilde{v} that follows the probability distribution with a cumulative probability distribution (CDF) F , under which the expectation is $\mathbb{E}_F[\cdot]$. The Dirac distribution at $v \in \mathbb{R}$ is denoted by δ_v . We adopt the convention that $1/0 = \infty$, and refer to “decreasing/increasing” in the weak sense.

2. Model

The newsvendor decides the order quantity before demand realization and tries to maximize her expected profit. Given the unit price p , unit cost c ($c < p$), and an order quantity q , the profit under the materialized demand v amounts to

$$\pi(q, v) = p \cdot \min\{q, v\} - cq = p \cdot \min\{q, v\} - (1 - \kappa)pq,$$

where we denote the profit margin by $\kappa = \frac{p-c}{p}$ (giving $c = (1 - \kappa)p$), which will be an important parameter for our analysis. Facing stochastic demand, the newsvendor must navigate optimizing her decision-making process to balance the trade-off between lost sales (incurred when $v > q$) and excess inventory (incurred when $v \leq q$). When the precise demand distribution G is fully known, the newsvendor maximizes her expected profit by solving the problem

$$\max_{q \geq 0} \mathbb{E}_G[\pi(q, \tilde{v})]. \quad (\text{NOMINAL})$$

The optimal order quantity q_G^* is characterized by the classic critical fractile $q_G^* = G^{-1}(\kappa)$. If G is an elliptical distribution with mean μ , standard deviation σ , and some density generator $\xi(\cdot)$, then $q_G^* = \mu + \sigma \cdot \Xi^{-1}(\kappa)$, where $\Xi(u) = \int_{-\infty}^u \xi(v^2)dv$.⁴ Such a formula holds for many other classes of distributions, including the uniform distributions and the exponential distributions. It is worth mentioning that within each class above, the optimal order quantity is also uniquely determined by only the mean and variance of the demand distribution.

In practice, full information on the demand distribution is often not accessible. To tackle the challenge of partial distributional information, significant advancements have been made in prescribing an ambiguity-averse solution that remains robust against all distributions specified by

⁴In practice, some necessary assumptions might be needed to ensure non-negativity of q_G^* (Snyder and Shen 2019).

some common distributional characteristics. The seminal work of Scarf (1958) specifies only the mean and variance of the demand distribution and solves

$$\max_{q \geq 0} \min_{G \in \mathcal{A}} \mathbb{E}_G[\pi(q, \tilde{v})] \quad (\text{AMBIGUITY})$$

with a mean-variance ambiguity set

$$\mathcal{A} = \{G \in \mathcal{P} \mid \mathbb{E}_G[\tilde{v}] = \mu, \mathbb{E}_G[\tilde{v}^2] = \mu^2 + \sigma^2\}.$$

The AMBIGUITY model admits an analytical solution⁵—for the reason that will become clear subsequently, we emphasize it with a subscript ‘ ∞ ’—as follows:

$$q_\infty^* = \begin{cases} \mu + \sigma f(1 - \kappa) & \kappa \geq \frac{\sigma^2}{\mu^2 + \sigma^2} \\ 0 & \kappa < \frac{\sigma^2}{\mu^2 + \sigma^2}, \end{cases} \quad (1)$$

where the function $f(\cdot)$ takes the form

$$f(x) = \frac{1 - 2x}{2\sqrt{x(1-x)}} \quad \forall 0 < x < 1. \quad (2)$$

As illustrated in Scarf (1958), the optimal order quantity q_∞^* of AMBIGUITY is comparatively close to the optimal order quantity of NOMINAL under a normal approximation of the Poisson distribution for a moderate range of profit margins. In effect, in many commonly used distributions (*e.g.*, elliptical, uniform, and exponential) of a nominal G as mentioned above, the optimal order quantities q_∞^* and q_G^* share important sensitivity features (to be discussed in Section 4.2). In addition, the AMBIGUITY model can also cover the situation where the mean and variance are themselves uncertain and reside in some estimated intervals, as remarked below.

REMARK 1 (GENERALITY OF AMBIGUITY). Consider an ambiguity set parameterized by bounds on the uncertain mean and variance:

$$\mathcal{V} = \{G \in \mathcal{P} \mid \mathbb{E}_G[\tilde{v}] = \mu, \mathbb{E}_G[\tilde{v}^2] = \mu^2 + \sigma^2 \text{ for some } \mu \in [\underline{\mu}, \bar{\mu}] \text{ and } \sigma^2 \in [\underline{\sigma}^2, \bar{\sigma}^2]\}.$$

By corollary 5.1 of Natarajan et al. (2011), it holds that

$$\max_{q \geq 0} \min_{G \in \mathcal{V}} \mathbb{E}_G[\pi(q, \tilde{v})] = \max_{q \geq 0} \min_{G \in \mathcal{A}} \mathbb{E}_G[\pi(q, \tilde{v})] \quad \text{with } \mathcal{A} = \{G \in \mathcal{P} \mid \mathbb{E}_G[\tilde{v}] = \underline{\mu}, \mathbb{E}_G[\tilde{v}^2] = \underline{\mu}^2 + \bar{\sigma}^2\}.$$

The right-hand side equivalence is indifferent to AMBIGUITY with mean $\underline{\mu}$ and variance $\bar{\sigma}^2$.

⁵ Note that when $\kappa = \frac{\sigma^2}{\mu^2 + \sigma^2}$, the optimal order quantity q_∞^* can take any value in $[0, \mu + \sigma f(1 - \kappa)]$.

An underlying assumption of **AMBIGUITY** is that the true distribution F_{true} falls in the specified ambiguity set \mathcal{A} . However, the ambiguity set \mathcal{A} is constructed using the mean and variance estimates for those of the true F_{true} , and is, therefore, may be misspecified, that is, $F_{\text{true}} \notin \mathcal{A}$ (see also the empirical evidence in Figure 1). This leads to *misspecification*—an issue we address next.

To capture misspecification formally, for a demand distribution $F \in \mathcal{P}$, we measure its closeness to the ambiguity set \mathcal{A} by

$$d(F, \mathcal{A}) = \min_{G \in \mathcal{A}} d(F, G)$$

with $d(F, G)$ being the optimal-transport cost (Villani 2009) between two distributions F and G with quadratic cost function $|\cdot|^2$ defined as

$$d(F, G) = \min_{\Gamma \in \mathcal{W}(F, G)} \int_{\mathbb{R}_+ \times \mathbb{R}_+} |u - v|^2 d\Gamma(u, v), \quad (3)$$

where $\mathcal{W}(F, G)$ is the set of joint probability distributions on $\mathbb{R}_+ \times \mathbb{R}_+$ with marginals F and G . The quantity $\sqrt{d(F, G)}$ is also known as the type-2 Wasserstein distance between F and G . Note that $d(F, \mathcal{A}) > 0$ if and only if $F \notin \mathcal{A}$. In the main content, we focus on the optimal-transport cost in characterizing misspecification, for the sake of tractability and statistical convenience (see more details in Section 4 and Section 5). Following the spirit of Cerreia-Vioglio et al. (2023),⁶ given the ambiguity set \mathcal{A} , we incorporate misspecification into the newsvendor's decision criterion so that a misspecification-averse (and ambiguity-averse) newsvendor solves

$$\Pi_\alpha^* = \max_{q \geq 0} \min_{F \in \mathcal{P}} \left\{ \mathbb{E}_F[\pi(q, \tilde{u})] + \alpha \cdot d(F, \mathcal{A}) \right\} \quad (\text{MISSPECIFICATION})$$

for some $\alpha \geq 0$ that represents the index of misspecification aversion: the lower the index, the stronger the aversion to misspecification. Intuitively speaking, a larger value of α puts a larger penalty on deviation from the ambiguity set \mathcal{A} (as measured by $d(F, \mathcal{A})$) and corresponds to higher confidence in \mathcal{A} (or equivalently, the **AMBIGUITY** model). On the one end, when $\alpha \rightarrow \infty$, misspecification aversion is absent (see section 4.1 in Cerreia-Vioglio et al. 2023), and **MISSPECIFICATION** reduces to **AMBIGUITY** as the newsvendor is absolutely confident with \mathcal{A} . On the other end, when $\alpha \rightarrow 0$, misspecification aversion is strongest, and **MISSPECIFICATION** reduces to the robust model

$$\max_{q \geq 0} \min_{F \in \mathcal{P}} \mathbb{E}_F[\pi(q, \tilde{u})] = \max_{q \geq 0} \min_{u \in \mathbb{R}_+} \pi(q, u),$$

wherein the newsvendor is so unconfident that she disregards the distributional characteristics specified in \mathcal{A} .

⁶ When considering misspecification aversion, Cerreia-Vioglio et al. (2023) focus on ϕ -divergence.

It is worth noting that the **MISSPECIFICATION** problem can also be regarded as the dual counterpart of an alternate formulation of the news vendor model under misspecification as follows:

$$\max_{q \geq 0} \min_{d(F, \mathcal{A}) \leq \varepsilon} \mathbb{E}_F[\pi(q, \tilde{u})] \quad (4)$$

for some $\varepsilon \geq 0$. In particular, when $\varepsilon = 0$, problem (4) reduces to **AMBIGUITY**; and when $\varepsilon > 0$, the optimal solution to problem (4) can be constructed from that of **MISSPECIFICATION** (Lemma EC.2 in Section EC.1). In other words, the decision of **MISSPECIFICATION** essentially hedges against some worst-case distribution that can stay *outside* the ambiguity set \mathcal{A} characterized by mean and variance information. This makes **MISSPECIFICATION** distinct from **AMBIGUITY** (with the underlying worst-case distribution within \mathcal{A}) in many aspects, which will be further explored in the forthcoming sections. In Section 6, we extend **MISSPECIFICATION** to involve multiple products, distance-based ambiguity set defined via optimal transport, and misspecification measured by ϕ -divergence.

3. Decision Criterion via Distributional Transform

To understand the decision criterion of misspecification aversion in our news vendor context,⁷ we investigate the objective function of **MISSPECIFICATION** from a perspective of *distributional transform*. We show that the objective function essentially transforms distributions in \mathcal{A} —via a *transform function* determined by the index α of misspecification aversion and the news vendor’s profit function—to new ones that possibly violate the mean and variance constraints specified by \mathcal{A} .

Exploring the definition of $d(F, \mathcal{A})$ and interchanging the minimization over F and G , we can represent equivalently the **MISSPECIFICATION** problem as follows:

$$\max_{q \geq 0} \min_{G \in \mathcal{A}} \min_{F \in \mathcal{P}} \left\{ \mathbb{E}_F[\pi(q, \tilde{u})] + \alpha \cdot d(F, G) \right\}.$$

Here, the inner minimization features the potential misspecification of a fixed distribution $G \in \mathcal{A}$, which is then robustified over the specified ambiguity set \mathcal{A} via the outer minimization. Recall that a distributional transform $T_\varphi[\cdot] : \mathcal{P} \mapsto \mathcal{P}_0$ maps distributions in \mathcal{P} to \mathcal{P}_0 via a *transform function* φ that can be defined in multiple ways per as necessary (Liu et al. 2021). We can then represent the above inner minimization term through the notion of distributional transform, leading to the following result that plays a key role in characterizing the decision criterion of **MISSPECIFICATION**.

THEOREM 1 (DISTRIBUTIONAL TRANSFORM). *Given $\alpha \geq 0$ and $q \geq 0$, it holds that*

$$\min_{F \in \mathcal{P}} \left\{ \mathbb{E}_F[\pi(q, \tilde{u})] + \alpha \cdot d(F, \mathcal{A}) \right\} = \min_{G \in \mathcal{A}} \int_{\mathbb{R}_+} \pi(q, v) dT_{\varphi_\alpha}[G](v),$$

⁷ Cerreia-Vioglio et al. (2023) establish the axiomatic foundation of misspecification aversion based on the representation of behavioral preferences in decision theory, which, however, does not offer many operational insights.

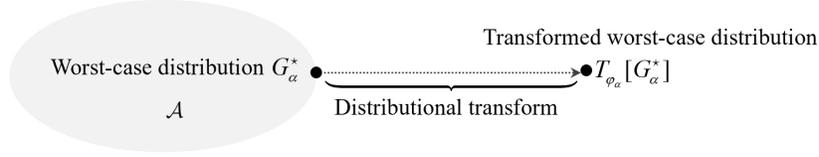


Figure 3 The decision criterion of **MISSPECIFICATION** transforms the worst-case distribution G_α^* in the ambiguity set \mathcal{A} into the transformed worst-case distribution $T_{\varphi_\alpha}[G_\alpha^*]$ that can be outside of \mathcal{A} .

where $T_{\varphi_\alpha}[G](v) = G \circ \varphi_\alpha^{-1}(v) \forall v \in \mathbb{R}_+$,⁸ and $T_{\varphi_\alpha}[\cdot]$ is a distributional transform of $G \in \mathcal{A}$ with an increasing and continuous transform function $\varphi_\alpha : \mathbb{R}_+ \mapsto \mathbb{R}_+$ defined as follows.

(i) If $\alpha < \frac{p}{4q}$, then

$$\varphi_\alpha(v) = \frac{\alpha}{p} \cdot v^2.$$

(ii) If $\alpha \geq \frac{p}{4q}$, then

$$\varphi_\alpha(v) = \begin{cases} \frac{\alpha}{p} \cdot v^2 & v < \frac{p}{2\alpha} \\ v - \frac{p}{4\alpha} & v \geq \frac{p}{2\alpha}. \end{cases}$$

By Theorem 1, the decision criterion of **MISSPECIFICATION** serves as an expectation under a transformed worst-case distribution (Figure 3), which establishes the equivalence between **MISPECIFICATION** and the following problem

$$\max_{q \geq 0} \min_{G \in \mathcal{A}} \mathbb{E}_{T_{\varphi_\alpha}[G]}[\pi(q, \tilde{v})]. \quad (\text{TRANSFORM})$$

For the remainder of this section, we may use **TRANSFORM** and **MISSPECIFICATION** interchangeably.

Recall that **AMBIGUITY** evaluates the performance of an order quantity q via the decision criterion

$$\min_{G \in \mathcal{A}} \mathbb{E}_G[\pi(q, \tilde{v})].$$

The above equivalence reveals that the key *difference* between **AMBIGUITY** and **MISSPECIFICATION** lies in the transform function φ_α applied to the probability distributions in the mean-variance ambiguity set \mathcal{A} . In particular, for any *physical*⁹ probability distribution $G \in \mathcal{A}$, φ_α transforms it to a *subjective* probability distribution $T_{\varphi_\alpha}[G]$ that can be *outside* \mathcal{A} , so that the resulting transformed expectation $\mathbb{E}_{T_{\varphi_\alpha}[G]}[\cdot]$ reflects the newsvendor's aversion to misspecification. On the one hand, for a small value of α such that $\alpha < \frac{p}{4q}$, the transform function φ_α compresses (resp., amplifies) low (resp., high) demand realizations of G ,¹⁰ and a smaller α results in more demand realizations being compressed, see the cases of α_1, α_2 on the left panel of Figure 4. On the other hand, for a large value

⁸ The transformed distribution $T_{\varphi_\alpha}[G]$ is also the CDF of $\varphi_\alpha(\tilde{v})$ with $\tilde{v} \sim G$.

⁹ All distributions in \mathcal{A} sharing the same *physically* observable mean-variance information are treated indifferently.

¹⁰ When $\alpha < \frac{p}{4q}$, $T_{\varphi_\alpha}[G](v) = G(\sqrt{\frac{p}{\alpha}v})$ for every $G \in \mathcal{A}$. Since $G(v)$ is increasing in v , it can be seen that $T_{\varphi_\alpha}[G](v) > G(v)$ when $v < \frac{p}{\alpha}$ and $T_{\varphi_\alpha}[G](v) \leq G(v)$ when $v \geq \frac{p}{\alpha}$.

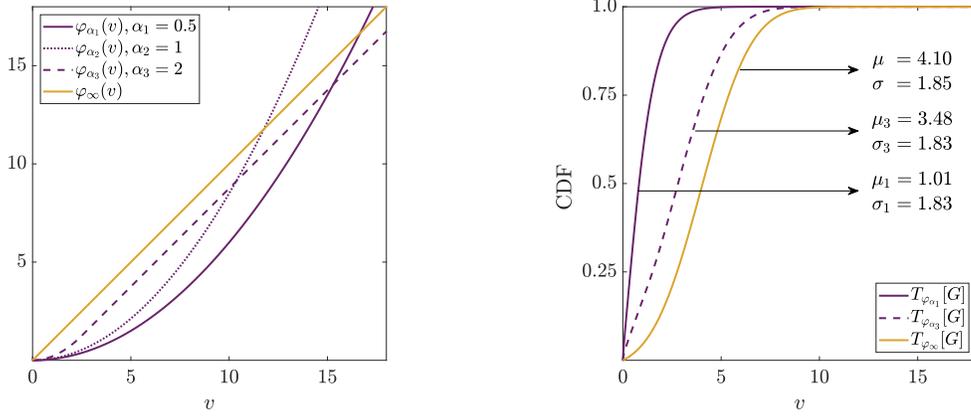


Figure 4 *Left:* Transform function $\varphi_\alpha(v)$. *Right:* CDF of a truncated normal distribution G and the transformed distribution $T_{\varphi_\alpha}[G]$. On both panels, $\alpha_1 < \alpha_2 < \frac{p}{4q} < \alpha_3$. For the right panel, $G \in \mathcal{A}$ is a normal distribution truncated to \mathbb{R}_+ with mean μ and standard deviation σ . Here, μ_1 and σ_1 (resp., μ_3 and σ_3) are the mean and standard deviation of the transformed distribution $T_{\varphi_{\alpha_1}}[G]$ (resp., $T_{\varphi_{\alpha_3}}[G]$).

of α such that $\alpha \geq \frac{p}{4q}$, φ_α compresses all demand realizations of G ;¹¹ see the case of α_3 on the left panel of Figure 4. In this case, misspecification aversion compresses all probability distributions in \mathcal{A} , and a smaller α also leads to a stronger compression. Importantly, due to the transform function φ_α , the mean or variance of the transformed distribution $T_{\varphi_\alpha}[G]$ can be different from that of the original distribution G in the ambiguity set \mathcal{A} , namely $T_{\varphi_\alpha}[G] \notin \mathcal{A}$; see the right panel of Figure 4 for a visualization. As $\alpha \rightarrow \infty$, the transform function becomes $\varphi_\alpha(v) = v$, implying $T_{\varphi_\alpha}[G] = G$ and that **MISSPECIFICATION** reduces to **AMBIGUITY**. That is, the index α of misspecification aversion, or equivalently, the newsvendor's aversion against misspecification of \mathcal{A} , is fully encoded in the transform function φ_α of **TRANSFORM**.

Interestingly, we emphasize that given α and an order quantity q , the distributional transform T_{φ_α} is determined by the price p (see the transform function φ_α derived in Theorem 1), leading to the transformed worst-case distribution $T_{\varphi_\alpha}[G_\alpha^*]$ with $G_\alpha^* \in \arg \min_{G \in \mathcal{A}} \mathbb{E}_{T_{\varphi_\alpha}[G]}[\pi(q, \tilde{v})]$ being dependent on the price (see Proposition EC.1 in Section EC.3). In contrast, we recall that the worst-case distribution implied by **AMBIGUITY**, *i.e.*, $G^* \in \arg \min_{G \in \mathcal{A}} \mathbb{E}_G[\pi(q, \tilde{v})]$, is however independent of the cost structure.¹² In other words, the *price-independent* worst-case distribution *inside* the ambiguity set \mathcal{A} in the decision criterion of **AMBIGUITY** now becomes a *price-dependent* transformed worst-case distribution *outside* of \mathcal{A} in the decision criterion of **MISSPECIFICATION**. We emphasize

¹¹ When $\alpha \geq \frac{p}{4q}$, $T_{\varphi_\alpha}[G](v) = G(\sqrt{\frac{p}{\alpha}}v) \geq G(v)$ if $v < \frac{p}{2\alpha}$ and $T_{\varphi_\alpha}[G](v) = G(v + \frac{p}{4\alpha}) \geq G(v)$ otherwise. Hence, for every $G \in \mathcal{A}$, we always have $T_{\varphi_\alpha}[G](v) \geq G(v)$ for all $v \geq 0$.

¹² Given an order quantity q , it can be shown that $G_\infty^* = (\frac{\sigma^2}{\mu^2 + \sigma^2}) \cdot \delta_0 + (\frac{\mu^2}{\mu^2 + \sigma^2}) \cdot \delta_{\frac{\mu^2 + \sigma^2}{\mu}}$ when $q < \frac{\mu^2 + \sigma^2}{2\mu}$, and $G_\infty^* = (\frac{1}{2} + \frac{q - \mu}{2w}) \cdot \delta_{q-w} + (\frac{1}{2} - \frac{q - \mu}{2w}) \cdot \delta_{q+w}$ otherwise, where $w = \sqrt{(q - \mu)^2 + \sigma^2}$, which is independent of p .

that such price-dependency effect indeed leads to operational consequences of **MISSPECIFICATION** being distinct from that of **AMBIGUITY**, which will be further explored in Section 4.

Finally, we also point out that the decision criterion of **MISSPECIFICATION** can be interpreted as a worst-case *convex risk measure* generated by the distributional transform and the original criterion as expected profit.¹³ In effect, given $\alpha \geq 0$ and $G \in \mathcal{A}$, if we define

$$\rho_\alpha^G(\tilde{\pi}) = -\min_{F \in \mathcal{P}} \{\mathbb{E}_F[\tilde{\pi}] + \alpha \cdot d(F, G)\}, \quad (5)$$

then according to the robust representation of convex risk measures (Föllmer and Schied 2016), we can formalize ρ_α^G being a *convex risk measure* on the space of random profits.

PROPOSITION 1. *Given $\alpha \geq 0$ and $G \in \mathcal{A}$, ρ_α^G is a convex risk measure.*

Note that given $q \geq 0$, $\rho_{\alpha_1}^G(\pi(q, \tilde{v})) \geq \rho_{\alpha_2}^G(\pi(q, \tilde{v}))$ for any $\alpha_1 \leq \alpha_2$. The distributional transforms $(T_{\varphi_\alpha})_{\alpha \geq 0}$ generate a collection of convex risk measures $(\rho_\alpha^G)_{\alpha \geq 0}$, where the parameter α —the index of misspecification aversion—now controls the level of risk measured by ρ_α^G . A smaller α (*i.e.*, a stronger misspecification aversion) in φ_α that transforms the distribution G leads to a higher level of risk. Using the risk-measure representation (5), **MISSPECIFICATION** is then equivalent to

$$\min_{q \geq 0} \max_{G \in \mathcal{A}} \rho_\alpha^G(\pi(q, \tilde{v})) \quad (\text{RISK})$$

that optimizes the worst-case convex risk measure generated by the distributional transform T_{φ_α} , providing another interpretation for the decision criterion of **MISSPECIFICATION**. Therefore, choosing $d(\cdot, \cdot)$ as optimal-transport cost not only enriches the risk-measure representations of the decision criterion of misspecification aversion, but also is important to the computational tractability for our newsvendor problem (see Sections 4 and 6.1).¹⁴

4. Optimal Solution and Sensitivity Analysis

In this section, we first derive the optimal order quantity of **MISSPECIFICATION** in closed form. We then investigate the impact of misspecification aversion via the optimal order quantity's sensitivity to the cost-structure information and distributional information, revealing important operational implications of **MISSPECIFICATION** distinct from **AMBIGUITY**.

¹³ As Liu et al. (2021) have pointed out, applying distributional transform can generate new risk measures from a risk measure (*e.g.*, expectation).

¹⁴ The connection between **MISSPECIFICATION** and **RISK** is consistent with the extant literature that chiefly measures misspecification by ϕ -divergence. Specifically, Cerreia-Vioglio et al. (2023) show that choosing $d(\cdot, \cdot)$ as ϕ -divergence would result in some well-known convex risk measures. For example, choosing $d(\cdot, \cdot)$ as Kullback–Leibler divergence (*resp.*, Gini concentration index) results in CARA risk measure (*resp.*, mean-variance risk measure). However, they are both hard to optimize (Chen and Sim 2023) and even computationally intractable in the newsvendor problem.

4.1. Analytical Solution

To proceed, we recall that **MISSPECIFICATION** can be reformulated as

$$\begin{aligned} \max_{q \geq 0} \min_{F \in \mathcal{P}} \{ \mathbb{E}_F[\pi(q, \tilde{u})] + \alpha \cdot d(F, \mathcal{A}) \} &= \max_{q \geq 0} \min_{G \in \mathcal{A}} \mathbb{E}_{T_{\varphi_\alpha}[G]}[\pi(q, \tilde{v})] \\ &= \max_{q \geq 0} \min_{G \in \mathcal{A}} \mathbb{E}_G[\pi(q, \varphi_\alpha(\tilde{v}))], \end{aligned}$$

where the second equality follows from the definition of distributional transform T_{φ_α} as identified in Theorem 1. Therefore, one can tackle **MISSPECIFICATION** by adapting the primal-dual machinery for solving a maximin problem similar to **AMBIGUITY** but with a new “profit” function $\Psi(\alpha, q, v) = \pi(q, \varphi_\alpha(v))$. Specifically, given $q \geq 0$, the inner worst-case expectation can be written as

$$\begin{aligned} \min_{G \in \mathcal{M}_+} \int_{\mathbb{R}_+} \Psi(\alpha, q, v) dG(v) \\ \text{s.t. } \int_{\mathbb{R}_+} v dG(v) &= \mu \quad \cdots s_\alpha \\ \int_{\mathbb{R}_+} v^2 dG(v) &= \mu^2 + \sigma^2 \quad \cdots r_\alpha \\ \int_{\mathbb{R}_+} dG(v) &= 1 \quad \cdots t_\alpha. \end{aligned} \tag{6}$$

With s_α , r_α , and t_α being dual variables that are respectively associated with the mean, variance, and support of the ambiguity set \mathcal{A} , the equivalent dual reformulation of problem (6) is

$$\begin{aligned} \max_{s_\alpha, r_\alpha, t_\alpha} \mu s_\alpha - (\mu^2 + \sigma^2) r_\alpha - t_\alpha \\ \text{s.t. } v s_\alpha - v^2 r_\alpha - t_\alpha &\leq \Psi(\alpha, q, v) \quad \forall v \geq 0 \\ s_\alpha \in \mathbb{R}, r_\alpha \in \mathbb{R}, t_\alpha \in \mathbb{R}. \end{aligned} \tag{7}$$

The key to the primal-dual machinery is to construct a pair of primal and dual solutions that share identical objective values. In particular, the primal solution is a worst-case distribution constructed by identifying tangent points between function $s_\alpha v - r_\alpha v^2 - t_\alpha$ and the function $\Psi(\alpha, q, v)$ in the dual problem (7). For **MISSPECIFICATION**, however, the new “profit” function Ψ —neither convex nor concave in v —is less structured than the concave piecewise affine function π of **AMBIGUITY**, making the primal-dual procedure more involved to analyze. Fortunately, leveraging the closed form of $\Psi(\alpha, q, v) = \pi(q, \varphi_\alpha(v))$ given by Theorem 1, we can derive an analytical reformulation of the objective function in **MISSPECIFICATION**.

PROPOSITION 2 (WORST-CASE TRANSFORMED EXPECTATION). *Given $\alpha \geq 0$ and $q \geq 0$,*

$$\min_{G \in \mathcal{A}} \mathbb{E}_{T_{\varphi_\alpha}[G]}[\pi(q, \tilde{v})] = \begin{cases} \frac{p}{2} \left(q + \mu - \frac{p}{4\alpha} - \sqrt{\left(q - \mu + \frac{p}{4\alpha} \right)^2 + \sigma^2} \right) - cq & \text{if } q \in \mathcal{Q} \\ \frac{\alpha}{2} \left(\frac{pq}{\alpha} + \mu^2 + \sigma^2 - \sqrt{\left(\frac{pq}{\alpha} + \mu^2 + \sigma^2 \right)^2 - 4\mu^2 \frac{pq}{\alpha}} \right) - cq & \text{otherwise,} \end{cases} \tag{8}$$

where $\mathcal{Q} = \{q \in \mathbb{R}_+ \mid q \geq \frac{p}{4\alpha}, (2\mu - \frac{p}{\alpha})q \geq \mu^2 + \sigma^2 - \frac{p\mu}{2\alpha}\}$.

The analytical form of the worst-case transformed expectation is non-trivial and generalizes the worst-case expected cost of **AMBIGUITY** as $\alpha \rightarrow \infty$.¹⁵ Equipped with the analytical form, we can then derive the optimal solution of **MISSPECIFICATION** as follows.

THEOREM 2 (OPTIMAL SOLUTION). *Given $\alpha \geq 0$, the optimal order quantity q_α^* of **MISSPECIFICATION** is*

$$q_\alpha^* = \begin{cases} \mu + \sigma f(1 - \kappa) - \frac{p}{4\alpha} & \kappa \geq \frac{\sigma^2}{\mu^2 + \sigma^2}, \alpha \geq \frac{p}{2(\mu - \sigma\sqrt{(1-\kappa)/\kappa})} \\ (\mu^2 - \sigma^2 + 2\mu\sigma f(1 - \kappa)) \cdot \frac{\alpha}{p} & \kappa \geq \frac{\sigma^2}{\mu^2 + \sigma^2}, \alpha < \frac{p}{2(\mu - \sigma\sqrt{(1-\kappa)/\kappa})} \\ 0 & \kappa < \frac{\sigma^2}{\mu^2 + \sigma^2}, \end{cases} \quad (9)$$

where $f(\cdot)$ is defined in (2). The optimal order quantity q_α^* is increasing in α .

Focusing on the non-degenerate case that $\kappa \geq \frac{\sigma^2}{\mu^2 + \sigma^2}$, for $0 \leq \alpha_1 < \frac{p}{2(\mu - \sigma\sqrt{(1-\kappa)/\kappa})} \leq \alpha_2$, we have

$$q_{\alpha_1}^* = (\mu^2 - \sigma^2 + 2\mu\sigma f(1 - \kappa)) \cdot \frac{\alpha_1}{p} \leq q_{\alpha_2}^* = \mu + \sigma f(1 - \kappa) - \frac{p}{4\alpha_2} \leq \mu + \sigma f(1 - \kappa) = q_\infty^*;$$

see left panel of Figure 5. This implies that the optimal order quantity q_α^* of **MISSPECIFICATION** is no larger than that of **AMBIGUITY** (*i.e.*, q_∞^*)—an intuitive result due to the additional aversion to misspecification—and $q_\alpha^* \rightarrow q_\infty^*$ as $\alpha \rightarrow \infty$. It is also notable that the optimal order quantity q_α^* is affected by misspecification aversion and ambiguity aversion *separately*. When $\alpha < \frac{p}{2(\mu - \sigma\sqrt{(1-\kappa)/\kappa})}$, q_α^* is a product of $\mu^2 - \sigma^2 + 2\mu\sigma f(1 - \kappa)$ and α/p that are purely determined by the mean and variance information specified in \mathcal{A} and purely determined by misspecification, respectively. When $\alpha \geq \frac{p}{2(\mu - \sigma\sqrt{(1-\kappa)/\kappa})}$, q_α^* is obtained by $\mu + \sigma f(1 - \kappa)$ that is exactly the optimal order quantity q_∞^* of **AMBIGUITY** minus $\frac{p}{4\alpha}$ that is purely determined by misspecification.

4.2. Sensitivity and its Implications

We next look at the optimal order quantity q_α^* 's sensitivity to the cost-structure information (*i.e.*, c and p) and distributional information (*i.e.*, μ and σ^2). Since it is straightforward that q_α^* is decreasing (resp., increasing) in c (resp., μ) being consistent with that of **AMBIGUITY**, we focus on its sensitivity to price p and variance σ^2 , which exhibits a different pattern from that of **AMBIGUITY**. In particular, we also focus on the non-degenerate case in Theorem 2 that $\kappa \geq \frac{\sigma^2}{\mu^2 + \sigma^2}$. In this case, recall from (1) and (2) that the optimal order quantity q_∞^* of **AMBIGUITY** is

$$q_\infty^* = \mu + \sigma \frac{2\kappa - 1}{2\sqrt{\kappa(1 - \kappa)}} = \mu + \frac{\sigma}{2} \left(\sqrt{\frac{\kappa}{1 - \kappa}} - \sqrt{\frac{1 - \kappa}{\kappa}} \right). \quad (10)$$

¹⁵ As $\alpha \rightarrow \infty$, \mathcal{Q} becomes $\{q \in \mathbb{R}_+ \mid q \geq \frac{\mu^2 + \sigma^2}{2\mu}\}$ and (8) recovers the worst-case expected cost of **AMBIGUITY** such that $\min_{G \in \mathcal{A}} \mathbb{E}_G[\pi(q, \tilde{v})] = \frac{\mu^2 + pq}{\mu^2 + \sigma^2} - cq$ if $q \geq \frac{\mu^2 + \sigma^2}{2\mu}$ and $\min_{G \in \mathcal{A}} \mathbb{E}_G[\pi(q, \tilde{v})] = \frac{p}{2}(q + \mu - \sqrt{(q - \mu)^2 + \sigma^2}) - cq$ otherwise.

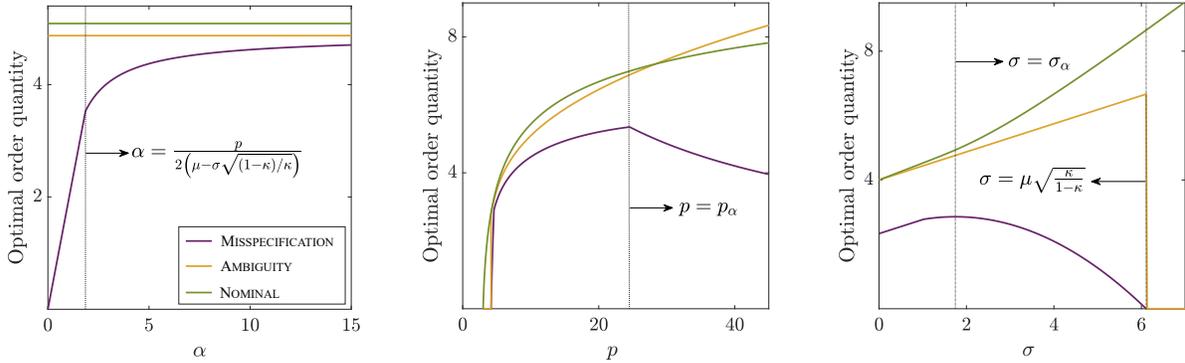


Figure 5 Optimal order quantity as a function of α (left), p (middle) and σ (right), respectively.

Notes. The optimal order quantity of **NOMINAL** is obtained under a normal distribution truncated to \mathbb{R}_+ with mean μ and standard deviation σ . For all three panels, we set $c = 3$ and $\mu = 4$. On the left panel, $p = 10$ and $\sigma = 2$. On the middle panel, $\sigma = 2.5$ and $\alpha = 4$, and we identify $p_\alpha = 22.5$. On the right panel, $p = 10$ and $\alpha = 1.5$, for which $\kappa = 0.7$ and the non-degenerate region is $\sigma \in [0, \mu\sqrt{\frac{\kappa}{1-\kappa}}] = [0, 4\sqrt{\frac{7}{3}}]$, and we identify $\sigma_\alpha = \frac{8}{\sqrt{21}}$.

By (10), q_∞^* of **AMBIGUITY** is always *increasing* in p , so is $q_G^* = G^{-1}(\kappa)$ of **NOMINAL** under any distribution G , by noting that the profit margin $\kappa = \frac{p-c}{p}$ is increasing in p . However, the monotonicity of q_α^* to p can reverse that of q_∞^* (q_G^*) as shown below.

PROPOSITION 3 (SENSITIVITY TO PRICE). *There exists some $p_\alpha \geq \max\{\frac{\mu^2 + \sigma^2}{\mu^2}c, 2\alpha\mu\}$ such that q_α^* is decreasing in $p \in (p_\alpha, \infty)$.*

Notably, Proposition 3 points out that when price p is sufficiently large, the optimal order quantity q_α^* of **MISSPECIFICATION**, in stark contrast to q_∞^* of **AMBIGUITY**, is *decreasing* in p ; see the middle panel of Figure 5. We emphasize that such distinct sensitivity is rooted from the induced *price dependency* of the transformed worst-case demand distribution $T_{\varphi_\alpha}[G_\alpha^*]$ in **MISSPECIFICATION**, which stochastically reduces in the price p (see transform function φ_α in Theorem 1), while the worst-case demand distribution of **AMBIGUITY** is *independent* of the price. As the price becomes sufficiently large, the effect of reduced “demand” ($T_{\varphi_\alpha}[G_\alpha^*]$) outweighs that of the increased profit margin, leading to the q_α^* of **MISSPECIFICATION** being decreased.

Likewise, by (10), the optimal order quantity q_∞^* of **AMBIGUITY** is *increasing* (resp., decreasing) in σ when $\kappa \geq \frac{1}{2}$ (resp., when $\kappa < \frac{1}{2}$), under the non-degenerate condition $\kappa \geq \frac{\sigma^2}{\mu^2 + \sigma^2}$, i.e., $\sigma \in [0, \mu\sqrt{\frac{\kappa}{1-\kappa}}]$. Such monotonicity also holds for the optimal order quantity $q_G^* = G^{-1}(\kappa)$ of **NOMINAL** under many commonly used distributions (e.g., elliptical, uniform, and exponential). However, the situation becomes different when considering the misspecification aversion: the optimal order quantity q_α^* of **MISSPECIFICATION**, can be *decreasing* in σ when $\kappa \geq \frac{1}{2}$ in the situation of non-degeneracy; see the right panel of Figure 5. The different sensitivity pattern also uncovers an advantage of **MISSPECIFICATION** in the solution’s smoothness to parameters, by noting that the

solution to **AMBIGUITY** is overly sensitive to the parameter σ as it can jump as σ changes slightly; see, *e.g.*, Embrechts et al. (2022), for various smoothness issues in optimizing risk measures.

PROPOSITION 4 (SENSITIVITY TO VARIANCE). *Given $\kappa \geq \frac{1}{2}$, there exists some $\sigma_\alpha \leq \mu \sqrt{\frac{\kappa}{1-\kappa}}$ such that q_α^* is decreasing in $\sigma \in [\sigma_\alpha, \mu \sqrt{\frac{\kappa}{1-\kappa}}]$.*

To summarize, sharing the mean and variance characteristics, the optimal order quantity of **AMBIGUITY**—hedging against the distributional uncertainty *within* the ambiguity set \mathcal{A} —may exhibit an *identical* sensitivity pattern to the cost-structure parameters with that of **NOMINAL**, and, in the situation of non-degeneracy, to the distributional characteristics with that of **NOMINAL** under many common distributions inside \mathcal{A} .¹⁶ The optimal order quantity of **MISSPECIFICATION**, however, hedges against another layer of distributional uncertainty *beyond* the ambiguity set \mathcal{A} , which therefore can *break* the sensitivity pattern of ordering characterized by the mean and variance information. This suggests that the ambiguity and misspecification, as different layers of distributional uncertainty, could result in *distinct* operational consequences, and therefore should be distinguished in the modeling.

5. Performance Guarantee

In this section, we investigate the out-of-sample performance guarantee of the optimal order quantity q_α^* of **MISSPECIFICATION**. As we have mentioned, in many practical situations, the newsvendor has only access to incomplete knowledge on demand, and the misspecification can arise from a mixing effect of estimation error (*e.g.*, due to data limitation) and distribution shift (*e.g.*, due to non-stationarity). We consider a data-driven setting where the mean-variance ambiguity set \mathcal{A} is estimated as \mathcal{A}_N by using demand samples drawn from a data-generating distribution D with mean μ and standard deviation σ .

ASSUMPTION 1. *Assume that $\hat{v}_1, \dots, \hat{v}_N$ are random samples independently drawn from the data-generating distribution D , and the mean-variance ambiguity set*

$$\mathcal{A}_N = \{G \in \mathcal{P} \mid \mathbb{E}_G[\tilde{v}] = \hat{\mu}, \mathbb{E}_G[\tilde{v}^2] = \hat{\mu}^2 + \hat{\sigma}^2\}$$

is constructed from sample mean and variance:

$$\hat{\mu} = \frac{1}{N} \sum_{i=1}^N \hat{v}_i \quad \text{and} \quad \hat{\sigma}^2 = \frac{1}{N} \sum_{i=1}^N \hat{v}_i^2 - \left(\frac{1}{N} \sum_{i=1}^N \hat{v}_i \right)^2.$$

¹⁶ It can be readily checked that both solutions of **AMBIGUITY** and **NOMINAL** share the same monotonicity to the cost c and to the mean value μ .

We consider the possibility that the out-of-sample distribution F can be *different* from D —a phenomenon of distribution shift. In particular, we look at the finite-sample performance guarantee leveraging a statistical approach that interprets insightfully the performance guarantee of **MISSPECIFICATION** by decoupling the effects of estimation error and distribution shift.

Our analysis relies on the concentration of the estimated mean-variance ambiguity set \mathcal{A}_N , for which we need to investigate the optimal-transport cost $d(D, \mathcal{A}_N)$ that is closely related to the *Gelbrich distance* (Gelbrich 1990). For any $G \in \mathcal{A}_N$, the Gelbrich distance between G and the data-generating D is $\sqrt{(\hat{\mu} - \mu)^2 + (\hat{\sigma} - \sigma)^2}$, and $d(D, G) \geq (\hat{\mu} - \mu)^2 + (\hat{\sigma} - \sigma)^2$ with the inequality being tight whenever G is an affine transformation of D (as shown in Gelbrich 1990, Nguyen et al. 2021). That is to say, if \mathcal{A}_N is supported on the whole space \mathbb{R} , then $d(D, \mathcal{A}_N) = (\hat{\mu} - \mu)^2 + (\hat{\sigma} - \sigma)^2$ —the optimal-transport cost amounts to the Gelbrich distance squared. This is *not* necessarily true in our news vendor context as the demand is non-negative and \mathcal{A}_N should be supported on \mathbb{R}_+ . Quite notably, we show that the optimal-transport cost still coincides with the Gelbrich distance squared if $\frac{\hat{\mu}}{\hat{\sigma}} \geq \frac{\mu}{\sigma}$ and otherwise, is bounded from above by the Gelbrich distance squared plus a term related to the true and estimated mean and variance—a result may be of independent interest.

LEMMA 1. *Under Assumption 1, the optimal-transport cost of moving the data-generating distribution D to the mean-variance ambiguity set \mathcal{A}_N can be characterized as follows.*

(i) *If $\frac{\hat{\mu}}{\hat{\sigma}} \geq \frac{\mu}{\sigma}$, then $d(D, \mathcal{A}_N) = (\hat{\mu} - \mu)^2 + (\hat{\sigma} - \sigma)^2$.*

(ii) *If $\frac{\hat{\mu}}{\hat{\sigma}} < \frac{\mu}{\sigma}$, then for sufficiently large N , it holds that*

$$(\hat{\mu} - \mu)^2 + (\hat{\sigma} - \sigma)^2 \leq d(D, \mathcal{A}_N) \leq (\hat{\mu} - \mu)^2 + (\hat{\sigma} - \sigma)^2 + \frac{\mu^2 \hat{\sigma}^2 - \hat{\mu}^2 \sigma^2}{\sigma \hat{\sigma}}.$$

We also assume the following regularity condition on the data-generating distribution D .

ASSUMPTION 2. *The data-generating distribution D is sub-Gaussian with a variance proxy ν^2 , i.e., $\mathbb{E}_D[\exp(x(\tilde{\nu} - \mu))] \leq \exp(\frac{x^2 \nu^2}{2})$, $\forall x \in \mathbb{R}$.*

The sub-Gaussianity, as a common type of light-tailed characteristics,¹⁷ captures a wide range of probability distributions, including, among many others, Gaussian distribution, Bernoulli distribution, uniform distribution on a convex set, and *any* bounded distributions (Vershynin 2010). With the characterization of $d(D, \mathcal{A}_N)$ in Lemma 1, we derive the following concentration inequality.

PROPOSITION 5 (CONCENTRATION OF MEAN-VARIANCE AMBIGUITY SET). *Under Assumptions 1 and 2, for a given confidence level $\eta \in (0, 1]$, it holds for sufficiently large N that*

$$\mathbb{P}_{DN} \left[d(D, \mathcal{A}_N) \leq \frac{(c_1 + c_2 \log(1/\eta))^2}{\sqrt{N}} \right] \geq 1 - \eta,$$

where $c_1, c_2 > 0$ are constants that only depend on μ, σ , and ν .

¹⁷The light-tailed assumption is typically necessary for establishing the large-deviation properties for statistics of the sample mean and sample variance (Catoni 2012). As for the heavy-tailed distributions, more complex estimation procedures (for the mean and variance) are needed to achieve acceptable convergence rates (Cai et al. 2010).

Leveraging the concentration of ambiguity set \mathcal{A}_N and the closed-form expression of the worst-case transformed expectation (Proposition 2), we can then establish a finite-sample performance guarantee of the optimal solution to **MISSPECIFICATION**.

THEOREM 3 (FINITE-SAMPLE PERFORMANCE GUARANTEE). *Under Assumptions 1 and 2, for a given confidence level $\eta \in (0, 1]$, let $\varepsilon_N = \frac{(c_1 + c_2 \log(1/\eta))^2}{\sqrt{N}}$ with $c_1, c_2 > 0$ being constants that only depend on μ , σ , and ν , and*

$$\alpha_N = \begin{cases} \frac{1}{2} \sqrt{\frac{p(p-c)}{\varepsilon_N + d(F, D)}} & \varepsilon_N + d(F, D) < \kappa \left(\hat{\mu} - \hat{\sigma} \sqrt{\frac{1-\kappa}{\kappa}} \right)^2 \\ 0 & \varepsilon_N + d(F, D) \geq \kappa \left(\hat{\mu} - \hat{\sigma} \sqrt{\frac{1-\kappa}{\kappa}} \right)^2. \end{cases} \quad (11)$$

Consider the optimal solution $q_{\alpha_N}^*$ and the optimal value $\Pi_{\alpha_N}^*$ of **MISSPECIFICATION** with $\alpha = \alpha_N$ and $\mathcal{A} = \mathcal{A}_N$. For sufficiently large N , it holds that

$$\mathbb{P}_{D^N} \left[\mathbb{E}_F[\pi(q_{\alpha_N}^*, \tilde{u})] \geq \left(\underbrace{\Pi_{\alpha_N}^*}_{\substack{\text{in-sample} \\ \text{optimal value}}} - \frac{1}{2} \sqrt{\underbrace{p(p-c)\varepsilon_N}_{\substack{\text{effect of} \\ \text{estimation error}}} + \underbrace{p(p-c)d(F, D)}_{\substack{\text{effect of} \\ \text{distribution shift}}}} \right)^+ \right] \geq 1 - \eta,$$

where D^N is the N -fold product of D .

The guarantee derived in Theorem 3 is the in-sample optimal value of **MISSPECIFICATION** subtracting the out-of-sample misspecification effect described by the estimation error in mean and variance and the distribution shift. For the estimation error, it is related to the upper bound ε_N on the distance $d(D, \mathcal{A}_N)$ between the data-generating distribution and the estimated mean-variance ambiguity set, which diminishes as $N \rightarrow \infty$. For the distribution shift captured by $d(F, D)$, it is *independent* of the sample size N . A key statistical implication is that as long as the out-of-sample distribution F shifts from the data-generating distribution D , there is always a constant amount of loss $\frac{1}{2} \sqrt{p(p-c)d(F, D)}$ in terms of the performance guarantee, even as $N \rightarrow \infty$ ($\varepsilon_N \rightarrow 0$).

Theorem 3 also suggests that the calibration for the index α_N of misspecification aversion is affected by both the estimation error and the distribution shift. According to (11), when non-zero, α_N is increasing in the sample size N (*i.e.*, decreasing in ε_N) while decreasing in extent of distribution shift $d(F, D)$. This implies that at the same confidence level, the newsvendor needs to be more misspecification averse in either case of a smaller amount of data or a more significant distribution shift, to guarantee the performance. Moreover, in the presence of distribution shift ($d(F, D) > 0$), even when the estimation error vanishes with the sufficient data (*i.e.*, $\varepsilon_N \rightarrow 0$ as $N \rightarrow \infty$), $\alpha_N \rightarrow \frac{1}{2} \sqrt{\frac{p(p-c)}{d(F, D)}} < \infty$, implying that **MISSPECIFICATION** ($\alpha_N < \infty$) shall still outperform **AMBIGUITY** ($\alpha_N = \infty$). Importantly, this means that the commonly used cross-validation approach (which is based on the data-generating distribution D) for calibrating distributionally robust optimization models could, unfortunately, work *poorly* in the situation of misspecification (*i.e.*, calibrating the index α for **MISSPECIFICATION**), as we demonstrate in the numerical study.

6. Extensions

In this section, we extend the model [MISSPECIFICATION](#) along the following directions: (i) there are multiple products, (ii) the ambiguity set is defined via optimal transport, and (iii) the extent of misspecification is measured by ϕ -divergence (total-variation distance).

6.1. Multiple Products

Our misspecification-averse model can be extended to the multi-product newsvendor problem. Consider M products (each with unit price p_i and cost c_i , $i \in [M]$) whose random demands are collectively denoted by $\tilde{\mathbf{u}} = (\tilde{u}_1, \dots, \tilde{u}_M)$ that follows a multi-dimensional distribution F . The misspecification-averse newsvendor then solves

$$\max_{\mathbf{q} \geq \mathbf{0}} \min_{F \in \mathcal{P}_M} \{ \mathbb{E}_F[\omega(\mathbf{q}, \tilde{\mathbf{u}})] + \alpha \cdot d(F, \mathcal{C}) \}, \quad (\text{MULTIPLE})$$

where \mathcal{P}_M is the set of probability distributions supported on \mathbb{R}_+^M , the optimal-transport cost $d(\cdot, \cdot)$ is defined in [\(3\)](#) with the cost function $\|\cdot\|_2^2$, $\mathbf{q} = (q_1, \dots, q_M)$ is the vector of order quantities, and

$$\omega(\mathbf{q}, \mathbf{u}) = \sum_{i=1}^M \pi_i(q_i, u_i) = \sum_{i=1}^M p_i \cdot \min\{q_i, u_i\} - c_i q_i.$$

If the ambiguity set \mathcal{C} is specified by marginal mean-variance information of each product, then as a straightforward case, [MULTIPLE](#) is separable concerning products and is thus equivalent to

$$\sum_{i \in [M]} \max_{q_i \geq 0} \min_{F_i \in \mathcal{P}} \{ \mathbb{E}_{F_i}[\pi_i(q_i, \tilde{u}_i)] + \alpha \cdot d(F_i, \mathcal{C}_i) \},$$

where for each product $i \in [M]$, $\tilde{u}_i \sim F_i$ and the mean-variance ambiguity set $\mathcal{C}_i = \{G \in \mathcal{P} \mid \mathbb{E}_G[\tilde{v}] = \mu_i, \mathbb{E}_G[\tilde{v}^2] = \mu_i^2 + \sigma_i^2\}$. [Theorem 2](#) then yields each product's optimal order quantity.

If \mathcal{C} is specified by mean and correlation information, then [MULTIPLE](#) becomes much more involved, as its ambiguity-averse counterpart is already intractable ([Hanasusanto et al. 2015](#), [Natarajan et al. 2018](#)). For more details on the reformulation and computational difficulty of [MULTIPLE](#) with complete covariance information, we refer to [Section EC.6](#).

In the following, we show that an analytical solution can be derived for a case that captures the partial correlation across products. In particular, we consider an ambiguity set with mean and sum-of-variance constraints:

$$\mathcal{C} = \left\{ G \in \mathcal{P}_M \mid \mathbb{E}_G[\tilde{v}_i] = \mu_i \ \forall i \in [M], \ \mathbb{E}_G \left[\sum_{i \in [M]} \tilde{v}_i^2 \right] \leq K \right\},$$

where K is some non-negative constant that bounds the sum of the variance of products' demands. Note that when $M = 1$ (*i.e.*, there is a single product), the ambiguity set \mathcal{C} reduces to the mean-variance ambiguity set \mathcal{A} . The analytical solution to [MULTIPLE](#) with \mathcal{C} relies on characterizing the

optimal dual variable, denoted by λ^* , to its sum-of-variance constraint. We indicate that adopting a similar technique, we can also obtain the optimal solution of **MULTIPLE** under an additional budget constraint $\sum_{i \in [M]} q_i \leq Q$ for some $Q > 0$.

To ease our presentation, let $\bar{\lambda}_0 = 0$, $\bar{\lambda}_i = \frac{c_i}{(2\mu_i - p_i/\alpha)^+}$ for $i \in [M]$ and $\bar{\lambda}_{M+1} = +\infty$. Without loss of generality, we rearrange $\bar{\lambda}_i, i \in [M]$ ascendingly, *i.e.*, $\bar{\lambda}_1 \leq \bar{\lambda}_2 \leq \dots \leq \bar{\lambda}_M$. Besides, we define

$$i^* = \min\{j \in [M+1] \mid \Theta_j(\bar{\lambda}_j) < K\}, \quad (12)$$

where for $j \in [M+1]$ and $\lambda \geq 0$,

$$\Theta_j(\lambda) = \sum_{i \in [M] \setminus [j-1]} \frac{p_i \mu_i^2 (\alpha^2 c_i + 2\alpha c_i \lambda + p_i \lambda^2)}{(p_i \lambda + \alpha c_i)^2} + \sum_{i \in [j-1]} \frac{(p_i - c_i) c_i}{4\lambda^2}. \quad (13)$$

We then present the following strong-duality result that characterizes the optimal dual variable to the sum-of-variance constraint and the *decomposibility* of the dual problem.

THEOREM 4. *Given $K \geq 0$ and $\alpha \geq 0$, **MULTIPLE** is equivalent to*

$$\max_{\lambda \geq 0} \left\{ -\lambda K + \sum_{i \in [M]} \Pi_{i,\alpha}^*(\lambda) \right\}.$$

Here, for each $i \in [M]$, $\Pi_{i,\alpha}^*(\lambda)$ is the optimal value of the following optimization problem:

$$\Pi_{i,\alpha}^*(\lambda) = \max_{q_i \geq 0} \min_{F_i \in \mathcal{P}} \left\{ \mathbb{E}_{F_i} [\pi_i(q_i, \tilde{u}_i)] + \min_{G_i \in \mathcal{C}_i} \{ \lambda \cdot \mathbb{E}_{G_i} [\tilde{v}_i^2] + \alpha \cdot d(F_i, G_i) \} \right\} \quad (14)$$

with $\tilde{u}_i \sim F_i$, $\tilde{v}_i \sim G_i$, and $\mathcal{C}_i = \{G \in \mathcal{P} \mid \mathbb{E}_G[\tilde{v}] = \mu_i\}$ being a mean ambiguity set. Moreover, with i^* defined in (12) and $\Theta_{i^*}(\cdot)$ defined in (13), the optimal solution λ^* is decreasing in K and can be characterized as follows.

(i) If $\Theta_{i^*}(\bar{\lambda}_{i^*-1}) \leq K$, then $\lambda^* = \bar{\lambda}_{i^*-1}$.

(ii) If $\Theta_{i^*}(\bar{\lambda}_{i^*-1}) > K$, then $\lambda^* \in (\bar{\lambda}_{i^*-1}, \bar{\lambda}_{i^*})$ is the solution to the equation $\Theta_{i^*}(\lambda) = K$.

By Theorem 4, the value of λ^* can be efficiently determined,¹⁸ and given the value of λ^* , **MULTIPLE** can be decomposed into multiple misspecification-averse *single-product* newsvendor problems in (14). In particular, each single-product problem is now regularized by

$$\min_{G_i \in \mathcal{C}_i} \{ \lambda^* \cdot \mathbb{E}_{G_i} [\tilde{v}_i^2] + \alpha \cdot d(F_i, G_i) \}.$$

Moreover, it is critical to note that the optimal dual variable λ^* captures not only the demand-correlation information encoded in the sum-of-variance constraint, but also the cross-product cost structure (*i.e.*, p_i and c_i , $i \in [M]$) that collectively affects those single-product problems. The following result adapts the reasoning for Theorem 2 to derive the analytical solution for **MULTIPLE**.

¹⁸ Indeed, the value of λ^* can be determined efficiently via a binary search, by noting that given j , the function $\Theta_j(\lambda)$ decreases in λ ; for more details, see the proof of Theorem 4.

THEOREM 5 (OPTIMAL SOLUTION: MULTIPLE PRODUCTS). *Given $\alpha \geq 0$ and the optimal dual variable λ^* characterized in Theorem 4, the optimal order quantity \mathbf{q}_α^* of **MULTIPLE** is*

$$q_{i,\alpha}^* = \begin{cases} \mu_i + \frac{p_i - 2c_i}{4\lambda^*} - \frac{p_i}{4\alpha} & \alpha \geq \frac{p_i}{2(\mu_i - c_i/(2\lambda^*))^+} \\ \frac{\lambda^*(\lambda^* + \alpha)p_i\mu_i^2}{\alpha(p_i\lambda^*/\alpha + c_i)^2} & \alpha < \frac{p_i}{2(\mu_i - c_i/(2\lambda^*))^+} \end{cases} \quad \forall i \in [M]. \quad (15)$$

The analytical solution \mathbf{q}_α^* derived in (15) captures the information of distribution characteristics, cost structure, and correlation across products. In particular, the optimal order quantity $q_{i,\alpha}^*$ for each product i is not only determined by its distribution characteristic (*i.e.*, μ_i) and cost structure (*i.e.*, p_i and c_i), but also by those of other products via λ^* . Furthermore, in the multi-product problem, the index of misspecification aversion α has a *double effect* on the optimal order quantity (*i.e.*, α affects the optimal order quantity in two ways): on the one hand, it directly affects the optimal order quantity $q_{i,\alpha}^*$ of each product in the decomposed single-product problem (14); on the other hand, it also affects the optimal dual variable λ^* that in turn influences the optimal order quantities $q_{i,\alpha}^*$ of all products.

To better understand the ordering pattern of different products, we rewrite the formula (15) as

$$q_{i,\alpha}^* = \begin{cases} \mu_i + \frac{p_i - c_i}{4\lambda^*} - \frac{p_i}{4\alpha} & \lambda^* \geq \bar{\lambda}_i \\ \frac{\lambda^*(\lambda^* + \alpha)p_i\mu_i^2}{\alpha(p_i\lambda^*/\alpha + c_i)^2} & \lambda^* < \bar{\lambda}_i. \end{cases}$$

Note that λ^* , once determined, is a fixed term shared by all products, and each term $\bar{\lambda}_i$ is a constant that features product i . Therefore, the above expression can be partitioned into two patterns according to the comparisons between λ^* and $\bar{\lambda}_i$'s as follows:

$$q_{i,\alpha}^* = \begin{cases} \mu_i + \frac{p_i - c_i}{4\lambda^*} - \frac{p_i}{4\alpha} & i \in [i^* - 1] \\ \frac{\lambda^*(\lambda^* + \alpha)p_i\mu_i^2}{\alpha(p_i\lambda^*/\alpha + c_i)^2} & i \in [M] \setminus [i^* - 1]. \end{cases}$$

Since Theorem 4 suggests that λ^* is decreasing in K , a higher value of K for the sum of variance implies that more (resp., less) products would follow the pattern $q_{i,\alpha}^* = \frac{\lambda^*(\lambda^* + \alpha)p_i\mu_i^2}{\alpha(p_i\lambda^*/\alpha + c_i)^2}$ (resp., $q_{i,\alpha}^* = \mu_i + \frac{p_i - c_i}{4\lambda^*} - \frac{p_i}{4\alpha}$).

Finally, we emphasize that Theorem 5 generalizes Theorem 2 from a single product to multiple products (see Section EC.5 for a detailed derivation) as well as the forthcoming Corollary 1 for the ambiguity-averse multi-product model to ambiguity and misspecification aversion. Note that as $\alpha \rightarrow \infty$, **MULTIPLE** immediately reduces to the ambiguity-averse only counterpart

$$\max_{\mathbf{q} \geq \mathbf{0}} \min_{G \in \mathcal{C}} \mathbb{E}_G[\omega(\mathbf{q}, \tilde{\mathbf{v}})]. \quad (16)$$

Its optimal solution, as expected, generalizes the Scarf model from a single product to multiple products (see Figure 6). The proof is straightforward and is thus omitted.

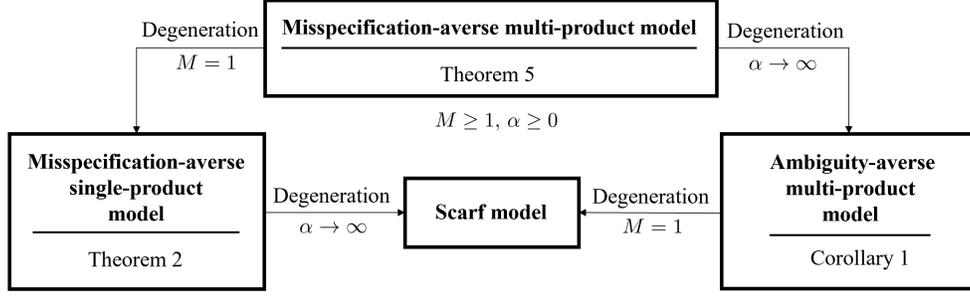


Figure 6 The closed-form solution (15) characterized in Theorem 5 generalizes the solutions for single-product misspecification-averse (Theorem 2 for **MISSPECIFICATION**) and ambiguity-averse multi-product (Corollary 1 for model (16)) newsvendor models, which in turn generalize the Scarf model **AMBIGUITY**.

COROLLARY 1. *Let the optimal dual variable λ^* be characterized in Theorem 4, the optimal quantity $q_{i,\infty}^*$ of the ambiguity-averse multi-product newsvendor problem (16) is given by*

$$q_{i,\infty}^* = \begin{cases} \mu_i + \frac{p_i - c_i}{4\lambda^*} & \lambda^* \geq \frac{c_i}{2\mu_i} \\ \frac{p_i \mu_i^2}{c_i^2} \cdot \lambda^* & \lambda^* < \frac{c_i}{2\mu_i} \end{cases} \quad \forall i \in [M].$$

6.2. Distance-Based Ambiguity Set

Apart from the mean-variance ambiguity set \mathcal{A} , the following distance-based ambiguity set

$$\mathcal{B}(\theta) = \{G \in \mathcal{P} \mid d(G, H) \leq \theta\}$$

with a reference distribution H , $\theta \geq 0$, and optimal-transport cost $d(\cdot, \cdot)$ between probability distributions is a popular alternative for specifying partial distributional information, which has also been widely used in aforementioned applications of decision theory (Petraçou et al. 2022), newsvendor (Chen and Xie 2021, Zhang et al. 2023), and risk management (Wozabal 2014). Conceptually, $\mathcal{B}(\theta)$ consists of all probability distributions in a θ -neighbourhood around H , where the closeness is measured by $d(\cdot, \cdot)$ given in (3). Since $\mathcal{B}(\theta_1) \subseteq \mathcal{B}(\theta_2)$ for any $\theta_2 \geq \theta_1 \geq 0$, a larger value of θ indicates a lower confidence in H . When $\theta = 0$, $\mathcal{B}(\theta)$ shrinks to a singleton containing only the reference distribution H , that is, $\mathcal{B}(0) = \{H\}$. It is natural to consider the following variant of **MISSPECIFICATION** where we replace \mathcal{A} with $\mathcal{B}(\theta)$:

$$\max_{q \geq 0} \min_{F \in \mathcal{P}} \left\{ \mathbb{E}_F[\pi(q, \tilde{u})] + \alpha \cdot d(F, \mathcal{B}(\theta)) \right\}, \quad (17)$$

which hedges against the possible misspecification over the ambiguity set $\mathcal{B}(\theta)$. Quite notably, problem (17) is essentially equivalent to hedging against misspecification over the singleton $\{H\}$ but with a *stronger* aversion to misspecification. To avoid a degenerate case, we assume $H^{-1}(\kappa) > 0$.

THEOREM 6 (OPTIMAL SOLUTION: DISTANCE-BASED AMBIGUITY SET). *Given $\theta \geq 0$, $\alpha \geq 0$ and a reference distribution H , there exists some $\gamma^* \in [0, \alpha]$ such that problem (17) can be equivalently reformulated as*

$$\max_{\psi \geq 0} \min_{F \in \mathcal{P}} \left\{ \mathbb{E}_F[\pi(\psi, \tilde{u})] + \gamma^* \cdot d(F, H) \right\}. \quad (18)$$

When $\theta = 0$, $\gamma^* = \alpha$; otherwise, with the optimal order quantity $q_H^* = H^{-1}(\kappa)$ of **NOMINAL** under H and $\beta = \int_0^{q_H^*} u^2 dH(u) > 0$, γ^* can be characterized as follows.

- (i) If $\theta \geq \beta$, then $\gamma^* = 0$.
- (ii) If $\theta < \beta$ and $\alpha(1 - \sqrt{\theta/\beta}) < \frac{p}{2q_H^*}$, then $\gamma^* = \alpha(1 - \sqrt{\theta/\beta})$.
- (iii) If $\theta < \beta$ and $\alpha(1 - \sqrt{\theta/\beta}) \geq \frac{p}{2q_H^*}$, then γ^* is the solution to

$$\int_0^{\frac{p}{2x}} u^2 dH(u) + \frac{p^2}{4x^2} \left(\kappa - H\left(\frac{p}{2x}\right) \right) - \frac{\alpha^2 \theta}{(\alpha - x)^2} = 0.$$

With γ^* , the optimal order quantity $\psi_{\gamma^*}^*$ of problem (18) can be characterized as

$$\psi_{\gamma^*}^* = \begin{cases} q_H^* \cdot \left(\frac{\gamma^* q_H^*}{p} \right) & \gamma^* < \frac{p}{2q_H^*} \\ q_H^* - \frac{p}{4\gamma^*} & \gamma^* \geq \frac{p}{2q_H^*}. \end{cases}$$

Theorem 6 establishes the equivalence between problem (17)—which hedges against misspecification over a distance-based ambiguity set $\mathcal{B}(\theta)$ around the reference distribution—and problem (18) that, with a stronger aversion, hedges against misspecification to the reference distribution H . Note that Theorem 6 states that $\gamma^* = \alpha$ whenever $\theta = 0$ —which, indeed, corresponds to the ambiguity neutrality. If we further have $\alpha \rightarrow \infty$, then problem (17) reduces to **NOMINAL** under H , and as expected, Theorem 6 concludes that $\psi_{\gamma^*}^* = q_H^*$.

6.3. Misspecification Measured by ϕ -Divergence

Apart from the optimal-transport cost, ϕ -divergence is also popular for measuring the closeness between probability distributions. In this section, we replace $d(\cdot, \cdot)$ in (3) with ϕ -divergence when defining $d(F, \mathcal{A})$ and investigate the corresponding **MISSPECIFICATION** problem.

Formally, equipped with a convex function $\phi : \mathbb{R}_+ \mapsto \mathbb{R}$ such that $\phi(x)$ is finite for all $x > 0$, $\phi(1) = 0$, and $\phi(0) = \lim_{t \downarrow 0} \phi(t)$, the ϕ -divergence of a probability distribution F relative to another probability distribution G is defined as

$$d_\phi(F \parallel G) = \begin{cases} \int_{\mathbb{R}_+} \phi\left(\frac{dF}{dG}\right) dG & \text{if } F \ll G \\ \infty & \text{otherwise.} \end{cases}$$

Here, $F \ll G$ means that F is absolutely continuous with respect to G . Specifically, we consider a function $\phi(t) = |t - 1|$ that would lead to the closed-form solution,¹⁹ making managerial insights possible. The ϕ -divergence equipped with such a function $\phi(\cdot)$ is also called the *total variation* (TV) distance. Given this ϕ -divergence, we investigate the following variant of **MISSPECIFICATION**:

$$\max_{q \geq 0} \min_{G \in \mathcal{A}} \min_{F \in \mathcal{P}} \{ \mathbb{E}_F[\pi(q, \tilde{v})] + \alpha \cdot d_\phi(F \| G) \}. \quad (19)$$

THEOREM 7 (OPTIMAL SOLUTION: TV-BASED MISSPECIFICATION). *Given $\alpha \geq 0$, the mean-variance ambiguity set \mathcal{A} , and the divergence function $\phi(t) = |t - 1|$, problem (19) can be equivalently reformulated as*

$$\max_{0 \leq q \leq \frac{2\alpha}{p}} \min_{G \in \mathcal{A}} \mathbb{E}_G[\pi(q, \tilde{v})]$$

and its optimal order quantity is

$$q_\alpha^* = \min \left\{ \frac{2\alpha}{p}, q_\infty^* \right\},$$

where q_∞^* is the optimal order quantity of **AMBIGUITY** characterized in (1).

Theorem 7 reveals that the optimal order quantity q_α^* of problem (19) grows increasingly and linearly in α , capped by the optimal order quantity q_∞^* of **AMBIGUITY**. When α is sufficiently large (that is, $\alpha \geq \frac{p}{2}q_\infty^*$), q_α^* coincides with q_∞^* . In this case, the newsvendor fully trusts the information specified in \mathcal{A} and essentially becomes misspecification neutral to the ambiguity set \mathcal{A} . Hence, ambiguity aversion takes full charge of determining the formula of q_α^* . When α is relatively small (that is, $\alpha < \frac{p}{2}q_\infty^*$), $q_\alpha^* = \frac{2\alpha}{p}$ is then purely determined by misspecification aversion without being affected by the mean-variance information in \mathcal{A} .

7. Numerical Experiments with Retailing Data

In this section, we demonstrate the effectiveness of incorporating misspecification, using the real-world daily demand data over one year for different stock keeping units (SKUs) of our industrial partner (a supermarket). Our goal is to compare the out-of-sample expected profit of the optimal order quantities obtained from **MISSPECIFICATION** and **AMBIGUITY**, as well as **NOMINAL**.²⁰

¹⁹ We point out that other types of ϕ -divergence can also be applied to problem (19) of misspecification, which however are less computationally appealing. For instance, if $d_\phi(\cdot \| \cdot)$ is defined as the Kullback–Leibler divergence with $\phi(t) = t \log(t) - t + 1$, then problem (19) becomes optimizing the worst-case CARA, which is generally intractable (Chen and Sim 2023). Also, if we take $d_\phi(\cdot \| \cdot)$ as the Gini concentration index with $\phi(t) = \frac{1}{2}(t - 1)^2$, then problem (19) becomes optimizing worst-case mean-variance, which does not admit analytical solutions either.

²⁰ The solution of **NOMINAL** is obtained by using the discrete empirical data (SAA approach).

7.1. Data and Models

Our data consists of a set of SKUs, and we first consider the popular drinking water (as mentioned in Figure 1 and denoted by SKU_0) that shows non-stationary characteristics, especially in the sense of monthly mean and variance. For the experimental purpose, we consider the demand data in two consecutive months as training and testing samples. In particular, according to the variability in sales series and the associate mean-variance change over the consecutive months as demonstrated in Figure 1, we identify October vs. November as a *low-variability* scenario, January vs. February as a *moderate-variability* scenario, and August vs. September as a *high-variability* scenario. See the first column of Figure 7, highlighting the non-stationarity of the demand.

At the end of the training month, the newsvendor obtains the demand observations (training samples) $\hat{v}_1, \dots, \hat{v}_N$ and needs to determine the order quantity to satisfy the random demand that will materialize in the testing month. The newsvendor solves **NOMINAL** with the empirical distribution based on $\hat{v}_1, \dots, \hat{v}_N$. For **AMBIGUITY**, the newsvendor estimates μ and σ^2 of the mean-variance ambiguity set \mathcal{A} via sample mean and sample variance, that is, $\mu = \frac{1}{N} \sum_{i=1}^N \hat{v}_i$ and $\sigma^2 = \frac{1}{N} \sum_{i=1}^N \hat{v}_i^2 - \left(\frac{1}{N} \sum_{i=1}^N \hat{v}_i\right)^2$. However, taking these estimates as mean and variance of the demand in the testing month may lead to misspecification (recall from Figure 1). It is thus meaningful to consider **MISSPECIFICATION** with different values of α .

7.2. Results and Discussion

Figure 7 summarizes the results of different approaches in the three scenarios where the variability between training and testing samples is, respectively, low, moderate, and high. Regarding the in-sample expected profit, in all scenarios, **NOMINAL** achieves the highest value, while **MISSPECIFICATION** converges to **AMBIGUITY** as α approaches infinity. Focusing on the out-of-sample performance, *first*, in the low-variability scenario (that is, the first row of Figure 7), **NOMINAL** outperforms **AMBIGUITY**, and under most values of α , **MISSPECIFICATION** does not yield a higher out-of-sample expected profit than **NOMINAL**—an intuitive result since the demand process is quite stationary. *Furthermore*, in the moderate-variability scenario (that is, the second row of Figure 7), **NOMINAL** yields \$3.19 in the out-of-sample expected profit while **MISSPECIFICATION** (resp., **AMBIGUITY**) results in an improvement at most \$0.54 or 16.93% in percentage (resp., an improvement of \$0.25 or 7.84%). *Finally*, in the high-variability scenario (that is, the third row of Figure 7), **AMBIGUITY** and **MISSPECIFICATION** have an even larger improvement in out-of-sample expected profit: **NOMINAL** yields \$3.24 while **MISSPECIFICATION** (resp., **AMBIGUITY**) results in an improvement at most \$2.65 or 81.79% (resp., an improvement of \$1.18 or 36.42%).

In the third column of Figure 7, we emphasize two values of the index of misspecification aversion, α^{CV} and α^* . The former is selected via cross-validation using the training data, while the latter

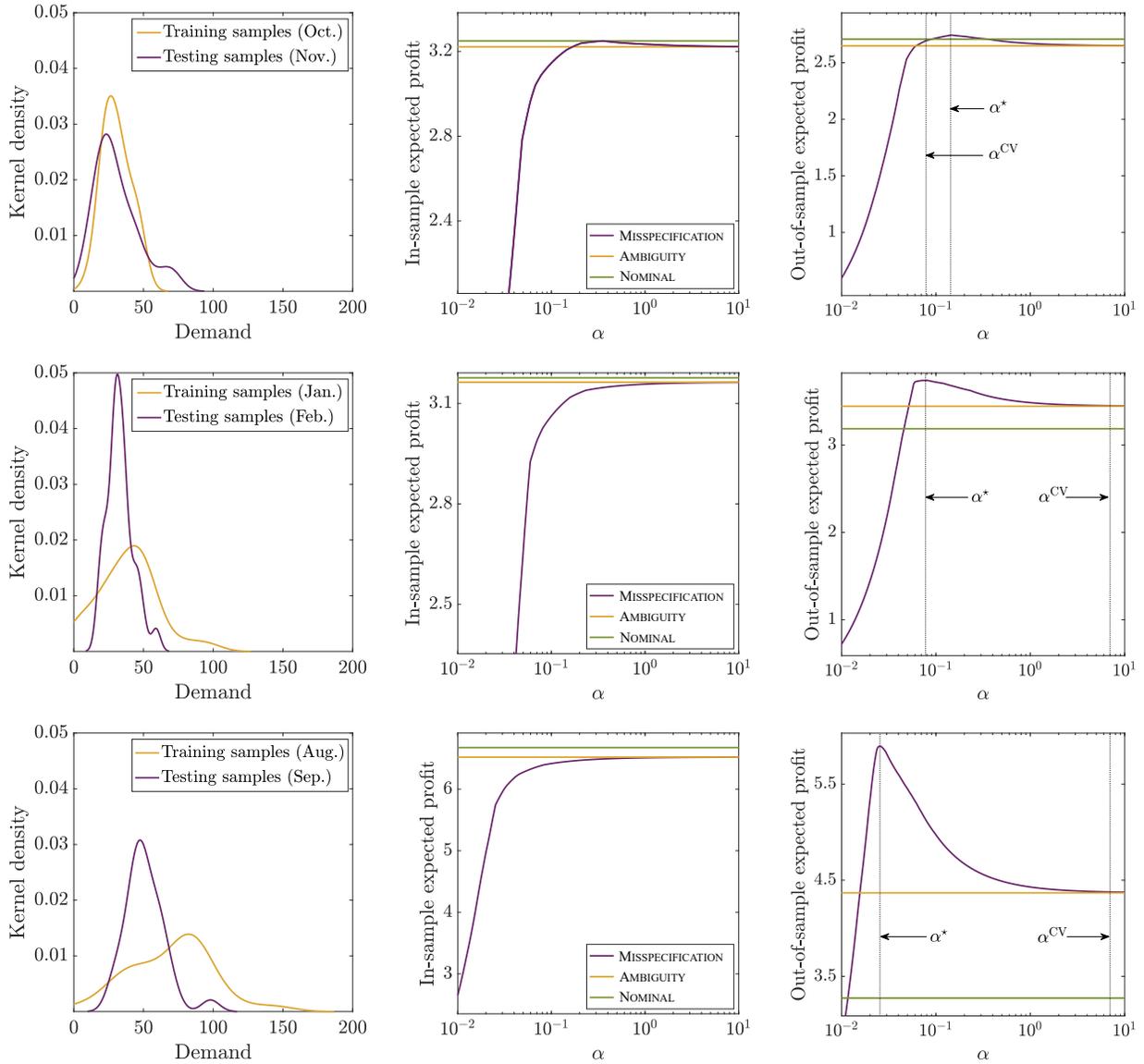


Figure 7 Kernel density of demand data and performance of **MISSPECIFICATION**, **AMBIGUITY**, and **NOMINAL** in the low-variability scenario (first row), moderate-variability scenario (second row), and high-variability scenario (third row). In the second (resp., third) column, the in-sample (resp., out-of-sample) expected profit refers to the expected profit under the empirical distribution of training (resp., testing) samples.

is the one that achieves the largest out-of-sample expected profit. We would like to highlight two important observations and insights as follows.

1. In the low-variability scenario with stationary demand, **MISSPECIFICATION** with α^{CV} performs quite close to **NOMINAL** and **AMBIGUITY**, and α^{CV} is also close to α^* . This, not only justifies the predominance of mean-variance statistics in capturing the underlying distribution for the newsvendor's decision, but also implies the usefulness of the cross-validation method in calibrating the parameter α of **MISSPECIFICATION**, in the situation of stationary demand.

α	Performance Comparison	Percentage	Π_M		Π_A		Π_S	
			Mean STD	Mean STD	Mean STD	Mean STD		
α_{low}	$\Pi_M > \Pi_S$ and $\Pi_M > \Pi_A$	28%	24.95 19.93	14.49 13.17	15.90 14.33			
	$\Pi_M \leq \Pi_S$ or $\Pi_M \leq \Pi_A$	72%	5.09 7.22	8.60 8.94	8.80 8.45			
α_{mid}	$\Pi_M > \Pi_S$ and $\Pi_M > \Pi_A$	81%	12.07 10.95	9.74 9.72	9.56 9.15			
	$\Pi_M \leq \Pi_S$ or $\Pi_M \leq \Pi_A$	19%	13.28 14.55	12.52 13.59	15.91 15.51			
α_{high}	$\Pi_M > \Pi_S$ and $\Pi_M > \Pi_A$	69%	11.49 11.04	10.03 10.10	9.58 9.50			
	$\Pi_M \leq \Pi_S$ or $\Pi_M \leq \Pi_A$	31%	11.47 11.55	10.69 11.39	13.06 12.84			

Table 2 Out-of-sample expected profits over 100 SKUs. For each SKU, $\alpha_{\text{low}} = p/100$, $\alpha_{\text{mid}} = p/20$, and $\alpha_{\text{high}} = p/10$, where p is the unit price of the SKU. Here, we denote by Π_M , Π_A , and Π_S the out-of-sample expected profits of [MISSPECIFICATION](#), [AMBIGUITY](#), and [NOMINAL](#), respectively.

- In the moderate-variability and high-variability scenarios with non-stationary demand, the calibrated [MISSPECIFICATION](#) model with $\alpha = \alpha^{\text{CV}}$ yields an out-of-sample performance close to that of [AMBIGUITY](#), which, however, is *far away* from the best performance that [MISSPECIFICATION](#) could achieve with $\alpha = \alpha^*$. This verifies the implication of finite-sample performance guarantee derived in Theorem 3: in the situation of distribution shift where the testing samples vary highly from the training samples, cross-validation—purely relying on training samples—could be depreciative in its effectiveness for calibrating a model’s parameter.

We next repeat the above experiment over a pool of 100 SKUs, for each of which we randomly select two consecutive months as training and testing samples. For each SKU, we consider the same setting as in Section 7.1 to evaluate the out-of-sample expected profits of [MISSPECIFICATION](#), [AMBIGUITY](#), and [NOMINAL](#). Table 2 summarizes the number of SKUs that one model outperforms another, and the corresponding mean and standard deviation of the out-of-sample profits of a model over these SKUs. Under a small value of α (*i.e.*, α_{low}), for 28% of 100 SKUs, [MISSPECIFICATION](#) outperforms both [AMBIGUITY](#) and [NOMINAL](#) with a large profit improvement but a large standard deviation; for the majority 72%, [MISSPECIFICATION](#) underperforms either [AMBIGUITY](#) or [NOMINAL](#) with a large profit loss and a small standard deviation. Under a medium value of α (*i.e.*, α_{mid}), [MISSPECIFICATION](#) yields superior performance than both [AMBIGUITY](#) and [NOMINAL](#) by noting that [MISSPECIFICATION](#) outperforms both [AMBIGUITY](#) and [NOMINAL](#) for a majority 81% of 100 SKUs. Even under a high value of α (*i.e.*, α_{high}), [MISSPECIFICATION](#) also has a fairly good out-of-sample performance, where [MISSPECIFICATION](#) outperforms both [AMBIGUITY](#) and [NOMINAL](#) for a majority 69% of 100 SKUs. In other words, for each $\alpha \in \{\alpha_{\text{low}}, \alpha_{\text{mid}}, \alpha_{\text{high}}\}$, there always quite a proportion of SKUs such that over these products [MISSPECIFICATION](#) has a better out-of-sample performance than both [AMBIGUITY](#) and [NOMINAL](#), justifying the need of incorporating misspecification to the newsvendor problem.

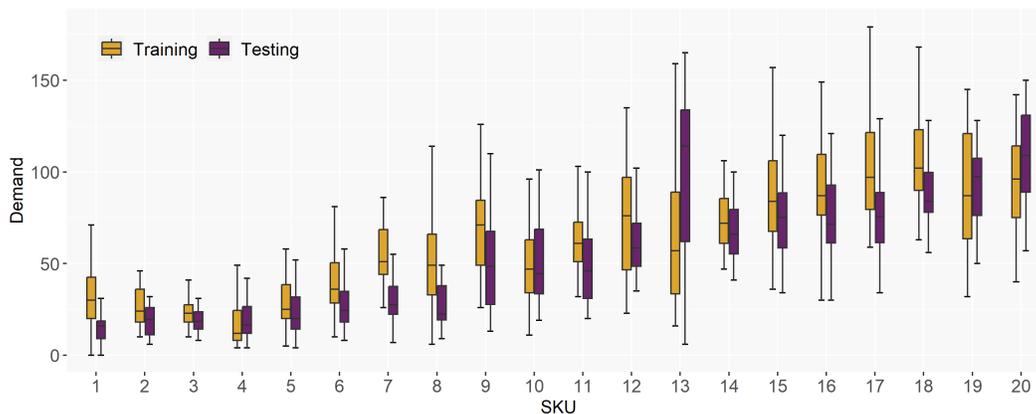


Figure 8 Boxplots of daily demand data of each SKU in two consecutive months, which we refer to as training and testing period, respectively.

7.3. More Results on Multi-Product Model

We perform similar experiments using the multi-product newsvendor model **MULTIPLE**, for which we employ the demand data of $M = 20$ SKUs whose life cycles share two consecutive (training and testing) months. The real-life demand data of these SKUs is visualized in Figure 8, which demonstrates a non-negligible variability between the training and testing demand samples. We estimate, with the training data, the parameters μ_i 's and K of **MULTIPLE** by the sample means and the sum of the sample second-order moment, respectively. We then test the performance of **MULTIPLE**, the corresponding ambiguity-averse model (16), as well as the nominal counterpart. Figure 9 plots the results of the three different approaches, and similar conclusions to the single-product case can be drawn that justify the value of capturing the misspecification aversion in newsvendor's decision-making.

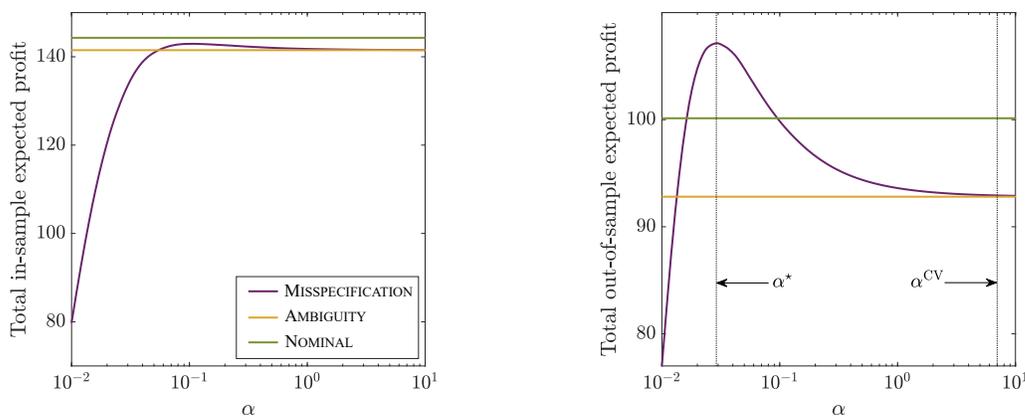


Figure 9 Performance comparison of **MULTIPLE**, the ambiguity-averse multi-product newsvendor model (16), and the associated nominal multi-product newsvendor model under the training empirical distribution.

8. Conclusion

Since the seminal work of Scarf (1958), the mean-variance ambiguity set has been popularly employed for decision-making in mitigating the distributional uncertainty. However, in many practical situations, the mean and variance can be misspecified, resulting consequently in inexperienced news vendor decisions. To address this issue, we introduce misspecification upon ambiguity and propose a misspecification-averse (and ambiguity-averse) news vendor model. We investigate the impact and rationale of misspecification aversion from decision-criterion, operational, and statistical perspectives. We also extend our model to establish a comprehensive framework (multi-products, ambiguity captured by optimal transport, and misspecification measured by ϕ -divergence) for the news vendor under ambiguity and misspecification.

Our present study focuses on and has investigated many aspects of the misspecification-averse news vendor problem. The framework has several interesting directions remaining unexplored and can be extended to other operational problems, opening up promising avenues for future studies.

Estimation of distribution shift. As articulated in Theorem 3, the performance guarantee and the index of misspecification aversion are statistically described with a term of distribution shift. How to estimate the distribution shift is critical and also practically relevant for calibrating the index of misspecification aversion. This task is statistically involved and is also an important research topic in machine learning (Lipton et al. 2018, Cauchois et al. 2024).

Misspecification in prescriptive analytics. Prescriptive analytics, as an emerging paradigm for data-driven decision-making, seeks a decision rule that maps the observed data to an action, which usually leverages some parametric or non-parametric (structural) assumptions on the uncertainty (see, e.g., Bertsimas and Kallus 2020, Qi and Shen 2022, Chu et al. 2024). These parametric or non-parametric models assumed could misspecify the ground truth. Therefore, we believe that our approach, in marriage with the prescriptive analytics framework, has the potential to mitigate the downside consequences of model misspecification.

Structuring distributional uncertainty in other operations management problems.

Although this study focuses on the news vendor problem, our analysis can also be attempted in other operations management settings, for instance, inventory control, logistics, dynamic pricing, and project management, wherein the distributional uncertainty has been widely acknowledged. Following the spirit of “all models are wrong, but some are useful” (Box 1976), we believe that treating ambiguity and misspecification differently in a properly structured fashion can differentiate the *useful* wrong models and *harmful* wrong models in coping with uncertainty, and therefore enhance the decisions for operations management.

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E-Companion to “Newsvendor under Mean-Variance Ambiguity and Misspecification”

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EC.1. Technical Lemmas

LEMMA EC.1. *For any $F, G \in \mathcal{P}$, $d(F, G)$ in (3) is jointly convex in F and G .*

Proof. Given $F_1, F_2, G_1, G_2 \in \mathcal{P}$, let $\Gamma_1 \in \mathcal{W}(F_1, G_1)$ and $\Gamma_2 \in \mathcal{W}(F_2, G_2)$ be the joint distributions that solve the corresponding optimal transport. That is,

$$d(F_1, G_1) = \int_{\mathbb{R}_+ \times \mathbb{R}_+} |u - v|^2 \Gamma_1(du, dv) \quad \text{and} \quad d(F_2, G_2) = \int_{\mathbb{R}_+ \times \mathbb{R}_+} |u - v|^2 \Gamma_2(du, dv).$$

We first show that the joint distribution $\Gamma_\lambda = (1 - \lambda)\Gamma_1 + \lambda\Gamma_2$ has marginals $F_\lambda = (1 - \lambda)F_1 + \lambda F_2$ and $G_\lambda = (1 - \lambda)G_1 + \lambda G_2$. In fact, for any Borel set $\mathfrak{B} \subseteq \mathbb{R}_+$, we have

$$\begin{aligned} \Gamma_\lambda(\mathfrak{B} \times \mathbb{R}_+) &= (1 - \lambda)\Gamma_1(\mathfrak{B} \times \mathbb{R}_+) + \lambda\Gamma_2(\mathfrak{B} \times \mathbb{R}_+) = (1 - \lambda)F_1(\mathfrak{B}) + \lambda F_2(\mathfrak{B}) \\ \Gamma_\lambda(\mathbb{R}_+ \times \mathfrak{B}) &= (1 - \lambda)\Gamma_1(\mathbb{R}_+ \times \mathfrak{B}) + \lambda\Gamma_2(\mathbb{R}_+ \times \mathfrak{B}) = (1 - \lambda)G_1(\mathfrak{B}) + \lambda G_2(\mathfrak{B}), \end{aligned}$$

which implies that $\Gamma_\lambda \in \mathcal{W}(F_\lambda, G_\lambda)$. As a result,

$$\begin{aligned} d(F_\lambda, G_\lambda) &\leq \int_{\mathbb{R}_+ \times \mathbb{R}_+} |u - v|^2 \Gamma_\lambda(du, dv) \\ &= (1 - \lambda) \int_{\mathbb{R}_+ \times \mathbb{R}_+} |u - v|^2 \Gamma_1(du, dv) + \lambda \int_{\mathbb{R}_+ \times \mathbb{R}_+} |u - v|^2 \Gamma_2(du, dv) \\ &= (1 - \lambda) \cdot d(F_1, G_1) + \lambda \cdot d(F_2, G_2), \end{aligned}$$

where the last line follows from the definition of Γ_1 and Γ_2 . □

LEMMA EC.2. *Suppose that $0 < \varepsilon < \infty$, and let Υ_ε^* denote the optimal value of problem (4) corresponding to ε , and Π_α^* the optimal value of [MISSPECIFICATION](#) corresponding to α . Then,*

$$\Upsilon_\varepsilon^* = \max_{\alpha \geq 0} \{\Pi_\alpha^* - \varepsilon\alpha\}. \tag{EC.1}$$

The optimal value α^ of problem (EC.1) is achieved, and the optimal solution $(q_{\alpha^*}^*, F_{\alpha^*}^*)$ of [MISSPECIFICATION](#) associated with $\alpha = \alpha^*$ is also the optimal solution to problem (4).*

Proof. We start by fixing the order quantity. For any fixed $q \geq 0$, we define a function $\varphi(q, \varepsilon) = \min_{d(F, \mathcal{A}) \leq \varepsilon} \mathbb{E}_F[\pi(q, \tilde{v})]$. First, it is clear that $\varphi(q, \varepsilon)$ is decreasing in ε . Second, $\varphi(q, \varepsilon)$ is bounded on \mathbb{R}_+ because for any $\varepsilon \in [0, +\infty)$, $-cq \leq \varphi(q, \varepsilon) \leq (p - c)q$. Third, $\varphi(q, \varepsilon)$ is convex in ε on \mathbb{R}_{++} . To see this, we fix $F_1, F_2 \in \mathcal{P}$ and $\varepsilon_1, \varepsilon_2 \geq 0$ such that $d(F_1, \mathcal{A}) \leq \varepsilon_1$ and $d(F_2, \mathcal{A}) \leq \varepsilon_2$. Note that $d(F, \mathcal{A}) = \min_{G \in \mathcal{A}} d(F, G)$ is also convex in F because $d(F, G)$ is jointly convex in F and G (Lemma EC.1) and maximization over a convex set preserves convexity. For any $\lambda \in [0, 1]$, it holds that

$$d(\lambda F_1 + (1 - \lambda)F_2, \mathcal{A}) \leq \lambda d(F_1, \mathcal{A}) + (1 - \lambda)d(F_2, \mathcal{A}) \leq \lambda \varepsilon_1 + (1 - \lambda)\varepsilon_2,$$

where the first inequality follows from the convexity of $d(\cdot, \mathcal{A})$. Thus we have

$$\varphi(q, \lambda \varepsilon_1 + (1 - \lambda)\varepsilon_2) \geq \mathbb{E}_{\lambda F_1 + (1 - \lambda)F_2}[\pi(q, \tilde{u})] = \lambda \cdot \mathbb{E}_{F_1}[\pi(q, \tilde{u})] + (1 - \lambda) \cdot \mathbb{E}_{F_2}[\pi(q, \tilde{u})].$$

Taking the minimum over F_1 and F_2 yields

$$\varphi(q, \lambda \varepsilon_1 + (1 - \lambda)\varepsilon_2) \geq \lambda \varphi(q, \varepsilon_1) + (1 - \lambda)\varphi(q, \varepsilon_2),$$

which establishes the convexity (and continuity) of $\varphi(q, \varepsilon)$. Finally, given $\alpha > 0$, the Legendre transform of the convex function $\varphi(q, \cdot)$ is

$$\begin{aligned} \varphi^*(q, \alpha) &= \min_{\varepsilon \geq 0} \{\alpha \varepsilon + \varphi(q, \varepsilon)\} = \min_{\varepsilon \geq 0} \min_{F \in \mathcal{P}} \{\alpha \varepsilon + \mathbb{E}_F[\pi(q, \tilde{u})] : d(F, \mathcal{A}) \leq \varepsilon\} \\ &= \min_{F \in \mathcal{P}} \min_{\varepsilon \geq 0} \{\alpha \varepsilon + \mathbb{E}_F[\pi(q, \tilde{u})] : d(F, \mathcal{A}) \leq \varepsilon\} \\ &= \min_{F \in \mathcal{P}} \{\alpha \cdot d(F, \mathcal{A}) + \mathbb{E}_F[\pi(q, \tilde{u})]\}, \end{aligned}$$

which is concave in α . Note that the above relation also holds for $\alpha = 0$. For any $\varepsilon > 0$, applying Legendre transform on the concave function $\varphi^*(q, \cdot)$ yields

$$(\varphi^*(q, \varepsilon))^* = \max_{\alpha \geq 0} \{\varphi^*(q, \alpha) - \alpha \varepsilon\} = \max_{\alpha \geq 0} \left\{ \min_{F \in \mathcal{P}} \{\mathbb{E}_F[\pi(q, \tilde{u})] + \alpha \cdot d(F, \mathcal{A})\} - \varepsilon \alpha \right\}.$$

Since $\varphi(q, \varepsilon)$ is bounded, convex, and continuous, for any $\varepsilon > 0$, it holds that $\varphi(q, \varepsilon) = (\varphi^*(q, \varepsilon))^*$.

We now optimize the order quantity. Maximizing over $q \geq 0$ yields

$$\Upsilon_\varepsilon^* = \max_{q \geq 0} \varphi(q, \varepsilon) = \max_{q \geq 0} \min_{d(F, \mathcal{A}) \leq \varepsilon} \mathbb{E}_F[\pi(q, \tilde{u})] \tag{EC.2}$$

$$= \max_{q \geq 0} \max_{\alpha \geq 0} \left\{ \min_{F \in \mathcal{P}} \{\mathbb{E}_F[\pi(q, \tilde{u})] + \alpha \cdot d(F, \mathcal{A})\} - \varepsilon \alpha \right\} \tag{EC.3}$$

$$= \max_{\alpha \geq 0} \left\{ \max_{q \geq 0} \min_{F \in \mathcal{P}} \{\mathbb{E}_F[\pi(q, \tilde{u})] + \alpha \cdot d(F, \mathcal{A})\} - \varepsilon \alpha \right\} \tag{EC.4}$$

$$= \max_{\alpha \geq 0} \{\Pi_\alpha^* - \varepsilon \alpha\}, \tag{EC.5}$$

where (EC.4) follows from switching the “max” operators over q and α , and (EC.5) follows from the definition of Π_α^* . Indeed, the optimal value of (EC.5) is achieved at some finite $\alpha^* \geq 0$ because

the function $\Pi_\alpha^* - \varepsilon\alpha$ is continuous in α with $\Pi_0^* - \varepsilon \cdot 0 = 0$ and $\Pi_\alpha^* - \varepsilon\alpha \rightarrow -\infty$ as $\alpha \rightarrow \infty$. Finally, note that the optimal solution (α^*, q^*, F^*) of (EC.4) has its part (q^*, F^*) being the optimal solution of MISSPECIFICATION with $\alpha = \alpha^*$, which we have denoted by (q_α^*, F_α^*) . Since (EC.4) and (EC.3) are equivalent, (α^*, q^*, F^*) (i.e., $(\alpha^*, q_\alpha^*, F_\alpha^*)$) is also optimal to (EC.3). Consequently, $(q_{\alpha^*}^*, F_{\alpha^*}^*)$ is optimal to (EC.2), i.e., problem (4). This concludes the proof. \square

LEMMA EC.3 (INTERCHANGEABILITY). *Given $G \in \mathcal{P}$ and a measurable function $h(\cdot) : \mathbb{R}_+ \mapsto \mathbb{R}$ with $\mathbb{E}_G[h(\tilde{u})] < +\infty$, we have*

$$\min_{F \in \mathcal{P}, \Gamma \in \mathcal{W}(F, G)} \mathbb{E}_\Gamma[h(\tilde{u}) + \alpha \cdot |\tilde{u} - \tilde{v}|^2] = \mathbb{E}_G \left[\min_{u \geq 0} \{h(u) + \alpha \cdot |u - \tilde{v}|^2\} \right].$$

Proof. Denote by \mathcal{M} the set of all measurable mappings from \mathbb{R}_+ to \mathbb{R}_+ . Since $(\mathbb{R}_+, \|\cdot\|)$ is a Polish space, the interchangeability principle holds, implying that

$$\mathbb{E}_G \left[\min_{u \geq 0} \{h(u) + \alpha \cdot |u - \tilde{v}|^2\} \right] = \min_{m \in \mathcal{M}} \mathbb{E}_G [h(m(\tilde{v})) + \alpha \cdot |m(\tilde{v}) - \tilde{v}|^2].$$

By theorem 1 in Zhang et al. (2022), it then holds that

$$\min_{F \in \mathcal{P}, \Gamma \in \mathcal{W}(F, G)} \{ \mathbb{E}_F[h(\tilde{u})] + \alpha \cdot \mathbb{E}_\Gamma[|\tilde{u} - \tilde{v}|^2] \} = \mathbb{E}_G \left[\min_{u \geq 0} \{h(u) + \alpha \cdot |u - \tilde{v}|^2\} \right],$$

completing the proof. \square

LEMMA EC.4. *Let $\ell(\alpha, q, v) = \min_{u \geq 0} \{ \pi(q, u) + \alpha(u - v)^2 \}$. For any fixed $v \geq 0$,*

(i) *if $0 \leq q \leq \frac{p}{4\alpha}$, then*

$$\ell(\alpha, q, v) = \min\{\alpha v^2, pq\} - cq;$$

(ii) *if $q > \frac{p}{4\alpha}$, then*

$$\ell(\alpha, q, v) = \begin{cases} \alpha v^2 - cq & 0 \leq v \leq \frac{p}{2\alpha} \\ p \cdot \min\left\{v - \frac{p}{4\alpha}, q\right\} - cq & v > \frac{p}{2\alpha}. \end{cases}$$

Proof. The function $\pi(q, v) + \alpha(v - u)^2$ can be written as a piecewise quadratic function as follows:

$$g(u, q, v) = p \min\{q, u\} - cq + \alpha(u - v)^2 = \begin{cases} \underline{g}(u) = pu - cq + \alpha(u - v)^2 & u \leq q \\ \bar{g}(u) = pq - cq + \alpha(u - v)^2 & u > q. \end{cases}$$

Before proceeding, we denote the left and right derivatives of $g(u, q, v)$ at $u = u_0$ by $g'_-(u_0)$ and $g'_+(u_0)$, respectively. Based on the value of v , there are three cases to consider.

(i) If $v \geq q + \frac{p}{2\alpha}$, i.e., $g'_-(q) = 2\alpha(q - v) + p \leq 0$, then $\underline{g}(u)$ is decreasing over $(0, q]$. Note that $\bar{g}'(u) = 2\alpha(u - v) = 0$ admits a unique solution $u = v$, implying that $\bar{g}(u)$ is decreasing in (q, v) and increasing in $[v, +\infty)$. Therefore, it holds that

$$\min_{u \geq 0} g(u, q, v) = \min_{u \geq q} \bar{g}(u) = \bar{g}(v) = pq - cq.$$

(ii) If $v \leq q$, i.e., $\bar{g}'_+(q) = 2\alpha(q - v) \geq 0$, and we have $g'(u) = 2\alpha(u - v) + p = 0$ admits a unique solution $u = v - \frac{p}{2\alpha}$, implying that $g(u)$ is first decreasing in $[0, (v - p/2\alpha)^+]$ and then increasing in $((v - p/2\alpha)^+, q]$, and $\bar{g}(u)$ is increasing in $(q, +\infty)$. Therefore, it holds that

$$\min_{u \geq 0} g(u, q, v) = \min_{0 \leq u \leq q} \underline{g}(u) = \underline{g}\left(\left(v - \frac{p}{2\alpha}\right)^+\right).$$

(iii) If $q \leq v \leq q + \frac{p}{2\alpha}$, i.e., $\underline{g}'_-(q) \geq 0$ and $\bar{g}'_+(q) \leq 0$, then both $\underline{g}(u)$ and $\bar{g}(u)$ admit a corresponding minimizer in the domain. It follows that

$$\min_{u \geq 0} g(u, q, v) = \min \left\{ \underline{g}\left(\left(v - \frac{p}{2\alpha}\right)^+\right), \bar{g}(v) \right\}.$$

Note that

$$\underline{g}\left(\left(v - \frac{p}{2\alpha}\right)^+\right) = \begin{cases} \alpha v^2 - cq & v < \frac{p}{2\alpha} \\ p\left(v - \frac{p}{4\alpha}\right) - cq & \frac{p}{2\alpha} \leq v \leq q + \frac{p}{2\alpha}. \end{cases}$$

We next discuss based on the value of q . When $q \geq \frac{p}{2\alpha}$, we have

$$\begin{aligned} \ell(\alpha, q, v) = \min_{u \geq 0} g(u, q, v) &= \begin{cases} \alpha v^2 - cq & v \leq \frac{p}{2\alpha} \\ p\left(v - \frac{p}{4\alpha}\right) - cq & \frac{p}{2\alpha} \leq v \leq q \\ p \cdot \min\left\{v - \frac{p}{4\alpha}, q\right\} - cq & q \leq v \leq q + \frac{p}{2\alpha} \\ pq - cq & v \geq q + \frac{p}{2\alpha} \end{cases} \\ &= \begin{cases} \alpha v^2 - cq & v \leq \frac{p}{2\alpha} \\ p\left(v - \frac{p}{4\alpha}\right) - cq & \frac{p}{2\alpha} \leq v \leq q + \frac{p}{4\alpha} \\ pq - cq & v \geq q + \frac{p}{4\alpha}; \end{cases} \end{aligned}$$

When $q \leq \frac{p}{2\alpha}$, we have

$$\ell(\alpha, q, v) = \min_{u \geq 0} g(u, q, v) = \begin{cases} \alpha v^2 - cq & v \leq q \\ \min\{\alpha v^2, pq\} - cq & q \leq v \leq \frac{p}{2\alpha} \\ p \cdot \min\left\{v - \frac{p}{4\alpha}, q\right\} - cq & \frac{p}{2\alpha} \leq v \leq q + \frac{p}{2\alpha} \\ pq - cq & v \geq q + \frac{p}{2\alpha}. \end{cases}$$

If $\frac{p}{4\alpha} \leq q \leq \frac{p}{2\alpha}$, then $\min\{\alpha v^2, pq\} = \alpha v^2$ for $u \in [q, \frac{p}{2\alpha}]$, resulting in

$$\ell(\alpha, q, v) = \begin{cases} \alpha v^2 - cq & v \leq \frac{p}{2\alpha} \\ p\left(v - \frac{p}{4\alpha}\right) - cq & \frac{p}{2\alpha} \leq v \leq q + \frac{p}{4\alpha} \\ pq - cq & v \geq q + \frac{p}{4\alpha}. \end{cases}$$

If $q \leq \frac{p}{4\alpha}$, then $p \cdot \min \left\{ v - \frac{p}{4\alpha}, q \right\} - cq = pq - cq$ for $v \in \left[\frac{p}{2\alpha}, q + \frac{p}{2\alpha} \right]$. Correspondingly,

$$\ell(\alpha, q, v) = \begin{cases} \alpha v^2 - cq & v \leq \sqrt{\frac{pq}{\alpha}} \\ pq - cq & v \geq \sqrt{\frac{pq}{\alpha}} \end{cases} = \min\{\alpha v^2, pq\} - cq.$$

Consolidating these results based on the three ranges of q then completes the proof. \square

EC.2. Proofs.

Proof of Theorem 1.

In the **MISSPECIFICATION** problem, given $q \geq 0$ and $G \in \mathcal{A}$, it holds that

$$\min_{F \in \mathcal{P}} \{\mathbb{E}_F[\pi(q, \tilde{u})] + \alpha \cdot d(F, G)\} = \mathbb{E}_G \left[\min_{u \geq 0} \{\pi(q, u) + \alpha(u - \tilde{v})^2\} \right] = \mathbb{E}_G[\ell(\alpha, q, \tilde{v})].$$

Here, the first equality follows from the interchangeability principle (Lemma EC.3) and the second equality follows from $\ell(\alpha, q, v) = \min_{u \geq 0} \{\pi(q, u) + \alpha(u - v)^2\}$ (see Lemma EC.4 for its closed-form expression). It suffices to verify for any $q \geq 0$ that

$$\int_{\mathbb{R}_+} \pi(q, v) dT_{\varphi_\alpha}[G](v) = \int_{\mathbb{R}_+} \ell(\alpha, q, v) dG(v) \quad \forall G \in \mathcal{A}.$$

In view of (i), that is, $q < \frac{p}{4\alpha}$, we have

$$\int_{\mathbb{R}_+} \pi(q, v) dT_{\varphi_\alpha}[G](v) = \int_{\mathbb{R}_+} \pi(q, v) dG\left(\sqrt{\frac{p}{\alpha}}v\right) = \int_{\mathbb{R}_+} \pi\left(q, \frac{\alpha}{p}v^2\right) dG(v) = \int_{\mathbb{R}_+} \ell(\alpha, q, v) dG(v),$$

where the second equality follows from the variable substitution $v \leftarrow \sqrt{\frac{p}{\alpha}}v$ and the third equality follows from the fact that $\ell(\alpha, q, v) = \min\{\alpha v^2, pq\} - cq$ when $q < \frac{p}{4\alpha}$.

As for (ii), that is, $q \geq \frac{p}{4\alpha}$, we have

$$\begin{aligned} \int_{\mathbb{R}_+} \pi(q, v) dT_{\varphi_\alpha}[G](v) &= \int_0^{\frac{p}{4\alpha}} \pi(q, v) dG\left(\sqrt{\frac{p}{\alpha}}v\right) + \int_{\frac{p}{4\alpha}}^\infty \pi(q, v) dG\left(v + \frac{p}{4\alpha}\right) \\ &= \int_0^{\frac{p}{2\alpha}} \pi\left(q, \frac{\alpha}{p}v^2\right) dG(v) + \int_{\frac{p}{2\alpha}}^\infty \pi\left(q, v - \frac{p}{4\alpha}\right) dG(v) \\ &= \int_0^\infty \ell(\alpha, q, v) dG(v), \end{aligned}$$

where the second equality follows from the variable substitution: $v \leftarrow \sqrt{\frac{p}{\alpha}}v$ for $v < \frac{p}{4\alpha}$ and $v \leftarrow v + \frac{p}{4\alpha}$ for $v \geq \frac{p}{4\alpha}$ and the third equality follows from the fact that $\ell(\alpha, q, v) = \min\{\alpha v^2, pq\} - cq = \alpha v^2 - cq$ when $v < \frac{p}{2\alpha}$ and $\ell(\alpha, q, v) = p \min\{v - \frac{p}{4\alpha}, q\} - cq$ when $v \geq \frac{p}{2\alpha}$. \square

Proof of Proposition 1.

We show that ρ_α^G is a convex risk measure given $G \in \mathcal{A}$ by verifying its cash invariance, monotonicity, and convexity. First, note that for any $r \geq 0$, we have

$$\rho_\alpha^G(\pi(q, \tilde{v}) + r) = - \min_{F \in \mathcal{P}} \{\mathbb{E}_F[\pi(q, \tilde{u}) + r] + \alpha \cdot d(F, G)\} = \rho_\alpha^G(\pi(q, \tilde{v})) - r,$$

which verifies the cash-invariance property of ρ_α . Second, given $F \in \mathcal{P}$ and any $q_1, q_2 \geq 0$ that satisfy $\pi(q_1, \tilde{u}) \leq \pi(q_2, \tilde{u})$ almost surely, we have

$$-(\mathbb{E}_F[\pi(q_1, \tilde{u})] + \alpha \cdot d(F, G)) \geq -(\mathbb{E}_F[\pi(q_2, \tilde{u})] + \alpha \cdot d(F, G)),$$

and hence $\rho_\alpha^G(\pi(q_1, \tilde{v})) \geq \rho_\alpha^G(\pi(q_2, \tilde{v}))$ by taking the maximum over $F \in \mathcal{A}$, which implies the monotonicity of ρ_α . Finally, given $\alpha \geq 0$ and $q_1, q_2 \geq 0$, it holds that

$$\begin{aligned} & \min_{F \in \mathcal{P}} \{ \mathbb{E}_F[\lambda\pi(q_1, \tilde{u}) + (1-\lambda)\pi(q_2, \tilde{u})] + \alpha \cdot d(F, G) \} \\ & \geq \lambda \cdot \min_{F \in \mathcal{P}} \{ \mathbb{E}_F[\pi(q_1, \tilde{u})] + \alpha \cdot d(F, G) \} + (1-\lambda) \cdot \min_{F \in \mathcal{P}} \{ \mathbb{E}_F[\pi(q_2, \tilde{u})] + \alpha \cdot d(F, G) \}, \end{aligned}$$

and hence $\rho_\alpha^G(\lambda\pi(q_1, \tilde{v}) + (1-\lambda)\pi(q_2, \tilde{v})) \leq \lambda\rho_\alpha^G(\pi(q_1, \tilde{v})) + (1-\lambda)\rho_\alpha^G(\pi(q_2, \tilde{v}))$, which establishes the convexity of ρ_α . \square

Proof of Proposition 2.

Note that for any $q \geq 0$, it holds that

$$L(q) = \min_{F \in \mathcal{P}, G \in \mathcal{A}} \{ \mathbb{E}_F[\pi(q, \tilde{u})] + \alpha \cdot d(F, G) \} = \min_{G \in \mathcal{A}} \mathbb{E}_G[\Psi(\alpha, q, \tilde{v})],$$

where $\Psi(\alpha, q, v) = \pi(q, \varphi_\alpha(v))$. Given $q \geq 0$, $L(q)$ is a classic moment problem as follows:

$$\begin{aligned} & \min_G \int_{\mathbb{R}_+} \Psi(\alpha, q, v) dG(v) \\ & \text{s.t.} \quad \int_{\mathbb{R}_+} v dG(v) = \mu \quad \cdots s_\alpha \\ & \quad \int_{\mathbb{R}_+} v^2 dG(v) = \mu^2 + \sigma^2 \quad \cdots r_\alpha \\ & \quad \int_{\mathbb{R}_+} dG(v) = 1 \quad \cdots t_\alpha \\ & \quad G \in \mathcal{M}_+, \end{aligned} \tag{PRIMAL}$$

whose dual is

$$\begin{aligned} & \max_{s_\alpha, r_\alpha, t_\alpha} \mu s_\alpha - (\mu^2 + \sigma^2) r_\alpha - t_\alpha \\ & \text{s.t.} \quad v s_\alpha - v^2 r_\alpha - t_\alpha \leq \Psi(\alpha, q, v) \quad \forall v \geq 0 \\ & \quad s_\alpha \in \mathbb{R}, r_\alpha \in \mathbb{R}, t_\alpha \in \mathbb{R}. \end{aligned} \tag{DUAL}$$

We next derive the expression of $L(q)$ by constructing a pair of primal and dual feasible solutions that attain the same objective value (*i.e.*, strong duality holds between **PRIMAL** and **DUAL**). The argument breaks into three scenarios based on the value of q .

Scenario 1. When $0 \leq q \leq \frac{p}{4\alpha}$, we first construct a feasible distribution to **PRIMAL** as follows:

$$G_\alpha = \left(\frac{1}{2} - \frac{\mu^2 - \sigma^2 - \frac{pq}{\alpha}}{2\sqrt{(\frac{pq}{\alpha} + \mu^2 + \sigma^2)^2 - 4\mu^2 \frac{pq}{\alpha}}} \right) \cdot \delta_{v_1} + \left(\frac{1}{2} + \frac{\mu^2 - \sigma^2 - \frac{pq}{\alpha}}{2\sqrt{(\frac{pq}{\alpha} + \mu^2 + \sigma^2)^2 - 4\mu^2 \frac{pq}{\alpha}}} \right) \cdot \delta_{v_2}, \tag{EC.6}$$

where the support points are

$$\begin{aligned} v_1 &= \frac{1}{2\mu} \left(\frac{pq}{\alpha} + \mu^2 + \sigma^2 - \sqrt{\left(\frac{pq}{\alpha} + \mu^2 + \sigma^2 \right)^2 - 4\mu^2 \frac{pq}{\alpha}} \right) \\ v_2 &= \frac{1}{2\mu} \left(\frac{pq}{\alpha} + \mu^2 + \sigma^2 + \sqrt{\left(\frac{pq}{\alpha} + \mu^2 + \sigma^2 \right)^2 - 4\mu^2 \frac{pq}{\alpha}} \right). \end{aligned}$$

One can verify that $G_\alpha \in \mathcal{A}$ and the corresponding primal objective value under G_α is equal to

$$\mathbb{E}_{G_\alpha}[\Psi(\alpha, q, \tilde{u})] = \frac{\alpha}{2} \left(\frac{pq}{\alpha} + \mu^2 + \sigma^2 - \sqrt{\left(\frac{pq}{\alpha} + \mu^2 + \sigma^2 \right)^2 - 4\mu^2 \frac{pq}{\alpha}} \right) - cq.$$

We next construct a dual feasible solution that attains the same dual objective value. Note that $\Psi(\alpha, q, v) = \min\{\alpha v^2, pq\} - cq \forall v \geq 0$ when $0 \leq q \leq \frac{p}{4\alpha}$ (Lemma EC.4). Hence, **DUAL** becomes

$$\begin{aligned} & \max_{s_\alpha, r_\alpha, t_\alpha} s_\alpha \mu - r_\alpha (\mu^2 + \sigma^2) - t_\alpha \\ & \text{s.t.} \quad s_\alpha v - r_\alpha v^2 - t_\alpha \leq \alpha v^2 - cq \quad \forall v \geq 0 \\ & \quad \quad s_\alpha v - r_\alpha v^2 - t_\alpha \leq pq - cq \quad \forall v \geq 0 \\ & \quad \quad s_\alpha \in \mathbb{R}, r_\alpha \in \mathbb{R}, t_\alpha \in \mathbb{R}. \end{aligned}$$

Consider the following solution:

$$\begin{cases} s_\alpha = \frac{2\mu pq}{\sqrt{\left(\frac{pq}{\alpha} + \mu^2 + \sigma^2\right)^2 - 4\mu^2 \frac{pq}{\alpha}}} \\ r_\alpha = \frac{\alpha}{2} \left(\frac{\frac{pq}{\alpha} + \mu^2 + \sigma^2}{\sqrt{\left(\frac{pq}{\alpha} + \mu^2 + \sigma^2\right)^2 - 4\mu^2 \frac{pq}{\alpha}}} - 1 \right) \\ t_\alpha = \frac{pq}{2} \left(\frac{\frac{pq}{\alpha} + \mu^2 + \sigma^2}{\sqrt{\left(\frac{pq}{\alpha} + \mu^2 + \sigma^2\right)^2 - 4\mu^2 \frac{pq}{\alpha}}} - 1 \right) + cq, \end{cases} \quad (\text{EC.7})$$

which satisfies

$$s_\alpha \mu - r_\alpha (\mu^2 + \sigma^2) - t_\alpha = \frac{\alpha}{2} \left(\frac{pq}{\alpha} + \mu^2 + \sigma^2 - \sqrt{\left(\frac{pq}{\alpha} + \mu^2 + \sigma^2 \right)^2 - 4\mu^2 \frac{pq}{\alpha}} \right) - cq.$$

It remains to argue that this solution is feasible to **DUAL**. If $q = 0$, then $s_\alpha = r_\alpha = t_\alpha = 0$, naturally feasible to **DUAL**. We next investigate $q > 0$. In this case, $r_\alpha > 0$. The first semi-infinite constraint of **DUAL** is equivalent to

$$\max_{v \geq 0} \{s_\alpha v - (r_\alpha + \alpha)v^2 - t_\alpha + cq\} \leq 0.$$

For the left-hand side maximization, the optimal solution is $v^* = \frac{s_\alpha}{2(r_\alpha + \alpha)} \geq 0$, which attains an optimal value of $\frac{s_\alpha^2}{4(r_\alpha + \alpha)} - t_\alpha + cq = 0$. Hence, the first semi-infinite constraint is satisfied. Similarly, the second semi-infinite constraint of **DUAL** is equivalent to

$$\max_{v \geq 0} \{s_\alpha v - r_\alpha v^2 - t_\alpha - pq + cq\} \leq 0.$$

For the left-hand side, the optimal solution is $v^* = \frac{s_\alpha}{2r_\alpha}$ and the corresponding optimal value is $\frac{s_\alpha^2}{4r_\alpha} - t_\alpha - pq + cq = \frac{pq(r_\alpha + \alpha)}{\alpha} - \frac{pq}{\alpha} r_\alpha - pq = 0$. Hence, the second semi-infinite constraint is also satisfied, concluding that solution (EC.7) is feasible to **DUAL** and establishing the strong duality.

Scenario 2. When $q \geq \frac{p}{4\alpha}$ and $(2\mu - \frac{p}{\alpha})q < \mu^2 + \sigma^2 - \frac{p\mu}{2\alpha}$, **DUAL** becomes

$$\begin{aligned} & \max_{s_\alpha, r_\alpha, t_\alpha} s_\alpha \mu - r_\alpha (\mu^2 + \sigma^2) - t_\alpha \\ & \text{s.t.} \quad s_\alpha v - r_\alpha v^2 - t_\alpha \leq \alpha v^2 - cq \quad \forall 0 \leq v \leq \frac{p}{2\alpha} \\ & \quad \quad s_\alpha v - r_\alpha v^2 - t_\alpha \leq p \left(v - \frac{p}{4\alpha} \right) - cq \quad \forall v \geq \frac{p}{2\alpha} \\ & \quad \quad s_\alpha v - r_\alpha v^2 - t_\alpha \leq pq - cq \quad \forall v \geq \frac{p}{2\alpha} \\ & \quad \quad s_\alpha \in \mathbb{R}, r_\alpha \in \mathbb{R}, t_\alpha \in \mathbb{R}. \end{aligned}$$

Consider the pair of primal feasible solution (EC.6) and dual solution (EC.7). Upon the results in *Step 1*, it remains to argue that solution (EC.7) is feasible to the above representation of **DUAL**. Note that in *Step 1*, we have shown that $s_\alpha v - r_\alpha v^2 - t_\alpha \leq \alpha v^2 - cq \forall v \geq 0$ and $s_\alpha v - r_\alpha v^2 - t_\alpha \leq pq - cq \forall v \geq 0$, which are, respectively, more restrictive than the first and third semi-infinite constraints herein. Hence, the first and third constraints are satisfied. We next investigate the second constraint

$$\max_{v \geq \frac{p}{2\alpha}} \left\{ (s_\alpha - p)v - r_\alpha v^2 - t_\alpha + cq + \frac{p^2}{4\alpha} \right\} \leq 0.$$

The unconstrained maximizer $\frac{s_\alpha - p}{2r_\alpha}$ of the left-hand side maximization satisfies

$$\frac{s_\alpha - p}{2r_\alpha} = \frac{1}{2\mu} \left(\frac{pq}{\alpha} + \mu^2 + \sigma^2 - \sqrt{\left(\frac{pq}{\alpha} + \mu^2 + \sigma^2 \right)^2 - 4\mu^2 \frac{pq}{\alpha}} \right) \leq \frac{p}{2\alpha},$$

where the inequality follows from $(2\mu - \frac{p}{\alpha})q < \mu^2 + \sigma^2 - \frac{p\mu}{2\alpha}$. This implies that the constrained maximization is attained at $v = \frac{p}{2\alpha}$, and we have

$$s_\alpha \frac{p}{2\alpha} - r_\alpha \frac{p^2}{4\alpha^2} - t_\alpha \leq \alpha \frac{p^2}{4\alpha^2} - cq = p \left(\frac{p}{2\alpha} - \frac{p}{4\alpha} \right) - cq,$$

where the inequality follows from evaluating the first semi-infinite constraint at $v = \frac{p}{2\alpha}$. Hence, the second semi-infinite constraint is also satisfied, concluding this step.

Scenario 3. When $q \geq \frac{p}{4\alpha}$ and $(2\mu - \frac{p}{\alpha})q \geq \mu^2 + \sigma^2 - \frac{p\mu}{2\alpha}$, we first construct a feasible primal solution:

$$G_\alpha = \frac{1}{2} \left(1 + \frac{q + \frac{p}{4\alpha} - \mu}{\sqrt{\left(q + \frac{p}{4\alpha} - \mu \right)^2 + \sigma^2}} \right) \cdot \delta_{v_1} + \frac{1}{2} \left(1 - \frac{q + \frac{p}{4\alpha} - \mu}{\sqrt{\left(q + \frac{p}{4\alpha} - \mu \right)^2 + \sigma^2}} \right) \cdot \delta_{v_2}, \quad (\text{EC.8})$$

where

$$v_1 = q + \frac{p}{4\alpha} - \sqrt{\left(q + \frac{p}{4\alpha} - \mu \right)^2 + \sigma^2} \quad \text{and} \quad v_2 = q + \frac{p}{4\alpha} + \sqrt{\left(q + \frac{p}{4\alpha} - \mu \right)^2 + \sigma^2}.$$

One can verify that $G_\alpha \in \mathcal{A}$ and the corresponding primal objective value under G_α is equal to

$$\mathbb{E}_{G_\alpha}[\Psi(\alpha, q, \tilde{u})] = \frac{p}{2} \left(\mu - q - \frac{p}{4\alpha} - \sqrt{\left(q + \frac{p}{4\alpha} - \mu \right)^2 + \sigma^2} \right) + (p - c)q.$$

We next construct a dual feasible solution that attains the same dual objective value. Note that when $q \geq \frac{p}{4\alpha}$ and $(2\mu - \frac{p}{\alpha})q \geq \mu^2 + \sigma^2 - \frac{p\mu}{2\alpha}$, **DUAL** becomes

$$\begin{aligned} & \max_{s_\alpha, r_\alpha, t_\alpha} s_\alpha \mu - r_\alpha (\mu^2 + \sigma^2) - t_\alpha \\ & \text{s.t.} \quad s_\alpha v - r_\alpha v^2 - t_\alpha \leq \alpha v^2 - cq & \forall 0 \leq v \leq \frac{p}{2\alpha} \\ & \quad s_\alpha v - r_\alpha v^2 - t_\alpha \leq p \left(v - \frac{p}{4\alpha} \right) - cq & \forall v \geq \frac{p}{2\alpha} \\ & \quad s_\alpha v - r_\alpha v^2 - t_\alpha \leq pq - cq & \forall v \geq \frac{p}{2\alpha} \\ & \quad s_\alpha \in \mathbb{R}, r_\alpha \in \mathbb{R}, t_\alpha \in \mathbb{R}. \end{aligned}$$

Consider the following solution:

$$r_\alpha = \frac{p}{4\sqrt{(q + \frac{p}{4\alpha} - \mu)^2 + \sigma^2}}, \quad (\text{EC.9})$$

$$s_\alpha = \frac{p}{2} + 2r_\alpha \left(q + \frac{p}{4\alpha} \right), \quad \text{and} \quad t_\alpha = \frac{p^2}{16r_\alpha} + r_\alpha \left(q + \frac{p}{4\alpha} \right)^2 + \frac{p}{2} \left(q + \frac{p}{4\alpha} \right) - (p-c)q.$$

Because

$$s_\alpha \mu - r_\alpha (\mu^2 + \sigma^2) - t_\alpha = \frac{p}{2} \left(\mu - q - \frac{p}{4\alpha} - \sqrt{\left(q + \frac{p}{4\alpha} - \mu \right)^2 + \sigma^2} \right) + (p-c)q,$$

it remains to argue that this solution is feasible to **DUAL**. We observe that

$$\max_{v \geq 0} \left\{ (s_\alpha - p)v - r_\alpha v^2 + cq - t_\alpha + \frac{p^2}{4\alpha} \right\} \leq 0.$$

Indeed, for the left-hand side maximization, an optimal solution $v^* = \frac{s_\alpha - p}{2r_\alpha} \geq \frac{p}{2\alpha} \geq 0$ achieves the optimal value of $\frac{s_\alpha^2}{4(r_\alpha + \alpha)} - t_\alpha + cq + \frac{p^2}{4\alpha} = 0$. Hence, it holds that

$$-t_\alpha + s_\alpha v - r_\alpha v^2 \leq p \left(v - \frac{p}{4\alpha} \right) - cq \leq \alpha v^2 - cq \quad \forall v \geq 0,$$

where the last inequality follows from the fact that $p(v - \frac{p}{4\alpha}) \leq \alpha v^2 \quad \forall v \geq 0$. Consequently, the first and second semi-infinite constraints are satisfied. Finally, we note that

$$\max_{v \geq 0} \{ s_\alpha v - r_\alpha v^2 - t_\alpha + cq - pq \} = s_\alpha \frac{s_\alpha}{2r_\alpha} - r_\alpha \frac{s_\alpha^2}{4r_\alpha^2} - t_\alpha + cq - pq = 0,$$

where the first equality follows from the fact that an optimal solution to the leftmost maximization is $v^* = \frac{s_\alpha}{2r_\alpha}$ and the second equality follows from the definition of $(s_\alpha, r_\alpha, t_\alpha)$. Hence, the third semi-infinite constraint holds, concluding this step.

Note that *Scenario 1* and *Scenario 2* correspond to the same objective function. Combining the results in these three scenarios we then obtain the desired result immediately. \square

Proof of Theorem 2.

Defining $L(q) = \min_{G \in \mathcal{A}} \mathbb{E}_G[\Psi(\alpha, q, \tilde{v})]$, **MISSPECIFICATION** is then equivalent to $\max_{q \geq 0} L(q)$. Note that when $\kappa < \frac{\sigma^2}{\mu^2 + \sigma^2}$,

$$\max_{q \geq 0} \min_{G \in \mathcal{A}} \mathbb{E}_G[\Psi(\alpha, q, \tilde{v})] \leq \max_{q \geq 0} \min_{G \in \mathcal{A}} \mathbb{E}_G[\pi(q, \tilde{v})] = 0,$$

where the inequality holds since $\Psi(\alpha, q, v) = \pi(q, \varphi_\alpha(v)) \leq \pi(q, v) \forall q \geq 0$ and the equality follows from the tight lower bound derived in Scarf (1958). The order quantity $q = 0$ satisfies $\mathbb{E}_G[\Psi(\alpha, 0, \tilde{v})] = 0 \forall G \in \mathcal{A}$ (i.e., $\min_{G \in \mathcal{A}} \mathbb{E}_G[\Psi(\alpha, 0, \tilde{v})] = 0$). Hence, $q_\alpha^* = 0$. This corresponds to case (ii) in the statement. In the remainder of the proof, we focus on $\kappa \geq \frac{\sigma^2}{\mu^2 + \sigma^2}$. As shown in Proposition 2, we have

$$L(q) = \begin{cases} \frac{p}{2} \left(\mu - q - \frac{p}{4\alpha} - \sqrt{\left(q + \frac{p}{4\alpha} - \mu \right)^2 + \sigma^2} \right) + (p-c)q & \text{if } q \in \mathcal{Q} \\ \frac{\alpha}{2} \left(\frac{pq}{\alpha} + \mu^2 + \sigma^2 - \sqrt{\left(\frac{pq}{\alpha} + \mu^2 + \sigma^2 \right)^2 - 4\mu^2 \frac{pq}{\alpha}} \right) - cq & \text{otherwise} \end{cases}$$

where $\mathcal{Q} = \{q \in \mathbb{R}_+ \mid q \geq \frac{p}{4\alpha}, (2\mu - \frac{p}{\alpha})q \geq \mu^2 + \sigma^2 - \frac{p\mu}{2\alpha}\}$ as well as its derivative

$$L'(q) = \begin{cases} \frac{p}{2} \left(1 - \frac{2(q + \frac{p}{4\alpha})}{\sqrt{(q + \frac{p}{4\alpha} - \mu)^2 + \sigma^2}} \right) - c & \text{if } q \in \mathcal{Q} \\ \frac{p}{2} \left(1 - \frac{2(\frac{pq}{\alpha} + \sigma^2 - \mu^2)}{\sqrt{(\frac{pq}{\alpha} + \mu^2 + \sigma^2)^2 - 4\mu^2 \frac{pq}{\alpha}}} \right) - c & \text{otherwise.} \end{cases}$$

Based on the value of α , we divide the arguments into three different scenarios.

Scenario 1. Suppose that $\alpha < \frac{p}{2\mu}$, i.e., $2\mu - \frac{p}{\alpha} < 0$. For any $q \geq \frac{p}{4\alpha}$, it holds that $(2\mu - \frac{p}{\alpha})q \leq (2\mu - \frac{p}{\alpha})\frac{p}{4\alpha} = \frac{p}{\alpha}(\mu - \frac{p}{4\alpha}) - \frac{p\mu}{2\alpha} < \mu^2 + \sigma^2 - \frac{p\mu}{2\alpha}$, where the strict inequality follows from the fact that $\frac{p}{\alpha}(\mu - \frac{p}{4\alpha}) < \mu^2$ when $\alpha < \frac{p}{2\mu}$. That is to say, for any $q \geq 0$ we have

$$L(q) = \frac{\alpha}{2} \left(\frac{pq}{\alpha} + \mu^2 + \sigma^2 - \sqrt{\left(\frac{pq}{\alpha} + \mu^2 + \sigma^2 \right)^2 - 4\mu^2 \frac{pq}{\alpha}} \right) - cq.$$

Setting the derivative of $L(q)$ to 0, we then obtain

$$\frac{p}{2} \left(1 - \frac{2(\frac{pq_\alpha^*}{\alpha} + \sigma^2 - \mu^2)}{\sqrt{(\frac{pq_\alpha^*}{\alpha} + \mu^2 + \sigma^2)^2 - 4\mu^2 \frac{pq_\alpha^*}{\alpha}}} \right) - c = 0 \implies q_\alpha^* = (\mu^2 - \sigma^2 + 2f(1-\kappa)\mu\sigma) \cdot \frac{\alpha}{p}.$$

Scenario 2. Suppose that $\frac{p}{2\mu} \leq \alpha < \frac{p}{2(\mu - \sigma\sqrt{(1-\kappa)/\kappa})}$. Note that $(2\mu - \frac{p}{\alpha})\frac{p}{4\alpha} + \frac{p\mu}{2\alpha} = \frac{p}{\alpha}(\mu - \frac{p}{2\alpha}) \leq \mu^2 + \sigma^2$, where the inequality is due to the fact that $\frac{p}{\alpha}(\mu - \frac{p}{2\alpha}) \leq \frac{\mu^2}{2}$. Hence, $\frac{p}{4\alpha} \leq \frac{\mu}{2} + \frac{\sigma^2}{2\mu - \frac{p}{\alpha}}$, yielding

$$L(q) = \begin{cases} \frac{\alpha}{2} \left(\frac{pq}{\alpha} + \mu^2 + \sigma^2 - \sqrt{\left(\frac{pq}{\alpha} + \mu^2 + \sigma^2 \right)^2 - 4\mu^2 \frac{pq}{\alpha}} \right) - cq & q \leq \frac{\mu}{2} + \frac{\sigma^2}{2\mu - \frac{p}{\alpha}} \\ \frac{p}{2} \left(\mu - q - \frac{p}{4\alpha} - \sqrt{\left(q + \frac{p}{4\alpha} - \mu \right)^2 + \sigma^2} \right) + (p-c)q & q \geq \frac{\mu}{2} + \frac{\sigma^2}{2\mu - \frac{p}{\alpha}} \end{cases} \quad (\text{EC.10})$$

Consider first $q \leq \frac{\mu}{2} + \frac{\sigma^2}{2\mu - \frac{p}{\alpha}}$. Setting the derivative of $L(q)$ to 0 then yields

$$q_\alpha^* = (\mu^2 - \sigma^2 + 2f(1 - \kappa)\mu\sigma) \cdot \frac{\alpha}{p} \leq \frac{\mu}{2} + \frac{\sigma^2}{2\mu - \frac{p}{\alpha}},$$

where the inequality follows from the condition $\alpha < \frac{p}{2(\mu - \sigma\sqrt{(1-\kappa)/\kappa})}$. Consider next $q \geq \frac{\mu}{2} + \frac{\sigma^2}{2\mu - \frac{p}{\alpha}}$. Since $L(q)$ is concave, its derivative is decreasing. Hence, for any $q \geq \frac{\mu}{2} + \frac{\sigma^2}{2\mu - \frac{p}{\alpha}}$, it holds that

$$L'(q) \leq L'\left(\frac{\mu}{2} + \frac{\sigma^2}{2\mu - \frac{p}{\alpha}}\right) \leq L'(q_\alpha^*) = 0,$$

concluding that the maximum of $L(q)$ is indeed achieved in $[0, \frac{\mu}{2} + \frac{\sigma^2}{2\mu - \frac{p}{\alpha}}]$. Therefore, q_α^* is optimal.

Scenario 3. Suppose that $\alpha \geq \frac{p}{2(\mu - \sigma\sqrt{(1-\kappa)/\kappa})}$. Then $L(q)$ is given in (EC.10). Consider first $q \geq \frac{\mu}{2} + \frac{\sigma^2}{2\mu - \frac{p}{\alpha}}$. Setting $L'(q_\alpha^*) = 0$ yields

$$\frac{p}{2} \left(\mu - q_\alpha^* - \frac{p}{4\alpha} - \sqrt{\left(q_\alpha^* + \frac{p}{4\alpha} - \mu \right)^2 + \sigma^2} \right) + (p - c)q_\alpha^* = 0 \implies q_\alpha^* = \mu + \sigma f(1 - \kappa) - \frac{p}{4\alpha}.$$

Note that under the condition $\alpha \geq \frac{p}{2(\mu - \sigma\sqrt{(1-\kappa)/\kappa})}$, $q_\alpha^* = \mu + \sigma f(1 - \kappa) - \frac{p}{4\alpha} \geq \frac{\mu}{2} + \frac{\sigma^2}{2\mu - \frac{p}{\alpha}}$. Consider next $q \leq \frac{\mu}{2} + \frac{\sigma^2}{2\mu - \frac{p}{\alpha}}$. Since $L(q)$ is concave, its derivative is decreasing. Hence, it holds that

$$L'(q) \geq L'\left(\frac{\mu}{2} + \frac{\sigma^2}{2\mu - \frac{p}{\alpha}}\right) \geq L'(q_\alpha^*) = 0 \quad \forall q \leq \frac{\mu}{2} + \frac{\sigma^2}{2\mu - \frac{p}{\alpha}},$$

concluding that the maximum of $L(q)$ is indeed achieved in $q \geq \frac{\mu}{2} + \frac{\sigma^2}{2\mu - \frac{p}{\alpha}}$. Hence, q_α^* is optimal.

By noting that *Scenario 1* and *Scenario 2* correspond to $\alpha < \frac{p}{2(\mu - \sigma\sqrt{(1-\kappa)/\kappa})}$ and *Scenario 3* corresponds to $\alpha \geq \frac{p}{2(\mu - \sigma\sqrt{(1-\kappa)/\kappa})}$, we then complete the proof. \square

Proof of Proposition 3.

When $p \geq \max\left\{\frac{\mu^2 + \sigma^2}{\mu^2}c, 2\alpha\mu\right\}$, it holds that

$$q_\alpha^* = \left(\mu^2 - \sigma^2 + \mu\sigma \frac{1 - 2\kappa}{\sqrt{\kappa(1 - \kappa)}} \right) \cdot \frac{\alpha}{p} = q_\alpha^* = \frac{\alpha}{c} \cdot \frac{(\mu^2 - \sigma^2 + \mu\sigma(1 - 1/x))}{(x^2 + 1)},$$

where we denote $x = \sqrt{\frac{\kappa}{1 - \kappa}}$ to have the second equality. The derivative of q_α^* with respect to x is

$$\frac{\partial q_\alpha^*}{\partial x} = \frac{\alpha}{c} \cdot \frac{4\mu\sigma - \mu\sigma x^2 - 2x(\mu^2 - \sigma^2) + \mu\sigma/x^2}{(x^2 + 1)^2}.$$

To determine the sign of $\frac{\partial q_\alpha^*}{\partial x}$, it suffices to focus on the term $4\mu\sigma - \mu\sigma x^2 - 2x(\mu^2 - \sigma^2) + \frac{\mu\sigma}{x^2}$. Note that when $x \geq 1$ (i.e., $\kappa > \frac{1}{2}$), we have

$$4\mu\sigma - \mu\sigma x^2 - 2x(\mu^2 - \sigma^2) + \frac{\mu\sigma}{x^2} \leq 5\mu\sigma - \mu\sigma x^2 - 2x(\mu^2 - \sigma^2) = -\mu\sigma \left(x + \frac{\mu^2 - \sigma^2}{\mu\sigma} \right)^2 + 5\mu\sigma - \frac{(\mu^2 - \sigma^2)}{\mu\sigma}.$$

Since $\mu\sigma > 0$, there must exist some $x_1 \geq 1$ such that when $x > x_1$, it holds that

$$4\mu\sigma - \mu\sigma x^2 - 2x(\mu^2 - \sigma^2) + \frac{\mu\sigma}{x^2} \leq -\mu\sigma \left(x + \frac{\mu^2 - \sigma^2}{\mu\sigma} \right)^2 + 5\mu\sigma - \frac{(\mu^2 - \sigma^2)}{\mu\sigma} < 0.$$

As x is strictly increasing in $(\kappa$ and) p , it is clear that q_α^* is strictly decreasing in p when

$$p > p_\alpha^* = \max \left\{ \frac{\mu^2 + \sigma^2}{\mu^2} c, 2\alpha\mu, c(x_1^2 + 1) \right\},$$

completing the proof. \square

Proof of Proposition 4.

The formula of q_α^* characterized in Theorem 2 can be rewritten as

$$q_\alpha^* = \begin{cases} \mu + \sigma f(1 - \kappa) - \frac{p}{4\alpha} & \sigma < \left(\mu - \frac{p}{2\alpha} \right) \sqrt{\frac{\kappa}{1 - \kappa}} \\ (\mu^2 - \sigma^2 + 2\mu\sigma f(1 - \kappa)) \cdot \frac{\alpha}{p} & \left(\mu - \frac{p}{2\alpha} \right) \sqrt{\frac{\kappa}{1 - \kappa}} \leq \sigma \leq \mu \sqrt{\frac{\kappa}{1 - \kappa}} \\ 0 & \sigma > \mu \sqrt{\frac{\kappa}{1 - \kappa}}. \end{cases}$$

The derivative of q_α^* with respect to σ is

$$\frac{\partial q_\alpha^*}{\partial \sigma} = \begin{cases} f(1 - \kappa) & \sigma < \left(\mu - \frac{p}{2\alpha} \right) \sqrt{\frac{\kappa}{1 - \kappa}} \\ (-2\sigma + 2\mu f(1 - \kappa)) \cdot \frac{\alpha}{p} & \left(\mu - \frac{p}{2\alpha} \right) \sqrt{\frac{\kappa}{1 - \kappa}} \leq \sigma \leq \mu \sqrt{\frac{\kappa}{1 - \kappa}}, \end{cases}$$

which is decreasing in σ . When $\kappa \geq \frac{1}{2}$,

$$\frac{\partial q_\alpha^*}{\partial \sigma} = f(1 - \kappa) \geq 0 \quad \forall \sigma \in \left[0, \left(\mu - \frac{p}{2\alpha} \right) \sqrt{\frac{\kappa}{1 - \kappa}} \right].$$

We proceed by dividing the argument into two cases. On the one hand, if $\alpha \geq \frac{p-c}{\mu}$, we have

$$\mu f(1 - \kappa) = \frac{\mu}{2} \left(\sqrt{\frac{\kappa}{1 - \kappa}} - \sqrt{\frac{1 - \kappa}{\kappa}} \right) \leq \left(\mu - \frac{p}{2\alpha} \right) \sqrt{\frac{\kappa}{1 - \kappa}},$$

which indicates that

$$\frac{\partial q_\alpha^*}{\partial \sigma} = (-2\sigma + 2\mu f(1 - \kappa)) \cdot \frac{\alpha}{p} \leq 0 \quad \forall \sigma \in \left[\left(\mu - \frac{p}{2\alpha} \right) \sqrt{\frac{\kappa}{1 - \kappa}}, \mu \sqrt{\frac{\kappa}{1 - \kappa}} \right].$$

On the other hand, if $\alpha < \frac{p-c}{\mu}$, it holds that

$$\mu f(1 - \kappa) > \left(\mu - \frac{p}{2\alpha} \right) \sqrt{\frac{\kappa}{1 - \kappa}},$$

which implies that

$$\frac{\partial q_\alpha^*}{\partial \sigma} \geq 0 \quad \forall \sigma \in \left[\left(\mu - \frac{p}{2\alpha} \right) \sqrt{\frac{\kappa}{1 - \kappa}}, \mu f(1 - \kappa) \right] \quad \text{and} \quad \frac{\partial q_\alpha^*}{\partial \sigma} \leq 0 \quad \forall \sigma \in \left[\mu f(1 - \kappa), \mu \sqrt{\frac{\kappa}{1 - \kappa}} \right].$$

Combining the two cases together then yields the desired result. \square

Proof of Lemma 1.

We proceed with the proof by dividing the argument into two scenarios.

Scenario 1.1. If $\frac{\hat{\mu}}{\hat{\sigma}} \geq \frac{\mu}{\sigma}$, by theorem 2.1 in [Gelbrich\(1990\)](#), for any $G \in \mathcal{A}_N$, it holds that $d(D, G) \geq (\hat{\mu} - \mu)^2 + (\hat{\sigma} - \sigma)^2$, and hence $d(D, \mathcal{A}_N) \geq (\hat{\mu} - \mu)^2 + (\hat{\sigma} - \sigma)^2$. In the following, we show that the inequality is tight. Consider the transformed random variable $\tilde{w} = \frac{\hat{\sigma}}{\sigma} \tilde{u} + \hat{\mu} - \frac{\hat{\sigma}\mu}{\sigma} \sim G^\dagger$ where $\tilde{u} \sim D$. Since the \tilde{w} is a linear transformation of \tilde{u} , we have $d(D, G^\dagger) = (\hat{\mu} - \mu)^2 + (\hat{\sigma} - \sigma)^2$ ([Dowson and Landau 1982](#)). Moreover, we can verify $\mathbb{E}_{G^\dagger}[\tilde{w}] = \hat{\mu}$, $\mathbb{E}_{G^\dagger}[\tilde{w}^2] = \hat{\mu}^2 + \hat{\sigma}^2$, and $G^\dagger\{\tilde{w} \in [0, +\infty)\} = 1$ (since $\frac{\hat{\mu}}{\hat{\sigma}} \geq \frac{\mu}{\sigma}$). Hence, $G^\dagger \in \mathcal{A}_N$, concluding $d(D, \mathcal{A}_N) = (\hat{\mu} - \mu)^2 + (\hat{\sigma} - \sigma)^2$.

Scenario 1.2. If $\frac{\hat{\mu}}{\hat{\sigma}} < \frac{\mu}{\sigma}$, we construct an upper bound for $d(D, \mathcal{A}_N)$. Consider the transformed random variable $\tilde{w} = k^\dagger \max\{0, \tilde{u} - t^\dagger\} \sim G^\dagger$ with $\tilde{u} \sim D$, where $k^\dagger > 0$ and $t^\dagger \geq 0$ satisfy

$$\int_{t^\dagger}^{+\infty} k^\dagger(u - t^\dagger)dD(u) = \hat{\mu} \quad \text{and} \quad \int_{t^\dagger}^{+\infty} k^{\dagger 2}(u - t^\dagger)^2 dD(u) = \hat{\mu}^2 + \hat{\sigma}^2. \quad (\text{EC.11})$$

In the following, we first show that there exists (k^\dagger, t^\dagger) satisfying [\(EC.11\)](#). Eliminating the variable k in [\(EC.11\)](#), it suffices to check whether there exists $t \geq 0$ such that

$$\hat{\mu}^2 \int_t^{+\infty} (u - t)^2 dD(u) - (\hat{\mu}^2 + \hat{\sigma}^2) \left(\int_t^{+\infty} (u - t) dD(u) \right)^2 = 0.$$

Define $h(t) = \hat{\mu}^2 \int_t^{+\infty} (u - t)^2 dD(u) - (\hat{\mu}^2 + \hat{\sigma}^2) \left(\int_t^{+\infty} (u - t) dD(u) \right)^2$. Setting the derivative $h'(t) = 2 \int_t^{+\infty} (u - t) dD(u) ((\hat{\mu}^2 + \hat{\sigma}^2)(1 - D(t)) - \hat{\mu}^2)$ to 0 then yields $t^\circ = D^{-1}\left(\frac{\hat{\sigma}^2}{\hat{\mu}^2 + \hat{\sigma}^2}\right)$. It is straightforward to see that $h(0) = \hat{\mu}^2(\mu^2 + \sigma^2) - \mu^2(\hat{\mu}^2 + \hat{\sigma}^2) < 0$ and $\lim_{t \rightarrow +\infty} h(t) = 0$, which implies that $h(t^\circ) > \lim_{t \rightarrow +\infty} h(t) = 0$ since $h(t)$ is decreasing in $(t^\circ, +\infty)$. Therefore, there must exist some $t^\dagger \in [0, t^\circ]$ such that $h(t^\dagger) = 0$, verifying the feasibility of [\(EC.11\)](#). This indicates that $\mathbb{E}_{G^\dagger}[\tilde{w}] = \hat{\mu}$ and $\mathbb{E}_{G^\dagger}[\tilde{w}^2] = \hat{\mu}^2 + \hat{\sigma}^2$. Additionally, since $G^\dagger\{\tilde{w} \in [0, +\infty)\} = 1$, it is immediate to see that $G^\dagger \in \mathcal{A}_N$. Subsequently, we identify the upper bounds for k^\dagger and t^\dagger . Note that for any $t \in [0, t^\circ]$, we have

$$h''(t) = 2\hat{\mu}^2(1 - D(t)) - 2d(t)(\hat{\mu}^2 + \hat{\sigma}^2) \int_t^{+\infty} (u - t) dD(u) - 2(1 - D(t))^2(\hat{\mu}^2 + \hat{\sigma}^2) \leq 0,$$

where $d(t)$ is the density function of the distribution D . Hence, it holds that

$$\frac{h(t^\dagger) - h(0)}{t^\dagger - 0} \geq \frac{h(t^\circ) - h(t^\dagger)}{t^\circ - t^\dagger} \implies t^\dagger \leq \frac{-h(0)t^\circ}{h(t^\circ) - h(0)}.$$

Note that as $N \rightarrow +\infty$, $h(0) \rightarrow 0$ and hence $t^\dagger \rightarrow 0$. This implies that for sufficiently large N , $t^\dagger \leq \mu$. Since $\int_{t^\dagger}^{+\infty} (u - t^\dagger) dD(u) = \mu - \int_0^{t^\dagger} u dD(u) - t^\dagger(1 - D(t^\dagger)) \geq \mu - t^\dagger(1 - D(0))$, we then have

$$\frac{\hat{\mu}}{k^\dagger} \geq \mu - t^\dagger(1 - D(0)) \implies k^\dagger \leq \frac{\hat{\mu}}{\mu - t^\dagger(1 - D(0))} \leq \frac{\hat{\mu}}{\mu + \frac{h(0)t^\circ}{h(t^\circ) - h(0)}} \leq \frac{\hat{\mu}}{\mu + \frac{h(0)}{h'(0)}},$$

where the last inequality follows from the fact that $\frac{h(t^\diamond)-h(0)}{t^\diamond} \leq h'(0)$ since $h''(t) \leq 0$ for any $t \in [0, t^\diamond]$. Plugging the expressions of $h(0)$ and $h'(0)$, it is then immediate to see that

$$k^\dagger \leq \frac{\hat{\mu}}{\mu + \frac{h(0)}{h'(0)}} = \frac{2\mu^2\hat{\sigma}^2}{\mu^2\hat{\sigma}^2 + \hat{\mu}^2\sigma^2}.$$

For the optimal-transport cost, note that the objective of the Kantorovich formulation as defined in (3) is no larger than that of the Monge formulation (Villani 2009), *i.e.*,

$$d(D, G^\dagger) \leq \inf_{\psi: T_\psi[D]=G^\dagger} \int_0^{+\infty} (u - \psi(u))^2 dD(u). \quad (\text{EC.12})$$

By the definition of G^\dagger , the function $\psi^\dagger(u) = k^\dagger \cdot \max\{u - t^\dagger, 0\}$ is feasible to (EC.12). Hence,

$$\begin{aligned} d(D, \mathcal{A}_N) &\leq d(D, G^\dagger) \leq \int_0^t u^2 dD(u) + \int_t^{+\infty} (k^\dagger(u - t^\dagger) - u)^2 dD(u) \\ &= \mu^2 + \sigma^2 + \hat{\mu}^2 + \hat{\sigma}^2 - 2k^\dagger \int_{t^\dagger}^{+\infty} (u - t^\dagger) u dD(u) \\ &\leq \mu^2 + \sigma^2 + \hat{\mu}^2 + \hat{\sigma}^2 - \frac{2}{k^\dagger} k^{\dagger 2} \int_t^{+\infty} (u - t)^2 dD(u) \\ &\leq \mu^2 + \sigma^2 + \hat{\mu}^2 + \hat{\sigma}^2 - \frac{(\mu^2\hat{\sigma}^2 + \hat{\mu}^2\sigma^2)(\hat{\mu}^2 + \hat{\sigma}^2)}{\mu^2\hat{\sigma}^2} \\ &= (\mu - \hat{\mu})^2 + (\sigma - \hat{\sigma})^2 + 2\mu\hat{\mu} + 2\sigma\hat{\sigma} - \frac{(\mu^2\hat{\sigma}^2 + \hat{\mu}^2\sigma^2)(\hat{\mu}^2 + \hat{\sigma}^2)}{\mu^2\hat{\sigma}^2}, \end{aligned}$$

where the third line follows from $u \geq u - t^\dagger$ and the fourth line follows from $k^\dagger \leq \frac{2\mu^2\hat{\sigma}^2}{\mu^2\hat{\sigma}^2 + \hat{\mu}^2\sigma^2}$. Besides,

$$\begin{aligned} 2\mu\hat{\mu} + 2\sigma\hat{\sigma} - \frac{(\mu^2\hat{\sigma}^2 + \hat{\mu}^2\sigma^2)(\hat{\mu}^2 + \hat{\sigma}^2)}{\mu^2\hat{\sigma}^2} &= \frac{\hat{\mu}(\mu^2\hat{\sigma}^2 - \hat{\mu}^2\sigma^2)}{\mu\hat{\sigma}^2} + \frac{\sigma(\mu\hat{\sigma} - \hat{\mu}\sigma)}{\mu} + \frac{\hat{\sigma}(\hat{\mu}\sigma - \mu\hat{\sigma})}{\hat{\mu}} \\ &\leq \frac{\mu^2\hat{\sigma}^2 - \hat{\mu}^2\sigma^2}{\sigma\hat{\sigma}} + \frac{\sigma(\mu\hat{\sigma} - \hat{\mu}\sigma)}{\mu} + \frac{\sigma(\hat{\mu}\sigma - \mu\hat{\sigma})}{\mu} \\ &= \frac{\mu^2\hat{\sigma}^2 - \hat{\mu}^2\sigma^2}{\sigma\hat{\sigma}}, \end{aligned}$$

where the inequality is due to $\frac{\hat{\mu}}{\hat{\sigma}} < \frac{\mu}{\sigma}$. Hence, we have $d(D, \mathcal{A}_N) \leq (\mu - \hat{\mu})^2 + (\sigma - \hat{\sigma})^2 + \frac{\mu^2\hat{\sigma}^2 - \hat{\mu}^2\sigma^2}{\sigma\hat{\sigma}}$.

Combining the results in these two scenarios then completes the proof. \square

Proof of Proposition 5.

We proceed in two steps. In the first step, we derive the concentration inequalities of sample mean and variance, respectively. In the second step, we establish the concentration inequality for the mean-variance ambiguity set.

Step 1. Note that for any $x \in \mathbb{R}$,

$$\mathbb{E}_{D^N} \left[\exp \left(\frac{x}{N} \sum_{i=1}^N (\hat{v}_i - \mu) \right) \right] = \prod_{i=1}^N \mathbb{E}_D \left[\exp \left(\frac{x}{N} (\hat{v}_i - \mu) \right) \right] \leq \mathbb{E}_D \left[\exp \left(-\frac{x^2 \nu^2}{2N} \right) \right],$$

where the expectation is taken with respect to the random sample \hat{v}_i , the equality follows from the fact that $\hat{v}_1, \dots, \hat{v}_N$ are i.i.d, and the inequality follows from the fact that D is sub-Gaussian with variance proxy ν^2 . Hence, $\hat{\mu} - \mu = \frac{1}{N} \sum_{i=1}^N (\hat{v}_i - \mu)$ is sub-Gaussian with variance proxy $\frac{\nu^2}{N}$. According to the concentration inequality of sample mean for sub-Gaussian distribution characterized in lemma 1.3 of [Rigollet and Jan-Christian \(2023\)](#), with probability at least $1 - \eta$, we have

$$|\hat{\mu} - \mu| \leq \nu \sqrt{\frac{2 \log(2/\eta)}{N}}. \quad (\text{EC.13})$$

By theorem 6.5 in [Wainwright \(2019\)](#), for any $\delta > 0$ there exist some constants C_1, C_2 and C_3 such that with probability at least $1 - \eta$, it holds that

$$|\hat{\mu}^2 + \hat{\sigma}^2 - \mu^2 - \sigma^2| \leq \nu^2 C_1 \left(\frac{1}{N} + \sqrt{\frac{1}{N}} \right) + \nu^2 \max \left\{ \sqrt{\frac{\log(C_2/\eta)}{C_3 N}}, \frac{\log(C_2/\eta)}{C_3 N} \right\}.$$

Since $\frac{1}{N} \leq \frac{1}{\sqrt{N}}$ and $\sqrt{x} \leq 1 + x$ for any $x > 0$, with probability at least $1 - \eta$, we further have

$$|\hat{\mu}^2 + \hat{\sigma}^2 - \mu^2 - \sigma^2| \leq \frac{\nu^2}{\sqrt{N}} \left(2C_1 + 1 + \frac{\log(C_2/\eta)}{C_3} \right). \quad (\text{EC.14})$$

Note that

$$|\hat{\sigma}^2 - \sigma^2| \leq |\hat{\mu}^2 + \hat{\sigma}^2 - \mu^2 - \sigma^2| + |\hat{\mu}^2 - \mu^2| \leq |\hat{\mu}^2 + \hat{\sigma}^2 - \mu^2 - \sigma^2| + (\hat{\mu} - \mu)^2 + 2\mu|\hat{\mu} - \mu|, \quad (\text{EC.15})$$

where the first inequality follows from the triangle inequality, and the second inequality follows from the fact that $|\hat{\mu}^2 - \mu^2| = |(\hat{\mu} - \mu)^2 + 2\mu(\hat{\mu} - \mu)| \leq (\hat{\mu} - \mu)^2 + 2\mu|\hat{\mu} - \mu|$. Hence, it holds that

$$|\hat{\sigma} - \sigma| = \frac{|\hat{\sigma}^2 - \sigma^2|}{\hat{\sigma} + \sigma} \leq \frac{|\hat{\sigma}^2 - \sigma^2|}{\sigma} \leq \frac{|\hat{\mu}^2 + \hat{\sigma}^2 - \mu^2 - \sigma^2| + (\hat{\mu} - \mu)^2 + 2\mu|\hat{\mu} - \mu|}{\sigma}.$$

Applying the reverse union bound to inequalities [\(EC.13\)](#) and [\(EC.14\)](#), we then have with probability at least $1 - \eta$,

$$\begin{aligned} |\hat{\sigma} - \sigma| &\leq \frac{1}{\sigma} \left(\frac{\nu^2}{\sqrt{N}} \left(2C_1 + 1 + \frac{\log(2C_2/\eta)}{C_3} \right) + 2\nu^2 \frac{\log(4/\eta)}{N} + 2\mu\nu \sqrt{\frac{2 \log(4/\eta)}{N}} \right) \\ &\leq \frac{1}{\sigma} \left(\frac{\nu^2}{\sqrt{N}} \left(2C_1 + 1 + \frac{\log(2C_2/\eta)}{C_3} \right) + 2\nu^2 \frac{\log(4/\eta)}{\sqrt{N}} + 2\mu\nu \frac{2 \log(4/\eta) + 1}{\sqrt{N}} \right) \\ &= \frac{\xi_1 + \xi_2 \log(1/\eta)}{\sqrt{N}}, \end{aligned} \quad (\text{EC.16})$$

where $\xi_1 = \frac{\nu}{\sigma} \left(\nu \left(2C_1 + 1 + \frac{\log(2C_2)}{C_3} \right) + 2(\nu + 2\mu) \log(4) + 2\mu \right)$ and $\xi_2 = \frac{\nu}{\sigma} \left(\frac{\nu}{C_3} + 2\nu + 4\mu \right)$. Here, the second inequality follows from the fact that $\frac{1}{N} \leq \frac{1}{\sqrt{N}}$ and $\sqrt{x} \leq 1 + x$ for any $x \geq 0$.

Step 2. To derive the concentration property for the mean-variance ambiguity, we divide the argument into two cases based on the expression of $d(D, \mathcal{A}_N)$.

Scenario 1. If $\frac{\hat{\mu}}{\hat{\sigma}} \geq \frac{\mu}{\sigma}$, according to Lemma 1, we have $d(D, \mathcal{A}_N) = (\hat{\mu} - \mu)^2 + (\hat{\sigma} - \sigma)^2$. By the concentration inequalities for sample mean and sample variance derived in equations (EC.13) and (EC.16), it is then immediate to see that with probability at least $1 - \eta$, it holds that

$$\begin{aligned} (\hat{\mu} - \mu)^2 + (\hat{\sigma} - \sigma)^2 &\leq \nu^2 \frac{4 \log(2/\eta)}{N} + \frac{(\xi_1 + \xi_2 \log(1/\eta))^2}{N} \\ &\leq \frac{\xi_1^2 + 2 \log(4) \nu^2 + (2\xi_1 \xi_2 + 2\nu^2) \log(1/\eta) + \xi_2^2 (\log(1/\eta))^2}{\sqrt{N}}. \end{aligned} \quad (\text{EC.17})$$

Let $\zeta_1 = \xi_1^2 + 2 \log(4) \nu^2$ and $\zeta_2 = 2\xi_1 \xi_2 + 2\nu^2$. When $\zeta_2^2 \geq 4\zeta_1 \xi_2^2$, we have $\zeta_1 + \zeta_2 \log(1/\eta) + \xi_2^2 (\log(1/\eta))^2 \leq (\frac{\zeta_1}{\xi_2} + \xi_2 \log(1/\eta))^2$. Setting $c_1 = \frac{\xi_1 \xi_2 + \nu^2}{\xi_2}$ and $c_2 = \xi_2$ then yields the desired result. When $\zeta_2^2 < 4\zeta_1 \xi_2^2$, we have $\zeta_1 + \zeta_2 \log(1/\eta) + \xi_2^2 (\log(1/\eta))^2 \leq (\sqrt{\zeta_1} + \xi_2 \log(1/\eta))^2$. Setting $c_1 = \sqrt{\zeta_1}$ and $c_2 = \xi_2$ then yields the desired result.

Scenario 2. If $\frac{\hat{\mu}}{\hat{\sigma}} < \frac{\mu}{\sigma}$, it holds that

$$\begin{aligned} \frac{\mu^2 \hat{\sigma}^2 - \hat{\mu}^2 \sigma^2}{\sigma \hat{\sigma}} &\leq \frac{\mu |\hat{\sigma}^2 - \sigma^2| + \sigma^2 |\hat{\mu} - \mu|}{\sigma \hat{\sigma}} \\ &\leq \frac{\mu (|\hat{\mu}^2 + \hat{\sigma}^2 - \mu^2 - \sigma^2| + (\hat{\mu} - \mu)^2 + 2\mu |\hat{\mu} - \mu|) + \sigma^2 |\hat{\mu} - \mu|}{\sigma \hat{\sigma}}, \end{aligned}$$

where the second inequality follows from inequality (EC.15). According to inequalities (EC.13) and (EC.14), with probability at least $1 - \eta$, it holds that

$$\begin{aligned} &\mu (|\hat{\mu}^2 + \hat{\sigma}^2 - \mu^2 - \sigma^2| + (\hat{\mu} - \mu)^2 + 2\mu |\hat{\mu} - \mu|) + \sigma^2 |\hat{\mu} - \mu| \\ &\leq \frac{\nu^2 \mu}{\sqrt{N}} \left(2C_1 + 1 + \frac{\log(2C_2/\eta)}{C_3} \right) + (2\mu^2 + \sigma^2) \nu \sqrt{\frac{2 \log(4/\eta)}{N}} + \mu \nu^2 \frac{2 \log(4/\eta)}{N} \\ &\leq \frac{\nu^2 \mu}{\sqrt{N}} \left(2C_1 + 1 + \frac{\log(2C_2/\eta)}{C_3} \right) + (2\mu^2 + \sigma^2) \nu \frac{2 \log(4/\eta) + 1}{\sqrt{N}} + \mu \nu^2 \frac{2 \log(4/\eta)}{\sqrt{N}} \\ &= \frac{\delta_1 + \delta_2 \log(1/\eta)}{\sqrt{N}}, \end{aligned}$$

where $\delta_1 = \nu^2 \mu (2C_1 + 1 + \frac{\log(2C_2)}{C_3}) + 2 \log(4) (2\mu^2 + \sigma^2 + \nu \mu) \nu + (2\mu^2 + \sigma^2) \nu$ and $\delta_2 = \frac{\nu^2 \mu}{C_3} + 2(2\mu^2 + \sigma^2) \nu + 2\mu \nu^2$. When N is sufficiently large, $\sigma > \frac{\xi_1 + \xi_2 \log(1/\eta)}{\sqrt{N}}$, and then (EC.16) implies that $\hat{\sigma} \leq \sigma - \frac{\xi_1 + \xi_2 \log(1/\eta)}{\sqrt{N}}$ with probability at least $1 - \eta$. Hence, we have

$$\frac{\mu^2 \hat{\sigma}^2 - \hat{\mu}^2 \sigma^2}{\sigma \hat{\sigma}} \leq \frac{\frac{\delta_1 + \delta_2 \log(1/\eta)}{\sqrt{N}}}{\sigma (\sigma - \frac{\xi_1 + \xi_2 \log(1/\eta)}{\sqrt{N}})} = \frac{\delta_1 + \delta_2 \log(1/\eta)}{\sqrt{N} \sigma^2 - \sigma (\xi_1 + \xi_2 \log(1/\eta))},$$

holds with probability at least $1 - \eta$. Note that for sufficiently large N , we have $\sqrt{N} \sigma^2 > \delta_1 + \delta_2 \log(1/\eta) + \sigma (\xi_1 + \xi_2 \log(1/\eta))$, which implies that

$$\frac{\delta_1 + \delta_2 \log(1/\eta)}{\sqrt{N} \sigma^2 - \sigma (\xi_1 + \xi_2 \log(1/\eta))} < \frac{\delta_1 + \delta_2 \log(1/\eta) + \sigma (\xi_1 + \xi_2 \log(1/\eta))}{\sqrt{N} \sigma^2}.$$

The above inequality, together with (EC.17), implies that with probability at least $1 - \eta$, for sufficiently large N , it holds that

$$\begin{aligned} d(D, \mathcal{A}_N) &\leq (\hat{\mu} - \mu)^2 + (\hat{\sigma} - \sigma)^2 + \frac{\mu^2 \hat{\sigma}^2 - \hat{\mu}^2 \sigma^2}{\sigma \hat{\sigma}} \\ &\leq \frac{(\xi_1^2 + 2 \log(2) \nu^2) \sigma^2 + \delta_1 + \sigma \xi_1 + (2 \xi_1 \xi_2 \sigma^2 + 2 \nu^2 \sigma^2 + \delta_2 + \sigma \xi_2) \log(1/\eta) + \xi_2^2 \sigma^2 (\log(1/\eta))^2}{\sqrt{N} \sigma^2}. \end{aligned}$$

Using a similar argument as in *Scenario 1*, we can also show that with probability at least $1 - \eta$, for sufficiently large N , $d(D, \mathcal{A}_N) \leq \frac{(c_1 + c_2 \log(1/\eta))^2}{\sqrt{N}}$ where c_1 and c_2 are some constants that only depend on μ , σ and ν . \square

Proof of Theorem 3.

We proceed in three steps. In the first step, leveraging the equivalence between the following constrained problem

$$\Upsilon_\varepsilon^* = \max_{q \geq 0} \min_{d(F, \mathcal{A}) \leq \varepsilon} \mathbb{E}_F[\pi(q, \tilde{u})] \quad (\text{EC.18})$$

and **MISSPECIFICATION** (as shown in Lemma EC.2), we characterize the relationship between ε and α . In the second step, we translate the finite-sample performance guarantee of (EC.18) characterized in Proposition 5 as the performance guarantee of **MISSPECIFICATION**.

Step 1. Given N and $\varepsilon_N + d(F, D)$, consider the constrained problem (EC.18) with $\mathcal{A} = \mathcal{A}_N$ and $\varepsilon = \varepsilon_N + d(F, D)$. Suppose that α_N is an index of misspecification aversion such that **MISSPECIFICATION** with $\mathcal{A} = \mathcal{A}_N$ and $\alpha = \alpha_N$ has the same optimal solution as that of the corresponding constrained problem (EC.18). Denote by $\Pi_{\alpha_N}^*$ the optimal value of **MISSPECIFICATION** with $\alpha = \alpha_N$. By Lemma EC.2, we have

$$\Upsilon_{\varepsilon_N + d(F, D)}^* = \max_{\alpha \geq 0} \{\Pi_\alpha^* - (\varepsilon_N + d(F, D))\alpha\} = \Pi_{\alpha_N}^* - (\varepsilon_N + d(F, D))\alpha_N.$$

In the following, we characterize the expression of α_N . Plugging the expression of the optimal order quantity q_α^* into the worst-case transformed expectation characterized in Proposition 2, we have

$$\Pi_\alpha^* - (\varepsilon_N + d(F, D))\alpha = \begin{cases} k\alpha \hat{v}^{*2} - (\varepsilon_N + d(F, D))\alpha & \alpha < \frac{p}{2\hat{v}^*} \\ (p - c)\hat{v}^* - \frac{p(p - c)}{4\alpha} - (\varepsilon_N + d(F, D))\alpha & \alpha \geq \frac{p}{2\hat{v}^*}, \end{cases}$$

where

$$\hat{v}^* = \hat{\mu} - \hat{\sigma} \sqrt{\frac{1 - \kappa}{\kappa}}.$$

Note that $\Pi_\alpha^* - (\varepsilon_N + d(F, D))\alpha$ is concave in α . If $\varepsilon_N + d(F, D) \geq k\hat{v}^{*2}$, then $\Pi_\alpha^* - (\varepsilon_N + d(F, D))\alpha$ is decreasing in α , and hence $\max_{\alpha \geq 0} \{\Pi_\alpha^* - (\varepsilon_N + d(F, D))\alpha\} = 0$ with $\alpha_N = 0$. If $\varepsilon_N + d(F, D) < k\hat{v}^{*2}$, then by the first-order optimality condition, the maximum is attained at

$$\alpha_N = \frac{\sqrt{p(p - c)}}{2\sqrt{\varepsilon_N + d(F, D)}}$$

and

$$\max_{\alpha \geq 0} \{ \Pi_{\alpha}^* - (\varepsilon_N + d(F, D))\alpha \} = \Pi_{\alpha_N}^* - \frac{1}{2} \sqrt{p(p-c)(\varepsilon_N + d(F, D))}.$$

To summarize the second step, we have obtained

$$\alpha_N = \begin{cases} \frac{\sqrt{p(p-c)}}{2\sqrt{\varepsilon_N + d(F, D)}} & \varepsilon_N + d(F, D) < \kappa \hat{v}^{*2} \\ 0 & \varepsilon_N + d(F, D) \geq \kappa \hat{v}^{*2}, \end{cases}$$

and

$$\Upsilon_{\varepsilon_N + d(F, D)}^* = \left(\Pi_{\alpha_N}^* - \frac{1}{2} \sqrt{p(p-c)(\varepsilon_N + d(F, D))} \right)^+.$$

Step 2. Denote by $q_{\alpha_N}^*$ the optimal solution to **MISSPECIFICATION** with $\alpha = \alpha_N$, which, by Lemma EC.2, is also the optimal solution to the constrained problem (EC.18). Note that the empirical distribution $\hat{G} = \frac{1}{N} \sum_{i=1}^N \hat{v}_i$ satisfies $\mathbb{E}_{\hat{G}}[\hat{v}] = \hat{\mu}$ and $\mathbb{E}_{\hat{G}}[\hat{v}^2] = \hat{\mu}^2 + \hat{\sigma}^2$. Hence, $\hat{G} \in \mathcal{A}_N$. For any F such that $d(F, \mathcal{A}_N) \leq \varepsilon_N + d(F, D)$, we have $\mathbb{E}_F[\pi(q_{\alpha_N}^*, \tilde{v})] \geq \Upsilon_{\varepsilon_N + d(F, D)}^*$. Therefore,

$$\begin{aligned} \mathbb{P}_{D^N} \{ \mathbb{E}_F[\pi(q_{\alpha_N}^*, \tilde{v})] \geq \Upsilon_{\varepsilon_N + d(F, D)}^* \} &\geq \mathbb{P}_{D^N} \{ d(F, \mathcal{A}_N) \leq \varepsilon_N + d(F, D) \} \\ &\geq \mathbb{P}_{D^N} \{ d(F, \hat{G}) \leq \varepsilon_N + d(F, D) \}, \end{aligned} \quad (\text{EC.19})$$

where the second inequality follows by noting that

$$d(D, \mathcal{A}_N) \leq \varepsilon_N \implies d(F, \mathcal{A}_N) \leq d(D, \mathcal{A}_N) + d(F, D) \leq \varepsilon_N + d(F, D).$$

Combining (EC.19) and the concentration inequality derived in Proposition 5, we have

$$\mathbb{P}_{D^N} \{ \mathbb{E}_F[\pi(q_{\alpha_N}^*, \tilde{u})] \geq \Upsilon_{\varepsilon_N + d(F, D)}^* \} \geq 1 - \eta.$$

Plugging the expressions of α_N and $\Upsilon_{\varepsilon_N + d(F, D)}^*$ characterized in the first step, we can obtain the desired result. \square

Proof of Theorem 4.

For ease of notation, define $\mathcal{G} = \{G \in \mathcal{P}_M \mid \mathbb{E}_G[\tilde{v}_i] = \mu_i \ \forall i \in [M]\}$ and $\mathcal{C}_i = \{G \in \mathcal{P} \mid \mathbb{E}_G[\tilde{v}_i] = \mu_i\}$ for $i \in [M]$. Introducing the dual variable $\lambda \geq 0$ to the sum-of-variance constraint in the ambiguity set, then the **MULTIPLE** model can be equivalently reformulated as

$$\max_{\lambda \geq 0} \left\{ -\lambda K + \max_{\mathbf{q} \geq 0} \min_{F \in \mathcal{P}_M, G \in \mathcal{G}} \mathbb{E}_F \left[\sum_{i \in [M]} \pi(q_i, \tilde{u}_i) \right] + \lambda \cdot \mathbb{E}_G \left[\sum_{i \in [M]} \tilde{v}_i^2 \right] + \alpha \cdot d(F, G) \right\},$$

which, by noting that \mathcal{G} is decomposable with respect to multiple products, further reduces to

$$\max_{\lambda \geq 0} \left\{ -\lambda K + \sum_{i \in [M]} \max_{q_i \geq 0} \min_{F_i \in \mathcal{P}, G_i \in \mathcal{C}_i} \{ \mathbb{E}_{F_i}[\pi(q_i, \tilde{u}_i)] + \lambda \cdot \mathbb{E}_{G_i}[\tilde{v}_i^2] + \alpha \cdot d(F_i, G_i) \} \right\}. \quad (\text{EC.20})$$

In the remainder of the proof, we solve for the optimal λ^* and \mathbf{q}_α^* of problem (EC.20). Invoking the interchangeability principle characterized in Lemma EC.3, then problem (EC.20) becomes

$$\max_{\lambda \geq 0} \left\{ -\lambda K + \sum_{i \in [M]} \max_{q_i \geq 0} \min_{G_i \in \mathcal{C}_i} \mathbb{E}_{G_i} \left[\min_{u_i \geq 0} \{ \pi(q_i, u_i) + \lambda \cdot \tilde{v}_i^2 + \alpha \cdot (u_i - \tilde{v}_i)^2 \} \right] \right\},$$

which, by defining $F_i(\lambda, q_i, v_i) = \lambda \cdot v_i^2 + \min_{u_i \geq 0} \{ \pi(q_i, u_i) + \alpha \cdot (u_i - v_i)^2 \}$ (see Lemma EC.4 for its closed-form expression) for each $i \in [M]$ and $u_i \geq 0$, can be equivalently written as

$$\max_{\lambda \geq 0} \left\{ -\lambda K + \sum_{i \in [M]} \max_{q_i \geq 0} \min_{G_i \in \mathcal{C}_i} \mathbb{E}_{G_i} [F_i(\lambda, q_i, \tilde{v}_i)] \right\}. \quad (\text{EC.21})$$

In the following, our remaining proof proceeds in three steps: deriving the expression for $L_i(q_i) = \min_{G_i \in \mathcal{C}_i} \mathbb{E}_{G_i} [F_i(\lambda, q_i, \tilde{v}_i)]$ (*Step 1*), optimizing over q_i to solve $\max_{q_i \geq 0} L_i(q_i)$ for each $i \in [M]$ (*Step 2*), and finally, optimizing over $\lambda \geq 0$ (*Step 3*). Note that given $\lambda \geq 0$, we solve the inner maximization of problem (EC.21) over $q_i \geq 0$ for each $i \in [M]$ in *Step 1* and *Step 2*.

Step 1. We drop the subscript ‘ i ’ to avoid clutter. Given $q \geq 0$, $L(q)$ is a classical moment problem as follows

$$\begin{aligned} & \min_G \int_{\mathbb{R}_+} F(\lambda, q, v) dG(v) \\ & \text{s.t.} \int_{\mathbb{R}_+} v dG(v) = \mu \quad \cdots s_\alpha \\ & \int_{\mathbb{R}_+} dG(v) = 1 \quad \cdots t_\alpha \\ & G \in \mathcal{M}_+, \end{aligned} \quad (\text{PRIMAL})$$

whose dual is given by

$$\begin{aligned} & \max_{s_\alpha, t_\alpha} \mu s_\alpha - t_\alpha \\ & \text{s.t.} \quad v s_\alpha - t_\alpha \leq F(\lambda, q, v) \quad \forall v \geq 0 \\ & s_\alpha \in \mathbb{R}, t_\alpha \in \mathbb{R}. \end{aligned} \quad (\text{DUAL})$$

We next derive the expression of $L(q)$ by constructing a pair of primal and dual feasible solutions that attain the same objective value (that is, strong duality holds between **PRIMAL** and **DUAL**). The argument breaks into nine scenarios based on the value of q .

Scenario 1.1. When $q \leq \frac{p}{4\alpha}$ and $\frac{\alpha\lambda\mu^2}{p(\lambda+\alpha)} \leq q \leq \frac{\alpha(\lambda+\alpha)\mu^2}{p\lambda}$, we first construct a feasible distribution to **PRIMAL** as follows:

$$G_\alpha = \left(\frac{\sqrt{\frac{\lambda+\alpha}{\lambda}} - \mu\sqrt{\frac{\alpha}{pq}}}{\sqrt{\frac{\lambda+\alpha}{\lambda}} - \sqrt{\frac{\lambda}{\lambda+\alpha}}} \right) \cdot \delta_{\sqrt{\frac{\lambda pq}{\alpha(\lambda+\alpha)}}} + \left(\frac{\mu\sqrt{\frac{\alpha}{pq}} - \sqrt{\frac{\lambda}{\lambda+\alpha}}}{\sqrt{\frac{\lambda+\alpha}{\lambda}} - \sqrt{\frac{\lambda}{\lambda+\alpha}}} \right) \cdot \delta_{\sqrt{\frac{(\lambda+\alpha)pq}{\alpha\lambda}}}.$$

One can verify that $G_\alpha \in \mathcal{A}$ and the corresponding primal objective value under G_α is equal to

$$\mathbb{E}_{G_\alpha} [F(\lambda, q, \tilde{v})] = 2\mu\sqrt{\frac{\lambda(\lambda+\alpha)pq}{\alpha}} - \frac{\lambda pq}{\alpha} - cq. \quad (\text{EC.22})$$

We next construct a dual feasible that attains the same dual objective value. Note that $F(\lambda, q, v) = \lambda v^2 + \min\{\alpha v^2, pq\} - cq \forall v \geq 0$ when $q \leq \frac{p}{4\alpha}$. Hence, **DUAL** becomes

$$\begin{aligned} & \max_{s_\alpha, t_\alpha} \mu s_\alpha - t_\alpha \\ & \text{s.t. } v s_\alpha - t_\alpha \leq (\lambda + \alpha)v^2 - cq \quad \forall v \geq 0 \\ & \quad v s_\alpha - t_\alpha \leq \lambda v^2 + pq - cq \quad \forall v \geq 0 \\ & \quad s_\alpha \in \mathbb{R}, t_\alpha \in \mathbb{R}. \end{aligned}$$

Consider the following solution

$$s_\alpha = 2\sqrt{\frac{\lambda(\lambda + \alpha)pq}{\alpha}}, \quad t_\alpha = \frac{\lambda pq}{\alpha} + cq, \quad (\text{EC.23})$$

which satisfies

$$s_\alpha \mu - t_\alpha = 2\mu\sqrt{\frac{\lambda(\lambda + \alpha)pq}{\alpha}} - \frac{\lambda pq}{\alpha} - cq.$$

It remains to argue that this solution is feasible to **DUAL**. Note that the first semi-infinite constraint of **DUAL** is equivalent to

$$\max_{v \geq 0} \{s_\alpha v - (\lambda + \alpha)v^2 - t_\alpha + cq\} \leq 0.$$

For the left-hand side maximization, the optimal solution is $v^* = \frac{s_\alpha}{2(\lambda + \alpha)} \geq 0$, which attains an optimal value of $\frac{s_\alpha^2}{4(\lambda + \alpha)} - t_\alpha + cq = 0$. Hence, the first semi-infinite constraint is satisfied. Similarly, the second semi-infinite constraint of **DUAL** is equivalent to

$$\max_{v \geq 0} \{s_\alpha v - \lambda v^2 - t_\alpha - pq + cq\} \leq 0.$$

For the left-hand side, the optimal solution is $v^* = \frac{s_\alpha}{2\lambda}$ and the corresponding optimal value is $\frac{s_\alpha^2}{4\lambda} - t_\alpha - pq + cq = \frac{pq(\lambda + \alpha)}{\alpha} - \frac{pq}{\alpha}\lambda - pq = 0$. Hence, the second semi-infinite constraint is also satisfied, concluding that solution (EC.23) is feasible to **DUAL** and establishing the strong duality.

Scenario 1.2. When $q \leq \frac{p}{4\alpha}$ and $q \leq \frac{\alpha\lambda\mu^2}{p(\lambda + \alpha)}$, we construct a primal feasible solution $G_\alpha = \delta_\mu$ with a primal objective value $\mathbb{E}_{G_\alpha}[F(\lambda, q, \tilde{v})] = \lambda\mu^2 + pq - cq$. Consider the solution $s_\alpha = 2\lambda\mu$ and $t_\alpha = \lambda\mu^2 - (p - c)q$, which satisfies $s_\alpha\mu - t_\alpha = \lambda\mu^2 + pq - cq$. It remains to argue that this solution is feasible to **DUAL**. For the first semi-infinite constraint of **DUAL**,

$$\max_{v \geq 0} \{s_\alpha v - (\lambda + \alpha)v^2 - t_\alpha + cq\} = \frac{s_\alpha^2}{4(\lambda + \alpha)} - t_\alpha + cq = -\frac{\alpha\lambda\mu^2}{\lambda + \alpha} + pq \leq 0,$$

where the last inequality follows from $q \leq \frac{\alpha\lambda\mu^2}{p(\lambda + \alpha)}$. For the second semi-infinite constraint of **DUAL**,

$$\max_{v \geq 0} \{s_\alpha v - \lambda v^2 - t_\alpha - pq + cq\} = \frac{s_\alpha^2}{4\lambda} - t_\alpha - pq + cq = 0.$$

Scenario 1.3. When $q \leq \frac{p}{4\alpha}$ and $q \geq \frac{\alpha(\lambda + \alpha)\mu^2}{p\lambda}$, we construct a primal feasible solution $G_\alpha = \delta_\mu$ with a primal objective value $\mathbb{E}_{G_\alpha}[F(\lambda, q, \tilde{v})] = (\lambda + \alpha)\mu^2 - cq$. Consider the solution $s_\alpha = 2(\lambda + \alpha)\mu$ and

$t_\alpha = (\lambda + \alpha)\mu^2 + cq$, which satisfies $s_\alpha\mu - t_\alpha = (\lambda + \alpha)\mu^2 - cq$. For the first semi-infinite constraint of **DUAL**,

$$\max_{v \geq 0} \{s_\alpha v - (\lambda + \alpha)v^2 - t_\alpha + cq\} = \frac{s_\alpha^2}{4(\lambda + \alpha)} - t_\alpha + cq = 0.$$

Similarly, for the second semi-infinite constraint of **DUAL**,

$$\max_{v \geq 0} \{s_\alpha v - \lambda v^2 - t_\alpha - pq + cq\} = \frac{s_\alpha^2}{4\lambda} - t_\alpha - pq + cq = \frac{\alpha(\lambda + \alpha)\mu^2}{\lambda} - pq \leq 0,$$

where the last inequality follows from $q \geq \frac{\alpha(\lambda + \alpha)\mu^2}{p\lambda}$.

Scenario 1.4. When $\frac{p}{4\alpha} \leq q \leq \frac{p}{4\alpha} + \frac{p}{4\lambda}$ and $\frac{\alpha\lambda\mu^2}{p(\lambda + \alpha)} \leq q \leq \frac{\alpha(\lambda + \alpha)\mu^2}{p\lambda}$, **DUAL** becomes

$$\begin{aligned} & \max_{s_\alpha, t_\alpha} \mu s_\alpha - t_\alpha \\ & \text{s.t. } v s_\alpha - t_\alpha \leq (\lambda + \alpha)v^2 - cq & \forall 0 \leq v \leq \frac{p}{2\alpha} \\ & v s_\alpha - t_\alpha \leq \lambda v^2 + p\left(v - \frac{p}{4\alpha}\right) - cq & \forall v \geq \frac{p}{2\alpha} \\ & v s_\alpha - t_\alpha \leq \lambda v^2 + pq - cq & \forall v \geq \frac{p}{2\alpha} \\ & s_\alpha \in \mathbb{R}, t_\alpha \in \mathbb{R}. \end{aligned}$$

Consider the pair of primal feasible solution (EC.22) and dual solution (EC.23). Upon the results established in *Scenario 1.1*, it remains to argue that solution (EC.7) is feasible to the above representation of **DUAL**.

In *Scenario 1.1*, we have shown that $s_\alpha v - t_\alpha \leq (\lambda + \alpha)v^2 - cq \forall v \geq 0$ and $s_\alpha v - t_\alpha \leq \lambda v^2 + pq - cq \forall v \geq 0$, which are, respectively, more restrictive than the first and third semi-infinite constraints herein. Hence, the first and third constraints are satisfied. We next investigate the second constraint

$$\max_{v \geq \frac{p}{2\alpha}} \left\{ (s_\alpha - p)v - \lambda v^2 - t_\alpha + cq + \frac{p^2}{4\alpha} \right\} \leq 0.$$

The unconstrained maximizer $\frac{s_\alpha - p}{2\lambda}$ of the left-hand side maximization satisfies

$$\frac{s_\alpha - p}{2\lambda} = \sqrt{\frac{(\lambda + \alpha)pq}{\lambda\alpha}} - \frac{p}{2\lambda} \leq \frac{p}{2\alpha},$$

where the inequality follows from $q \leq \frac{p}{4\alpha} + \frac{p}{4\lambda}$. This implies that the constrained maximization is attained at $v = \frac{p}{2\alpha}$, and we have

$$s_\alpha \frac{p}{2\alpha} - \lambda \frac{p^2}{4\alpha^2} - t_\alpha \leq \alpha \frac{p^2}{4\alpha^2} - cq = p\left(\frac{p}{2\alpha} - \frac{p}{4\alpha}\right) - cq,$$

where the inequality follows from evaluating the first semi-infinite constraint at $v = \frac{p}{2\alpha}$. Hence, the second semi-infinite constraint is also satisfied, concluding this scenario.

Scenario 1.5. When $\frac{p}{4\alpha} \leq q \leq \frac{p}{4\alpha} + \frac{p}{4\lambda}$ and $q \leq \frac{\alpha\lambda\mu^2}{p(\lambda + \alpha)}$, we construct a primal feasible solution $G_\alpha = \delta_\mu$ with a primal objective value $\mathbb{E}_{G_\alpha}[F(\lambda, q, \tilde{v})] = \lambda\mu^2 + pq - cq$. Consider the solution $s_\alpha =$

$2\lambda\mu$ and $t_\alpha = \lambda\mu^2 - (p-c)q$, which satisfies $s_\alpha\mu - t_\alpha = \lambda\mu^2 + pq - cq$. The feasibility of (s_α, t_α) can be verified similarly as in *Scenario 1.2*.

Scenario 1.6. When $\frac{p}{4\alpha} \leq q \leq \frac{p}{4\alpha} + \frac{p}{4\lambda}$ and $q \geq \frac{\alpha(\lambda+\alpha)\mu^2}{p\lambda}$, we construct a primal feasible solution $G_\alpha = \delta_\mu$ with a primal objective value $\mathbb{E}_{G_\alpha}[F(\lambda, q, \tilde{v})] = (\lambda + \alpha)\mu^2 - cq$. Consider the solution $s_\alpha = 2(\lambda + \alpha)\mu$ and $t_\alpha = (\lambda + \alpha)\mu^2 + cq$, which satisfies $s_\alpha\mu - t_\alpha = (\lambda + \alpha)\mu^2 - cq$. The feasibility of (s_α, t_α) can be verified similarly as in *Scenario 1.3*.

Scenario 1.7. When $q \geq \frac{p}{4\alpha} + \frac{p}{4\lambda}$ and $\mu - \frac{p}{4\alpha} - \frac{p}{4\lambda} \leq q \leq \mu - \frac{p}{4\alpha} + \frac{p}{4\lambda}$, we first construct a primal feasible solution:

$$G_\alpha = \left(\frac{1}{2} - \frac{2\lambda}{p}(\mu - q - \frac{p}{4\alpha})\right) \cdot \delta_{q + \frac{p}{4\alpha} - \frac{p}{4\lambda}} + \left(\frac{1}{2} + \frac{2\lambda}{p}(\mu - q - \frac{p}{4\alpha})\right) \cdot \delta_{q + \frac{p}{4\alpha} + \frac{p}{4\lambda}}.$$

One can verify that $G_\alpha \in \mathcal{A}$ and the corresponding objective value under G_α is equal to

$$\mathbb{E}_{G_\alpha}[F(\lambda, q, \tilde{v})] = \left(2\lambda q + \frac{(\lambda + \alpha)p}{2\alpha}\right)\mu - \lambda q^2 - \frac{(\lambda + \alpha)pq}{2\alpha} - \frac{(\lambda + \alpha)^2 p^2}{16\alpha^2 \lambda} + (p - c)q.$$

Note that when $q \geq \frac{p}{4\alpha} + \frac{p}{4\lambda}$, **DUAL** becomes

$$\begin{aligned} & \max_{s_\alpha, t_\alpha} \mu s_\alpha - t_\alpha \\ & \text{s.t. } vs_\alpha - t_\alpha \leq (\lambda + \alpha)v^2 - cq \quad \forall 0 \leq v \leq \frac{p}{2\alpha} \\ & \quad vs_\alpha - t_\alpha \leq \lambda v^2 + p\left(v - \frac{p}{4\alpha}\right) - cq \quad \forall v \geq \frac{p}{2\alpha} \\ & \quad vs_\alpha - t_\alpha \leq \lambda v^2 + pq - cq \quad \forall v \geq \frac{p}{2\alpha} \\ & \quad s_\alpha \in \mathbb{R}, t_\alpha \in \mathbb{R}. \end{aligned}$$

Consider the following solution:

$$s_\alpha = 2\lambda q + \frac{(\lambda + \alpha)p}{2\alpha}, t_\alpha = \lambda q^2 + \frac{(\lambda + \alpha)pq}{2\alpha} + \frac{(\lambda + \alpha)^2 p^2}{16\alpha^2 \lambda} - (p - c)q.$$

Because

$$s_\alpha\mu - t_\alpha = \left(2\lambda q + \frac{(\lambda + \alpha)p}{2\alpha}\right)\mu - \lambda q^2 - \frac{(\lambda + \alpha)pq}{2\alpha} - \frac{(\lambda + \alpha)^2 p^2}{16\alpha^2 \lambda} + (p - c)q,$$

it remains to argue that this solution is feasible to **DUAL**. We observe that

$$\max_{v \geq 0} \left\{ (s_\alpha - p)v - \lambda v^2 + cq - t_\alpha + \frac{p^2}{4\alpha} \right\} \leq 0.$$

Indeed, for the left-hand side maximization, an optimal solution $v^* = \frac{s_\alpha - p}{2\lambda} \geq \frac{p}{2\alpha} \geq 0$ achieves the optimal value of $\frac{s_\alpha^2}{4(\lambda + \alpha)} - t_\alpha + cq + \frac{p^2}{4\alpha} = 0$. Hence, it holds that

$$-t_\alpha + s_\alpha v - \lambda v^2 \leq p\left(v - \frac{p}{4\alpha}\right) - cq \leq \alpha v^2 - cq \quad \forall v \geq 0,$$

where the last inequality follows from the fact that $p(v - \frac{p}{4\alpha}) \leq \alpha v^2 \forall v \geq 0$. Consequently, the first and second semi-infinite constraints are satisfied. Finally, we note that

$$\max_{v \geq 0} \{s_\alpha v - \lambda v^2 - t_\alpha + cq - pq\} = s_\alpha \frac{s_\alpha}{2\lambda} - \lambda \frac{s_\alpha^2}{4\lambda^2} - t_\alpha + cq - pq = 0,$$

where the first equality follows from the fact that an optimal solution to the leftmost maximization is $v^* = \frac{s_\alpha}{2\lambda}$ and the second equality follows from the definition of (s_α, t_α) . Hence, the third semi-infinite constraint holds, concluding this scenario.

Scenario 1.8. When $q \geq \frac{p}{4\alpha}$ and $q \leq \mu - \frac{p}{4\alpha} - \frac{p}{4\lambda}$, we construct a primal feasible solution $G_\alpha = \delta_\mu$ with a primal objective value $\mathbb{E}_{G_\alpha}[F(\lambda, q, \tilde{v})] = \lambda\mu^2 + pq - cq$. Consider the solution $s_\alpha = 2\lambda\mu$ and $t_\alpha = \lambda\mu^2 - (p-c)q$, which satisfies $s_\alpha\mu - t_\alpha = \lambda\mu^2 + pq - cq$. The feasibility of (s_α, t_α) can be verified similarly as *Step 1.2*.

Scenario 1.9. When $q \geq \frac{p}{4\alpha}$ and $q \geq \mu - \frac{p}{4\alpha} + \frac{p}{4\lambda}$, we first construct a primal feasible solution $G_\alpha = \delta_\mu$ with a primal objective value $\mathbb{E}_{G_\alpha}[F(\lambda, q, \tilde{v})] = \lambda\mu^2 + p(\mu - \frac{p}{4\alpha}) - cq$. Consider the solution $s_\alpha = 2\lambda\mu + p$ and $t_\alpha = \lambda\mu^2 + \frac{p^2}{4\alpha} + cq$, which satisfies $s_\alpha\mu - t_\alpha = \lambda\mu^2 + p(\mu - \frac{p}{4\alpha}) - cq$. For the feasibility of (s_α, t_α) , note that

$$\max_{v \geq 0} \left\{ (s_\alpha - p)v - \lambda v^2 + cq - t_\alpha + \frac{p^2}{4\alpha} \right\} = 0.$$

Hence, it holds that

$$-t_\alpha + s_\alpha v - \lambda v^2 \leq p\left(v - \frac{p}{4\alpha}\right) - cq \leq \alpha v^2 - cq \quad \forall v \geq 0,$$

where the last inequality follows from the fact that $p(v - \frac{p}{4\alpha}) \leq \alpha v^2 \forall v \geq 0$. Consequently, the first and second semi-infinite constraints are satisfied. Finally, we note that

$$\max_{v \geq 0} \{s_\alpha v - \lambda v^2 - t_\alpha + cq - pq\} = p\left(\mu - \frac{p}{4\alpha} + \frac{p}{4\lambda} - q\right) \leq 0,$$

where the last equality follows from $q \geq \mu - \frac{p}{4\alpha} + \frac{p}{4\lambda}$. Hence, the third semi-infinite constraint holds.

To summarize *Step 1*, we note that when the constructed primal feasible distribution is $G_\alpha = \delta_\mu$ (*i.e.*, *Scenarios 1.2, 1.3, 1.5, 1.6, 1.8, 1.9*), the objective function $L(q)$ is either increasing or decreasing in q , implying that the maximum can not be attained in these scenarios. Therefore, we only need to focus on the remaining scenarios (*i.e.*, *Scenarios 1.1, 1.4, 1.7*) where

$$L(q) = \begin{cases} 2\mu\sqrt{\frac{\lambda(\lambda+\alpha)pq}{\alpha}} - \frac{\lambda pq}{\alpha} - cq & q \in \mathcal{Q}_1 \\ \left(2\lambda q + \frac{(\lambda+\alpha)p}{2\alpha}\right)\mu - \lambda q^2 - \frac{(\lambda+\alpha)pq}{2\alpha} - \frac{(\lambda+\alpha)^2 p^2}{16\alpha^2 \lambda} + (p-c)q & q \in \mathcal{Q}_2 \end{cases}$$

with $\mathcal{Q}_1 = \{q \mid q \leq \frac{p}{4\alpha} + \frac{p}{4\lambda}, \frac{\alpha\lambda\mu^2}{p(\lambda+\alpha)} \leq q \leq \frac{\alpha(\lambda+\alpha)\mu^2}{p\lambda}\}$ and $\mathcal{Q}_2 = \{q \mid q \geq \frac{p}{4\alpha} + \frac{p}{4\lambda}, \mu - \frac{p}{4\alpha} - \frac{p}{4\lambda} \leq q \leq \mu - \frac{p}{4\alpha} + \frac{p}{4\lambda}\}$. The corresponding derivative takes the form

$$L'(q) = \begin{cases} \mu\sqrt{\frac{\lambda(\lambda+\alpha)p}{\alpha q}} - \frac{\lambda p}{\alpha} - c & q \in \mathcal{Q}_1 \\ 2\lambda\mu - 2\lambda q - \frac{(\lambda+\alpha)p}{2\alpha} + p - c & q \in \mathcal{Q}_2. \end{cases}$$

Step 2. We consider three scenarios based on the values of α and λ to solve for the optimal q .

Scenario 2.1. Suppose that $\lambda \leq \frac{c}{2\mu}$. For any $q \in \mathcal{Q}_1$, setting the derivative of $L(q)$ to 0 yields

$$q_\alpha^*(\lambda) = \frac{\lambda(\lambda+\alpha)p\mu^2}{\alpha(\lambda p/\alpha + c)^2}. \quad (\text{EC.24})$$

One can verify that $\frac{\alpha\lambda\mu^2}{p(\lambda+\alpha)} \leq q_\alpha^* \leq \frac{\alpha(\lambda+\alpha)\mu^2}{p\lambda}$. We next show that $q_\alpha^*(\lambda) \leq \frac{p}{4\lambda} + \frac{p}{4\alpha}$. Since given $\alpha \geq 0$,

$$\frac{\partial}{\partial \alpha} \left(q_\alpha^*(\lambda) - \frac{p}{4\alpha} \right) = \frac{p\lambda^2\mu^2(\alpha(p-c) + \alpha p + \lambda p)}{(\alpha c + \lambda p)^3} + \frac{p}{4\alpha^2} \geq 0, \quad (\text{EC.25})$$

we have

$$q_\alpha^*(\lambda) - \frac{p}{4\alpha} \leq \lim_{\alpha \rightarrow \infty} \left(q_\alpha^*(\lambda) - \frac{p}{4\alpha} \right) = \frac{\lambda p \mu^2}{c^2} \leq \frac{p}{4\lambda},$$

where the last inequality follows from $\lambda \leq \frac{c}{2\mu}$. Since $L(q)$ is concave, $q_\alpha^*(\lambda)$ is indeed optimal.

Scenario 2.2. Suppose that $\lambda \geq \frac{c}{2\mu}$ and $\alpha < \frac{p}{2(\mu-c/(2\lambda))}$. For $q \in \mathcal{Q}_1$, setting the derivative of $L(q)$ to 0 yields

$$q_\alpha^*(\lambda) = \frac{\lambda(\lambda+\alpha)p\mu^2}{\alpha(\lambda p/\alpha + c)^2} \in \left[\frac{\alpha\lambda\mu^2}{p(\lambda+\alpha)}, \frac{\alpha(\lambda+\alpha)\mu^2}{p\lambda} \right].$$

By (EC.25), $q_\alpha^*(\lambda) - \frac{p}{4\alpha}$ is increasing in α , and we have

$$q_\alpha^*(\lambda) - \frac{p}{4\alpha} < \lim_{\alpha \rightarrow \frac{p}{2(\mu-c/(2\lambda))}} \left(q_\alpha^*(\lambda) - \frac{p}{4\alpha} \right) = \frac{p-c+2\lambda\mu}{4\lambda} - \frac{1}{2} \left(\mu - \frac{c}{2\lambda} \right) = \frac{p}{4\lambda}.$$

This implies that $q_\alpha^*(\lambda) \in \mathcal{Q}_1$. Hence, $q_\alpha^*(\lambda)$ is optimal.

Scenario 2.3. Suppose that $\lambda \geq \frac{c}{2\mu}$ and $\alpha \geq \frac{p}{2(\mu-c/(2\lambda))}$. For $q \in \mathcal{Q}_2$, setting the derivative of $L(q)$ to 0 yields

$$q_\alpha^*(\lambda) = \mu + \frac{p-2c}{4\lambda} - \frac{p}{4\alpha}. \quad (\text{EC.26})$$

One can verify that $\mu - \frac{p}{4\alpha} - \frac{p}{4\lambda} \leq q_\alpha^*(\lambda) \leq \mu - \frac{p}{4\alpha} + \frac{p}{4\lambda}$. Since $\lambda \geq \frac{c}{2\mu}$ and $\alpha \geq \frac{p}{2(\mu-c/(2\lambda))}$, we have

$$q_\alpha^*(\lambda) = \mu + \frac{p-2c}{4\lambda} - \frac{p}{2\alpha} + \frac{p}{4\alpha} \geq \mu + \frac{p-2c}{4\lambda} - \left(\mu - \frac{c}{2\lambda} \right) + \frac{p}{4\alpha} = \frac{p}{4\alpha} + \frac{p}{4\lambda},$$

which indicates that $q_\alpha^*(\lambda) \in \mathcal{Q}_2$. Therefore, $q_\alpha^*(\lambda)$ is optimal.

To summarize *Step 2*, we note that *Scenario 2.1* and *Scenario 2.2* correspond to $\alpha < \frac{p}{2(\mu-c/(2\lambda))^+}$ and *Scenario 2.3* corresponds to $\alpha \geq \frac{p}{2(\mu-c/(2\lambda))^+}$. Hence, we have

$$q_\alpha^* = \begin{cases} \mu + \frac{p-2c}{4\lambda} - \frac{p}{4\alpha} & \alpha \geq \frac{p}{2(\mu-c/(2\lambda))^+} \quad \left(\lambda \geq \frac{c}{(2\mu-p/\alpha)^+} \right) \\ \frac{\lambda(\lambda+\alpha)p\mu^2}{\alpha(\lambda p/\alpha + c)^2} & \alpha < \frac{p}{2(\mu-c/(2\lambda))^+} \quad \left(\lambda < \frac{c}{(2\mu-p/\alpha)^+} \right). \end{cases}$$

Step 3. We next solve the optimal λ^* of the outer maximization of problem (EC.21), whose objective function we denote by

$$Q(\lambda) = -\lambda K + \sum_{i \in [M]} \max_{q_i \geq 0} \min_{G_i \in \mathcal{C}_i} \mathbb{E}_{G_i}[F_i(\lambda, q_i, \tilde{v}_i)] = -\lambda K + \sum_{i \in [M]} L_i(q_{i,\alpha}^*(\lambda)).$$

Note that given $v_i \geq 0$ and $i \in [M]$, $F_i(\lambda, q_i, v_i)$ is jointly concave in (λ, q_i) . Based on the first equality, $Q(\lambda)$ is concave in λ because (i) joint concavity of (λ, q_i) is preserved under non-negative weighted integration and minimization over $G_i \in \mathcal{C}_i$; (ii) concavity of λ is preserved under maximization over $q_i \geq 0$; and (iii) $-\lambda K$ is linear in λ . Leveraging the closed-form expression of $L_i(q_{i,\alpha}^*(\lambda))$, we derive the expression of $Q(\lambda)$ and its derivative. When $\lambda < \bar{\lambda}_i = \frac{c_i}{(2\mu_i - p_i/\alpha)^+}$ (*Scenario 2.1* and *Scenario 2.2*), plugging the expression of $q_{i,\alpha}^*(\lambda)$ in (EC.24), we have

$$L_i(q_{i,\alpha}^*(\lambda)) = \frac{\lambda p_i \mu_i^2 \alpha (\lambda + \alpha)}{\lambda p_i + \alpha c_i} \quad \text{and} \quad \frac{\partial L_i(q_{i,\alpha}^*(\lambda))}{\partial \lambda} = \frac{\mu_i^2 p_i (\alpha^2 c_i + 2\alpha c_i \lambda + \lambda^2 p_i)}{(\lambda p_i + \alpha c_i)^2}.$$

When $\lambda \geq \bar{\lambda}_i = \frac{c_i}{(2\mu_i - p_i/\alpha)^+}$ (*Scenario 2.3*), plugging the expression of $q_{i,\alpha}^*(\lambda)$ in (EC.26), we have

$$L_i(q_{i,\alpha}^*(\lambda)) = \frac{\lambda(c_i - p_i)p_i + \alpha(c^2 + 4\lambda\mu_i(\mu_i + p_i) - c(4\lambda\mu_i + p_i))}{4\alpha\lambda} \quad \text{and} \quad \frac{\partial L_i(q_{i,\alpha}^*(\lambda))}{\partial \lambda} = \frac{c_i(p_i - c_i)}{4\lambda^2}.$$

For any $\lambda \in (\bar{\lambda}_{j-1}, \bar{\lambda}_j)$ with $j \in [M+1]$, we then have

$$\begin{aligned} Q(\lambda) &= -\lambda K + \sum_{i \in [M] \setminus [j-1]} \frac{\lambda p_i \mu_i^2 \alpha (\lambda + \alpha)}{\lambda p_i + \alpha c_i} + \sum_{i \in [j-1]} \frac{4\alpha \lambda \mu_i (\mu_i + p_i - c_i) - (\lambda p_i + \alpha c_i)(p_i - c_i)}{4\alpha \lambda} \\ Q'(\lambda) &= -K + \sum_{i \in [M] \setminus [j-1]} \frac{\mu_i^2 p_i (\alpha^2 c_i + 2\alpha c_i \lambda + \lambda^2 p_i)}{(\lambda p_i + \alpha c_i)^2} + \sum_{i \in [j-1]} \frac{c_i(p_i - c_i)}{4\lambda^2} = -K + \Theta_j(\lambda). \end{aligned}$$

It can be noted that $Q(\lambda)$ is concave and $Q'(\lambda)$ is always decreasing in $(\bar{\lambda}_{j-1}, \bar{\lambda}_j)$, where at the end points it holds that $Q'_-(\bar{\lambda}_j) \geq Q'_+(\bar{\lambda}_j)$ for any $j \in [M+1]$. On the one hand, if

$$Q'_+(\bar{\lambda}_{i^*-1}) = -K + \Theta_{i^*}(\bar{\lambda}_{i^*-1}) \leq 0,$$

then when $i^* = 1$, we have $Q'(\lambda) \leq Q'_+(\bar{\lambda}_0) \leq 0$ for $\lambda \geq 0$, and hence $\lambda^* = \bar{\lambda}_0 = 0$. When $i^* > 1$, by the definition of i^* , we have $Q'_-(\bar{\lambda}_{i^*-1}) \geq 0$. By the optimality condition of concave functions, it is then clear that $\lambda^* = \bar{\lambda}_{i^*-1}$. On the other hand, if

$$Q'_+(\bar{\lambda}_{i^*-1}) = -K + \Theta_{i^*}(\bar{\lambda}_{i^*-1}) > 0,$$

then since (i) $Q'_-(\bar{\lambda}_{i^*}) < 0$ by the definition of i^* and (ii) $Q'(\lambda)$ is continuous in $(\bar{\lambda}_{i^*-1}, \bar{\lambda}_{i^*})$, there must exist some $\lambda^* \in (\bar{\lambda}_{i^*-1}, \bar{\lambda}_{i^*})$ such that $Q'(\lambda^*) = 0$ (i.e., $\Theta_{i^*}(\lambda^*) = K$), concluding *Step 3*. \square

Proof of Theorem 5.

With the optimal dual variable λ^* , we can determine the optimal order quantity leveraging (EC.24) and (EC.26) established in *Step 2* of the proof for Theorem 4. \square

Proof of Theorem 6.

By the interchangeability principle (see Lemma EC.3), we have

$$\max_{\psi \geq 0} \min_{G \in \mathcal{B}(\theta)} \min_{F \in \mathcal{P}} \{\mathbb{E}_F[\pi(\psi, \tilde{u})] + \alpha \cdot d(F, G)\} = \max_{\psi \geq 0} \min_{G \in \mathcal{B}(\theta)} \mathbb{E}_G \left[\min_{u \geq 0} \{\pi(\psi, u) + \alpha(u - \tilde{v})^2\} \right],$$

Using a standard duality argument (see, *e.g.*, Gao and Kleywegt 2023, Esfahani and Kuhn 2018), the right-hand side problem admits an equivalent dual reformulation

$$\max_{\psi \geq 0} \sup_{t \geq 0} \left\{ -t\theta + \mathbb{E}_H \left[\min_{u \geq 0, v \geq 0} \{\pi(\psi, u) + \alpha(u - v)^2 + t(v - \tilde{w})^2\} \right] \right\}$$

with a random variable $\tilde{w} \sim H$. By the first-order optimality condition, for fixed $u \geq 0$ and $w \geq 0$, the problem $\min_{v \geq 0} \{\alpha(u - v)^2 + t(v - w)^2\} = \frac{\alpha t}{\alpha + t}(u - w)^2$ with $v^* = \frac{\alpha}{\alpha + t}u + \frac{t}{\alpha + t}w$ being an optimal solution. That is to say, the above dual reformulation is equivalent to

$$\max_{\psi \geq 0} \sup_{t \geq 0} \left\{ -t\theta + \mathbb{E}_H \left[\min_{u \geq 0} \left\{ \pi(\psi, u) + \frac{\alpha t}{\alpha + t}(u - \tilde{w})^2 \right\} \right] \right\},$$

which, after interchanging the “max” operators over ψ and t and applying the variable substitution $\gamma \leftarrow \frac{\alpha t}{\alpha + t}$, becomes

$$\max_{0 \leq \gamma \leq \alpha} \left\{ -\frac{\alpha \gamma}{\alpha - \gamma} \theta + \max_{\psi \geq 0} \mathbb{E}_H \left[\min_{u \geq 0} \{\pi(\psi, u) + \gamma(u - \tilde{w})^2\} \right] \right\}. \quad (\text{EC.27})$$

Here, $\gamma = \alpha$ corresponds to $t = \infty$, and $\lim_{\gamma \rightarrow \alpha^-} -\frac{\alpha \gamma}{\alpha - \gamma} \theta = 0$ if $\theta = 0$ and $\lim_{\gamma \rightarrow \alpha^-} -\frac{\alpha \gamma}{\alpha - \gamma} \theta = \infty$ if $\theta > 0$. Hence, there must exist $\gamma^* \in [0, \alpha]$ such that problem (EC.27) can be equivalently solved by

$$\begin{aligned} \max_{\psi \geq 0} \mathbb{E}_H \left[\min_{u \geq 0} \{\pi(\psi, u) + \gamma^* \cdot (u - \tilde{w})^2\} \right] &= \max_{\psi \geq 0} \min_{F \in \mathcal{P}, \Gamma \in \mathcal{W}(F, H)} \mathbb{E}_\Gamma[\pi(\psi, \tilde{u}) + \gamma^* \cdot (\tilde{u} - \tilde{w})^2] \\ &= \max_{\psi \geq 0} \min_{F \in \mathcal{P}} \{\mathbb{E}_F[\pi(\psi, \tilde{u})] + \gamma^* \cdot d(F, H)\}, \end{aligned}$$

where the first equality follows from Lemma EC.3, and the second equality follows from the definition of $d(F, H)$. Hence, problem (17) is equivalent to $\max_{\psi \geq 0} \min_{F \in \mathcal{P}} \{\mathbb{E}_F[\pi(\psi, \tilde{u})] + \gamma^* \cdot d(F, H)\}$ for some $\gamma^* \in [0, \alpha]$.

In the remainder of the proof, we solve the optimal γ^* and $\psi_{\gamma^*}^*$ of problem (EC.27). For any fixed $w \geq 0$, define $\Psi(\gamma, q, w) = \min_{u \geq 0} \{\pi(q, u) + \gamma(u - w)^2\}$. Problem (EC.27) is then equivalent to

$$\max_{0 \leq \gamma \leq \alpha} \left\{ -\frac{\alpha \gamma}{\alpha - \gamma} \theta + \max_{\psi \geq 0} \mathbb{E}_H [\Psi(\gamma, \psi, \tilde{w})] \right\}. \quad (\text{EC.28})$$

We first solve, by the first-order optimality condition, the inner maximization of problem (EC.28) given $\gamma \in [0, \alpha]$. Let $Z(\psi) = \mathbb{E}_H[\Psi(\gamma, \psi, \tilde{w})]$. Given $w \geq 0$, $\Psi(\gamma, \psi, w)$ is concave in ψ . Since concavity is preserved under non-negative weighted integration, $Z(\psi)$ is also concave, and hence, its derivative is decreasing in ψ . In particular, the derivative of $Z(\psi)$ is

$$Z'(\psi) = \begin{cases} p \cdot \mathbb{P}_H\{\gamma \tilde{w}^2 \geq p\psi\} - c & \psi < \frac{p}{4\gamma} \\ p \cdot \mathbb{P}_H\{\tilde{w} - \frac{p}{4\gamma} \geq \psi\} - c & \psi \geq \frac{p}{4\gamma} \end{cases}$$

with $Z'(0) = p - c > 0$ and $\lim_{\psi \rightarrow \infty} Z'(\psi) = -c < 0$. Let $\gamma_0 = \frac{p}{2q_H^*}$. If $\gamma < \gamma_0$, then $Z'(\frac{p}{4\gamma}) = p(\kappa - H(\frac{p}{2\gamma})) < 0$. Hence, the maximum of $Z(\psi)$ is attained in $[0, \frac{p}{4\gamma}]$. Setting the derivative to 0 yields

$$\psi_\gamma^* = (q_H^*)^2 \cdot \frac{\gamma}{p} < \frac{p}{4\gamma}. \quad (\text{EC.29})$$

If $\gamma \geq \gamma_0$, then $Z'(\frac{p}{4\gamma}) = p(\kappa - H(\frac{p}{2\gamma})) \geq 0$, implying that the maximum of $Z(\psi)$ must be attained in $[\frac{p}{4\gamma}, \infty)$. Setting the derivative to 0 then yields

$$\psi_\gamma^* = q_H^* - \frac{p}{4\gamma} \geq \frac{p}{4\gamma}. \quad (\text{EC.30})$$

We next solve the optimal γ^* of the outer maximization of problem (EC.28), whose objective function we denote by

$$Q(\gamma) = -\frac{\alpha\gamma}{\alpha - \gamma}\theta + \max_{\psi \geq 0} \mathbb{E}_H[\Psi(\gamma, \psi, \tilde{w})] = -\frac{\alpha\gamma}{\alpha - \gamma}\theta + \mathbb{E}_H[\Psi(\gamma, \psi_\gamma^*, \tilde{w})].$$

Note that given $w \geq 0$, $\Psi(\gamma, \psi, w)$ is jointly concave in (γ, ψ) . Based on the first equality, $Q(\gamma)$ is concave in γ because (i) concavity of (γ, ψ) is preserved under non-negative weighted integration; (ii) concavity of γ is preserved under maximization over $\psi \geq 0$; and (iii) $-\frac{\alpha\gamma}{\alpha - \gamma}\theta$ is concave in γ . Leveraging the closed-form expression of $\Psi(\alpha, \psi, w)$ in Lemma EC.3, we derive the expression of $Q(\gamma)$ and its derivative. When $\gamma < \gamma_0$, plugging the expression of ψ_γ^* in (EC.29), we have

$$\begin{aligned} Q(\gamma) &= -\frac{\alpha\gamma}{\alpha - \gamma}\theta + \mathbb{E}_H[\Psi(\gamma, \psi_\gamma^*, \tilde{w})] = -\frac{\alpha\gamma}{\alpha - \gamma}\theta + \int_0^{q_H^*} zw^2 dH(w) \\ Q'(\gamma) &= -\frac{\alpha^2}{(\alpha - \gamma)^2}\theta + \int_0^{q_H^*} w^2 dH(w). \end{aligned}$$

When $\gamma \geq \gamma_0$, plugging the expression of ψ_γ^* in (EC.30), we have

$$\begin{aligned} Q(\gamma) &= -\frac{\alpha\gamma}{\alpha - \gamma}\theta + \int_0^{\frac{p}{2\gamma}} \gamma w^2 dH(w) + \int_{\frac{p}{2\gamma}}^{q_H^*} p \left(w - \frac{p}{4\gamma} \right) dH(w) \\ Q'(\gamma) &= -\frac{\alpha^2\theta}{(\alpha - \gamma)^2} + \frac{p^2}{4\gamma^2} \left(\kappa - H\left(\frac{p}{2\gamma}\right) \right) + \int_0^{\frac{p}{2\gamma}} w^2 dH(w). \end{aligned}$$

Note that $Q'(\gamma)$ is always decreasing in γ . When $\theta = 0$, it is straightforward to see that $Q'(\gamma) \geq 0$ regardless of whether $\gamma < \gamma_0$ or $\gamma \geq \gamma_0$. Hence, $\gamma^* = \alpha$ (which corresponds to $t^* = \infty$ in the dual reformulation). In the following, we focus on $\theta > 0$. Based on the sign of $Q'(0)$, we divide the problem into two scenarios: $\theta \geq \beta$ and $\theta < \beta$, with $\beta = \int_0^{q_H^*} u^2 dH(u)$.

For the former scenario of $\theta \geq \beta$, $Q'(\gamma) \leq Q'(0) = -\theta + \beta \leq 0$ for any $\gamma \in [0, \alpha]$. Hence, the maximum of $Q(\gamma)$ is attained at $\gamma^* = 0$. Equation (EC.29) then yields $\psi_{\gamma^*}^* = 0$. This corresponds to the case (i) in the statement.

For the latter scenario of $\theta < \beta$, $Q'(0) = -\theta + \beta > 0$. To proceed, we further consider two situations based on the sign of $Q'(\gamma_0)$. If $1 - \sqrt{\frac{\theta}{\beta}} < \frac{\gamma_0}{\alpha}$, *i.e.*, $\sqrt{\frac{\beta}{\theta}} < \frac{\alpha}{\alpha - \gamma_0}$, then

$$Q'(\lambda_0) = \beta - \frac{\alpha^2}{(\alpha - \gamma_0)^2} \theta = \left(\sqrt{\beta} + \frac{\alpha}{\alpha - \gamma_0} \sqrt{\theta} \right) \left(\sqrt{\frac{\beta}{\theta}} - \frac{\alpha}{\alpha - \gamma_0} \right) \sqrt{\theta} < 0.$$

Since $Q'(0) = -\theta + \beta > 0$, the maximum of $Q(\gamma)$ must be attained in $[0, \gamma_0]$. Setting the derivative of $Q(\gamma)$ to 0 yields $\gamma^* = \alpha(1 - \sqrt{\frac{\theta}{\beta}}) < \gamma_0$. By equation (EC.29) we have

$$\psi_{\gamma^*}^* = (q_H^*)^2 \left(1 - \sqrt{\frac{\theta}{\beta}} \right) \cdot \frac{\alpha}{p}.$$

This corresponds to case (ii) in the statement. If $1 - \sqrt{\frac{\theta}{\beta}} \geq \frac{\gamma_0}{\alpha}$, then $Q'(\gamma_0) \geq 0$. Moreover, $\theta > 0$ gives $Q'_-(\alpha) = -\infty$, which further implies that there exists some $\gamma^* \in [\gamma_0, \alpha)$ such that

$$-\frac{\alpha^2 \theta}{(\alpha - \gamma^*)^2} + \frac{p^2}{4\gamma^{*2}} \left(\kappa - H\left(\frac{p}{2\gamma^*}\right) \right) + \int_0^{\frac{p}{2\gamma^*}} w^2 dH(w) = 0.$$

Equation (EC.30) then yields $\psi_{\gamma^*}^* = q_H^* - \frac{p}{4\gamma^*}$. This corresponds to case (iii) in the statement. \square

Proof of Theorem 7.

By theorem 4.2 in Ben-Tal and Teboulle (2007), given $G \in \mathcal{A}$ we have

$$\min_{F \in \mathcal{P}} \{ \mathbb{E}_F[\pi(q, \tilde{u})] + \alpha \cdot d_\phi(F \| G) \} = \max_{\tau \in \mathbb{R}} \left\{ \tau - \alpha \cdot \mathbb{E}_G \left[\phi^* \left(\frac{\tau - \pi(q, \tilde{v})}{\alpha} \right) \right] \right\},$$

where the conjugate function $\phi^*(s) = \max\{-1, s\}$ has a domain $(-\infty, 1]$. Then for any $v \geq 0$, $\tau - \pi(q, v) \leq \alpha$, *i.e.*, $\tau \leq \alpha - cq$. Plugging the expression of $\phi^*(\cdot)$, problem (19) becomes

$$\begin{aligned} & \max_{q \geq 0} \min_{G \in \mathcal{A}} \max_{\tau \leq \alpha - cq} \{ \tau - \mathbb{E}_G[\max\{-\alpha, \tau - \pi(q, \tilde{v})\}] \} \\ &= \max_{q \geq 0} \min_{G \in \mathcal{A}} \max_{\tau \leq \alpha - cq} \{ -\mathbb{E}_G[\max\{-\alpha - \tau, -\pi(q, \tilde{v})\}] \} \\ &= \max_{q \geq 0} \min_{G \in \mathcal{A}} \max_{\tau \leq \alpha - cq} \mathbb{E}_G[\min\{\alpha + \tau, \pi(q, \tilde{v})\}] \\ &= \max_{q \geq 0} \min_{G \in \mathcal{A}} \max_{\tau \geq cq - \alpha} \{ \mathbb{E}_G[\min\{\alpha - \tau + cq, p\tilde{v}, pq\}] - cq \}, \end{aligned}$$

where the last line follows from the variable substitution $-\tau \leftarrow \tau$ and $\pi(q, v) = p \cdot \min\{q, v\} - cq$.

We first look at the inner maximization over τ . For any $\tau \geq \alpha + cq$ (resp., $\tau \leq \alpha - (p - c)q$), $\min\{\alpha - \tau + cq, p\tilde{v}, pq\} = 0$ (resp., $= \min\{p\tilde{v}, pq\}$) and hence, $\mathbb{E}_G[\min\{\alpha - \tau + cq, p\tilde{v}, pq\}] - cq$ is independent of τ . Since it is continuous in τ , the maximum must be attained in $[\alpha - (p - c)q, \alpha + cq]$. Consequently, it suffices to focus on $\alpha - (p - c)q \leq \tau \leq \alpha + cq$, which, with the prerequisite $\tau \geq cq - \alpha$, becomes $0 \leq \alpha - \tau + cq \leq \min\{pq, 2\alpha\}$.

We next look at the optimization over $q \geq 0$:

$$\begin{aligned} & \max_{q \geq 0} \min_{G \in \mathcal{A}} \max_{0 \leq \alpha - \tau + cq \leq \min\{pq, 2\alpha\}} \{\mathbb{E}_G[\min\{\alpha - \tau + cq, p\tilde{v}\}] - cq\} \\ &= \max_{q \geq 0} \min_{G \in \mathcal{A}} \max_{0 \leq \tau \leq \min\{pq, 2\alpha\}} \{\mathbb{E}_G[\min\{\tau, p\tilde{v}\}] - cq\} \\ &= \max_{q \geq 0} \min_{G \in \mathcal{A}} \{\mathbb{E}_G[\min\{pq, 2\alpha, p\tilde{v}\}] - cq\}, \end{aligned}$$

where the first equality follows from the variable substitution $\tau \leftarrow \alpha - \tau + cq$ and the second equality follows from the fact that $\mathbb{E}_G[\min\{\tau, p\tilde{v}\}]$ is increasing in τ so its maximum is attained at $\min\{pq, 2\alpha\}$. When $q \geq \frac{2\alpha}{p}$, the objective function $\mathbb{E}_G[\min\{pq, 2\alpha, p\tilde{v}\}] - cq = \mathbb{E}_G[\min\{2\alpha, p\tilde{v}\}] - cq$ is decreasing in q given $G \in \mathcal{A}$. Hence, it is optimal to set q to $\frac{2\alpha}{p}$ whenever $q \geq \frac{2\alpha}{p}$. That is to say, the optimal order quantity of problem (19) must reside in $[0, \frac{2\alpha}{p}]$. For this interval, we have

$$\max_{0 \leq q \leq \frac{2\alpha}{p}} \min_{G \in \mathcal{A}} \{\mathbb{E}_G[\min\{pq, 2\alpha, p\tilde{v}\}] - cq\} = \max_{0 \leq q \leq \frac{2\alpha}{p}} \min_{G \in \mathcal{A}} \mathbb{E}_G[\pi(q, \tilde{v})],$$

where the equality follows from the fact that $\min\{pq, 2\alpha, p\tilde{v}\} = \min\{pq, p\tilde{v}\}$ for any $v \geq 0$ and $q \leq \frac{2\alpha}{p}$. Hence, it suffices to solve the right-hand side problem—a variant of **AMBIGUITY** with an additional upper bound $\frac{2\alpha}{p}$ on the order quantity. Let $\Phi(q) = \min_{G \in \mathcal{A}} \mathbb{E}_G[\pi(q, \tilde{v})]$. As shown in Scarf (1958), when $\kappa < \frac{\sigma^2}{\mu^2 + \sigma^2}$, $\Phi(q)$ is decreasing in q , so the optimal order quantity is $q_\alpha^* = 0$. When $\kappa \geq \frac{\sigma^2}{\mu^2 + \sigma^2}$, $\Phi(q)$ is increasing in $[0, \mu + \sigma f(1 - \kappa)]$ while decreasing in $[\mu + \sigma f(1 - \kappa), \infty)$. Hence, $q_\alpha^* = \min\{\frac{2\alpha}{p}, \mu + \sigma f(1 - \kappa)\}$. Combining the expression of q_∞^* in (1) then completes the proof. \square

EC.3. Transformed Worst-Case Distribution

In this section, we derive the worst-case transformed distribution $T_{\varphi_\alpha}[G_\alpha^*]$ given an order quantity $q \geq 0$. For ease of notation, we define

$$\begin{cases} v_1 = \frac{1}{2\mu} \left(\frac{pq}{\alpha} + \mu^2 + \sigma^2 - \sqrt{\left(\frac{pq}{\alpha} + \mu^2 + \sigma^2 \right)^2 - 4\mu^2 \frac{pq}{\alpha}} \right) \\ v_2 = \frac{1}{2\mu} \left(\frac{pq}{\alpha} + \mu^2 + \sigma^2 + \sqrt{\left(\frac{pq}{\alpha} + \mu^2 + \sigma^2 \right)^2 - 4\mu^2 \frac{pq}{\alpha}} \right) \\ v_3 = q + \frac{p}{4\alpha} - \sqrt{\left(q + \frac{p}{4\alpha} - \mu \right)^2 + \sigma^2} \\ v_4 = q + \frac{p}{4\alpha} + \sqrt{\left(q + \frac{p}{4\alpha} - \mu \right)^2 + \sigma^2}. \end{cases}$$

PROPOSITION EC.1 (WORST-CASE TRANSFORMED DISTRIBUTION). *Given $q \geq 0$ and $\alpha \geq 0$, the worst-case transformed distribution $T_{\varphi_\alpha}[G_\alpha^*]$ of **TRANSFORM** can be characterized as follows.*

(i) *When $0 \leq q \leq \frac{p}{4\alpha}$, we have*

$$T_{\varphi_\alpha}[G_\alpha^*] = \left(\frac{1}{2} - \frac{\mu^2 - \sigma^2 - \frac{pq}{\alpha}}{2\sqrt{\left(\frac{pq}{\alpha} + \mu^2 + \sigma^2 \right)^2 - 4\mu^2 \frac{pq}{\alpha}}} \right) \cdot \delta_{\frac{\alpha}{p} v_1} + \left(\frac{1}{2} + \frac{\mu^2 - \sigma^2 - \frac{pq}{\alpha}}{2\sqrt{\left(\frac{pq}{\alpha} + \mu^2 + \sigma^2 \right)^2 - 4\mu^2 \frac{pq}{\alpha}}} \right) \cdot \delta_{\frac{\alpha}{p} v_2}.$$

(ii) When $q \geq \frac{p}{4\alpha}$ and $(2\mu - \frac{p}{\alpha})q < \mu^2 + \sigma^2 - \frac{p\mu}{2\alpha}$, we have

$$T_{\varphi_\alpha}[G_\alpha] = \left(\frac{1}{2} - \frac{\mu^2 - \sigma^2 - \frac{pq}{\alpha}}{2\sqrt{(\frac{pq}{\alpha} + \mu^2 + \sigma^2)^2 - 4\mu^2\frac{pq}{\alpha}}} \right) \cdot \delta_{\frac{\alpha}{p}v_1^2} + \left(\frac{1}{2} + \frac{\mu^2 - \sigma^2 - \frac{pq}{\alpha}}{2\sqrt{(\frac{pq}{\alpha} + \mu^2 + \sigma^2)^2 - 4\mu^2\frac{pq}{\alpha}}} \right) \cdot \delta_{v_2 - \frac{p}{4\alpha}}.$$

(iii) When $q \geq \frac{p}{4\alpha}$ and $(2\mu - \frac{p}{\alpha})q \geq \mu^2 + \sigma^2 - \frac{p\mu}{2\alpha}$, we have

$$T_{\varphi_\alpha}[G_\alpha] = \frac{1}{2} \left(1 + \frac{q + \frac{p}{4\alpha} - \mu}{\sqrt{(q + \frac{p}{4\alpha} - \mu)^2 + \sigma^2}} \right) \cdot \delta_{v_3 - \frac{p}{4\alpha}} + \frac{1}{2} \left(1 - \frac{q + \frac{p}{4\alpha} - \mu}{\sqrt{(q + \frac{p}{4\alpha} - \mu)^2 + \sigma^2}} \right) \cdot \delta_{v_4 - \frac{p}{4\alpha}}.$$

Proof. Given $q \geq 0$, we have derived the expression of the worst-case distribution G_α^* as in (EC.6) and (EC.8). Plugging the expression of φ_α , we then obtain the desired results. \square

EC.4. On the Computation of $d(D, \mathcal{A}_N)$

In this section, we provide an exact computation for the distance between the data-generating distribution D and the mean-variance ambiguity set \mathcal{A}_N . If $\frac{\hat{\mu}}{\hat{\sigma}} \geq \frac{\mu}{\sigma}$, the closed-form expression for $d(D, \mathcal{A}_N)$ has been derived in Lemma 1, and we shall focus on $\frac{\hat{\mu}}{\hat{\sigma}} < \frac{\mu}{\sigma}$ subsequently.

PROPOSITION EC.2. *If $\frac{\hat{\mu}}{\hat{\sigma}} < \frac{\mu}{\sigma}$, then we have $d(D, \mathcal{A}_N) = -2s^*\hat{\mu} - (2r^* + 1)(\hat{\mu}^2 + \hat{\sigma}^2) + \mu^2 + \sigma^2$, where (s^*, r^*) is the solution to the following equation*

$$\int_{s^*}^{+\infty} (u - s^*) dD(u) = (r^* + 1)\hat{\mu}, \quad \int_{s^*}^{+\infty} (u - s^*)^2 dD(u) = (r^* + 1)^2(\hat{\mu}^2 + \hat{\sigma}^2).$$

Proof. Note that the distance between D and \mathcal{A}_N can be written as the following moment problem

$$\begin{aligned} & \min \mathbb{E}_\Gamma[(\tilde{u} - \tilde{v})^2] \\ & \text{s.t. } \mathbb{E}_G[\tilde{v}] = \hat{\mu} \\ & \quad \mathbb{E}_G[\tilde{v}^2] = \hat{\mu}^2 + \hat{\sigma}^2 \\ & \quad \tilde{u} \sim D, \tilde{v} \sim G \in \mathcal{P}, (\tilde{u}, \tilde{v}) \sim \Gamma \in \mathcal{W}(D, G). \end{aligned}$$

Introducing dual variables to the moment constraints, we obtain an equivalent dual reformulation

$$\begin{aligned} & \sup_{s, r} \left\{ -s\hat{\mu} - r(\hat{\mu}^2 + \hat{\sigma}^2) + \min_{G \in \mathcal{P}, \Gamma \in \mathcal{W}(D, G)} \mathbb{E}_\Gamma[(\tilde{u} - \tilde{v})^2 + s\tilde{v} + r\tilde{v}^2] \right\} \\ & = \sup_{s, r} \left\{ -s\hat{\mu} - r(\hat{\mu}^2 + \hat{\sigma}^2) + \mathbb{E}_D \left[\min_{v \geq 0} \{(\tilde{u} - v)^2 + sv + rv^2\} \right] \right\}, \end{aligned}$$

where the equality follows from the interchangeability characterized in Lemma EC.3. We proceed the remaining proof by solving the inner minimization problem over v and the outer maximization problem over s and r sequentially. For ease of notation, we define $g(v) = (u - v)^2 + sv + rv^2$ and $Q(s, r) = -s\hat{\mu} - r(\hat{\mu}^2 + \hat{\sigma}^2) + \mathbb{E}_D[\min_{v \geq 0} \{(\tilde{u} - v)^2 + sv + rv^2\}]$. For the inner minimization problem over $v \geq 0$, to ensure that $g(v)$ has a finite minimum value, we must have $r + 1 \geq 0$. Moreover, it is straightforward to verify that the function $Q(s, r)$ is jointly concave in (s, r) . In the following, we divide the problem into two arguments.

Scenario 1. When $s \leq 0$, it is straightforward to see that $\min_{v \geq 0} g(v) = -\frac{(s-2u)^2}{4(r+1)} + u^2$ with minimizer $v^* = -\frac{s-2u}{2(r+1)}$. Hence, the objective function becomes

$$Q(s, r) = -s\hat{\mu} - r(\hat{\mu}^2 + \hat{\sigma}^2) - \frac{\mathbb{E}_G[(s-2\tilde{u})^2]}{4(r+1)} + \mu^2 + \sigma^2 = -s\hat{\mu} - r(\hat{\mu}^2 + \hat{\sigma}^2) + \frac{r(\mu^2 + \sigma^2) + s\mu - \frac{s^2}{4}}{r+1}.$$

Consider the partial derivatives of $Q(s, r)$ with respect to s ,

$$\frac{\partial Q(s, r)}{\partial s} = -\frac{s-2\mu+2(r+1)\hat{\mu}}{2(r+1)}, \quad \frac{\partial Q(s, r)}{\partial r} = -(\hat{\mu}^2 + \hat{\sigma}^2) + \frac{\mu^2 + \sigma^2 - s\mu + \frac{s^2}{4}}{(r+1)^2}.$$

Under the condition $\frac{\hat{\mu}}{\hat{\sigma}} < \frac{\mu}{\sigma}$, we consider the solution $(s^*, r^*) = (0, \frac{\sqrt{\mu^2 + \sigma^2}}{\sqrt{\hat{\mu}^2 + \hat{\sigma}^2}} - 1)$. It is straightforward to verify that $\frac{\partial Q(s^*, r^*)}{\partial s} \geq 0$ and $\frac{\partial Q(s^*, r^*)}{\partial r} = 0$. Note that for any $s \leq 0$ and r , we have

$$\frac{\partial Q(s^*, r^*)}{\partial s}(s - s^*) + \frac{\partial Q(s^*, r^*)}{\partial r}(r - r^*) \leq 0,$$

which implies that s^* and r^* are indeed optimal by the optimality condition of concave functions. Plugging the expressions of s^* and r^* , the objective function then becomes $Q(s^*, r^*) = (\sqrt{\mu^2 + \sigma^2} - \sqrt{\hat{\mu}^2 + \hat{\sigma}^2})^2 \leq (\mu - \hat{\mu})^2 + (\sigma - \hat{\sigma})^2$, which implies that the optimum would not be attained in this case since it always holds that $d(D, \mathcal{A}_N) \geq (\mu - \hat{\mu})^2 + (\sigma - \hat{\sigma})^2$.

Scenario 2. When $s \geq 0$, it is straightforward to verify that $\min_{v \geq 0} g(v) = -\frac{(u-\frac{s}{2})^2}{r+1} + u^2$ when $u \geq \frac{s}{2}$, and $\min_{v \geq 0} g(v) = u^2$ when $u < \frac{s}{2}$. Hence, the objective function becomes

$$Q(s, r) = -s\hat{\mu} - r(\hat{\mu}^2 + \hat{\sigma}^2) - \int_{\frac{s}{2}}^{+\infty} \frac{(u-\frac{s}{2})^2}{r+1} dD(u) + \mu^2 + \sigma^2.$$

If $\frac{\hat{\mu}}{\hat{\sigma}} < \frac{\mu}{\sigma}$, we consider the solution (s^*, r^*) that satisfies

$$\int_{\frac{s^*}{2}}^{+\infty} \left(u - \frac{s^*}{2}\right) dD(u) = (r^* + 1)\hat{\mu}, \quad \int_{\frac{s^*}{2}}^{+\infty} \left(u - \frac{s^*}{2}\right)^2 dD(u) = (r^* + 1)^2(\hat{\mu}^2 + \hat{\sigma}^2). \quad (\text{EC.31})$$

We first show that there exists some $s \geq 0$ and $r > -1$ satisfying (EC.31). To this end, we eliminate the variable r , and it suffices to check whether there is $s \geq 0$ such that

$$\hat{\mu}^2 \int_{\frac{s}{2}}^{+\infty} \left(u - \frac{s}{2}\right)^2 dD(u) - (\hat{\mu}^2 + \hat{\sigma}^2) \left(\int_{\frac{s}{2}}^{+\infty} \left(u - \frac{s}{2}\right) dD(u)\right)^2 = 0.$$

Define $h(s) = \hat{\mu}^2 \int_{\frac{s}{2}}^{+\infty} (u - \frac{s}{2})^2 dD(u) - (\hat{\mu}^2 + \hat{\sigma}^2) (\int_{\frac{s}{2}}^{+\infty} (u - \frac{s}{2}) dD(u))^2$. Setting the derivative $h'(s) = \int_{\frac{s}{2}}^{+\infty} (u - \frac{s}{2}) dD(u) ((\hat{\mu}^2 + \hat{\sigma}^2)(1 - D(\frac{s}{2})) - \hat{\mu}^2)$ to 0 then yields that $s^\circ = 2D^{-1}(\frac{\hat{\sigma}^2}{\hat{\mu}^2 + \hat{\sigma}^2})$. It is straightforward to see that $h(0) = \hat{\mu}^2(\mu^2 + \sigma^2) - \mu^2(\hat{\mu}^2 + \hat{\sigma}^2) < 0$ and $\lim_{s \rightarrow +\infty} h(s) = 0$, which implies that $h(s^\circ) > \lim_{s \rightarrow +\infty} h(s) = 0$ since $h(s)$ is decreasing in $(s^\circ, +\infty)$. Therefore, there must exist some $s^* \in [0, s^\circ]$ and $r^* \geq -1$ satisfying the moment constraints (EC.31). Moreover, it can be verified that (s^*, r^*) satisfies the first-order condition, *i.e.*, $\frac{\partial Q(s^*, r^*)}{\partial s} = \frac{\partial Q(s^*, r^*)}{\partial r} = 0$. Hence, (s^*, r^*) is optimal. Plugging the conditions (EC.31) into the objective function, we then obtain $Q(s^*, r^*) = -s^*\hat{\mu} - (2r^* + 1)(\hat{\mu}^2 + \hat{\sigma}^2) + \mu^2 + \sigma^2$. Applying the variable substitution $s^* \rightarrow 2s^*$ then yields the desired result immediately. \square

EC.5. On the Generality of Theorem 5

In this section, we show how Theorem 5 generalizes Theorem 2 for single product to multiple products. To see this, let $K = \mu^2 + \sigma^2$ and note that for the single-product problem, λ^* is essentially the optimal dual variable r_α^* in problem (7). Plugging the expression of q_α^* into equations (EC.7) and (EC.9), it is immediate to see that

$$r_\alpha^* = \begin{cases} \frac{\sqrt{\kappa(1-\kappa)}}{2p\sigma} & \kappa \geq \frac{\sigma^2}{\mu^2 + \sigma^2}, \alpha \geq \frac{p}{2(\mu - \sigma\sqrt{(1-\kappa)/\kappa})} \\ \frac{\alpha\sqrt{\kappa(1-\kappa)}}{\sigma} \left(\mu - \sigma\sqrt{\frac{1-\kappa}{\kappa}} \right) & \kappa \geq \frac{\sigma^2}{\mu^2 + \sigma^2}, \alpha < \frac{p}{2(\mu - \sigma\sqrt{(1-\kappa)/\kappa})} \\ 0 & \kappa < \frac{\sigma^2}{\mu^2 + \sigma^2}. \end{cases}$$

If $\kappa \geq \frac{\sigma^2}{\mu^2 + \sigma^2}$ and $\alpha \geq \frac{p}{2(\mu - \sigma\sqrt{(1-\kappa)/\kappa})}$, it holds that $\lambda^* = \frac{\sqrt{\kappa(1-\kappa)}}{2p\sigma}$ and hence, $\frac{p}{2(\mu - c/(2\lambda^*))^+} = \frac{p}{2(\mu - \sigma\sqrt{(1-\kappa)/\kappa})}$. By Theorem 5, we have

$$q_\alpha^* = \mu + \frac{p-2c}{4\lambda^*} - \frac{p}{4\alpha} = \mu + \sigma \frac{2\kappa-1}{2\sqrt{\kappa(1-\kappa)}} - \frac{p}{4\alpha}.$$

If $\kappa \geq \frac{\sigma^2}{\mu^2 + \sigma^2}$ and $\alpha < \frac{p}{2(\mu - \sigma\sqrt{(1-\kappa)/\kappa})}$, then $\lambda^* = \frac{\alpha\sqrt{\kappa(1-\kappa)}}{\sigma} \left(\mu - \sigma\sqrt{\frac{1-\kappa}{\kappa}} \right)$. In this case, we can verify that $\alpha < \frac{p}{2(\mu - c/(2\lambda^*))^+}$, thus by Theorem 5,

$$q_\alpha^* = \frac{\lambda^*(\lambda^* + \alpha)p\mu^2}{\alpha(\lambda^*p/\alpha + c)^2} = (\mu^2 - \sigma^2 + 2\mu\sigma f(1-\kappa)) \cdot \frac{\alpha}{p}.$$

If $\kappa < \frac{\sigma^2}{\mu^2 + \sigma^2}$, we always have $\lambda^* = 0$, leading to $q_\alpha^* = 0$. Consolidating these three scenarios then recovers the optimal solution (9) in Theorem 2.

EC.6. Multiple Products with Complete Covariance Information

In line with the setting of Section 6.1, we study misspecification-averse multi-product newsvendor with mean and (complete) covariance information. Consider M products (with unit price p_i and cost c_i) whose random demands are collectively denoted by $\tilde{\mathbf{u}} = (\tilde{u}_1, \dots, \tilde{u}_i) \sim F$ that follows a multi-dimensional distribution F . The misspecification-averse newsvendor then solves

$$\max_{\mathbf{q} \geq \mathbf{0}} \min_{F \in \mathcal{P}_M} \{ \mathbb{E}_F[\omega(\mathbf{q}, \tilde{\mathbf{u}})] + \alpha \cdot d(F, \mathcal{A}) \}, \quad (\text{EC.32})$$

where the function $\omega(\mathbf{q}, \mathbf{u}) = \sum_{i=1}^M \pi_i(q_i, u_i)$, the optimal-transport cost $d(\cdot, \cdot)$ is defined in (3) with L_2 -norm, and the ambiguity set is specified by mean and covariance information, *i.e.*,

$$\mathcal{A} = \{ G \in \mathcal{P}_M \mid \mathbb{E}_G[\tilde{\mathbf{v}}] = \boldsymbol{\mu}, \mathbb{E}_G[(\tilde{\mathbf{v}} - \boldsymbol{\mu})(\tilde{\mathbf{v}} - \boldsymbol{\mu})^\top] = \boldsymbol{\Sigma} \}. \quad (\text{EC.33})$$

PROPOSITION EC.3. For the ambiguity set (EC.33) with mean and covariance information, the misspecification-averse multi-product newsvendor problem (EC.32) is equivalent to

$$\begin{aligned} & \max t + \boldsymbol{\lambda}^\top \boldsymbol{\mu} + \langle \mathbf{Q}, \boldsymbol{\Sigma} + \boldsymbol{\mu}\boldsymbol{\mu}^\top \rangle \\ & \text{s.t. } t + \boldsymbol{\lambda}^\top \mathbf{v} + \langle \mathbf{Q}, \mathbf{v}\mathbf{v}^\top \rangle \leq \sum_{i \in [M]} \Psi_i(\alpha, q_i, v_i) \quad \forall \mathbf{v} \geq 0 \\ & \mathbf{Q} \succeq \mathbf{0}, \mathbf{q} \geq 0, \end{aligned} \quad (\text{EC.34})$$

where for each $i \in [M]$,

$$\Psi_i(\alpha, q_i, v_i) = \begin{cases} \min\{\alpha v_i^2, p q_i\} - c_i q_i & 0 \leq q_i \leq \frac{p_i}{4\alpha} \\ \alpha v_i^2 - c_i q_i & q_i > \frac{p_i}{4\alpha}, 0 \leq v_i \leq \frac{p_i}{2\alpha} \\ p \cdot \min\left\{v_i - \frac{p_i}{4\alpha}, q_i\right\} - c_i q_i & q_i > \frac{p_i}{4\alpha}, v_i > \frac{p_i}{2\alpha}. \end{cases} \quad (\text{EC.35})$$

Proof. By the definition of $d(F, \mathcal{A})$, problem (EC.32) is equivalent to

$$\max_{\mathbf{q} \geq 0} \min_{F \in \mathcal{P}_M, G \in \mathcal{A}} \left\{ \mathbb{E}_F \left[\sum_{i \in [M]} \pi_i(q_i, \tilde{u}_i) \right] + \alpha \cdot d(F, G) \right\}.$$

Leveraging the multidimensional version of the interchangeability principle characterized in Lemma EC.3, we arrive at

$$\max_{\mathbf{q} \geq 0} \min_{G \in \mathcal{A}} \mathbb{E}_G \left[\min_{\mathbf{v} \geq 0} \left\{ \sum_{i \in [M]} \pi_i(q_i, u_i) + \alpha \sum_{i \in [M]} (u_i - \tilde{v}_i)^2 \right\} \right],$$

by noting that the innermost optimization problem is separable concerning products, which further reduces

$$\max_{\mathbf{q} \geq 0} \min_{G \in \mathcal{A}} \mathbb{E}_G \left[\sum_{i \in [M]} \min_{u_i \geq 0} \left\{ \pi_i(q_i, u_i) + \alpha \cdot (u_i - \tilde{v}_i)^2 \right\} \right].$$

For any fixed $v_i \geq 0$, defining $\Psi_i(\alpha, q_i, v_i) = \min_{u \geq 0} \{\pi_i(q_i, u) + \alpha(u - v_i)^2\}$ (see Lemma EC.4 for its closed-form expression) and leveraging a standard duality result for moment problem (see, *e.g.*, Hanasusanto et al. 2015), we then obtain the desired result immediately. \square

Recall from Natarajan et al. (2018) that the ambiguity-averse multi-product newsvendor problem

$$\max_{\mathbf{q} \geq 0} \min_{G \in \mathcal{A}} \mathbb{E}_G[\omega(\mathbf{q}, \tilde{\mathbf{v}})]$$

admits an equivalent dual reformulation

$$\begin{aligned} & \max t + \boldsymbol{\lambda}^\top \boldsymbol{\mu} + \langle \mathbf{Q}, \boldsymbol{\Sigma} + \boldsymbol{\mu}\boldsymbol{\mu}^\top \rangle \\ & \text{s.t. } t + \boldsymbol{\lambda}^\top \mathbf{v} + \langle \mathbf{Q}, \mathbf{v}\mathbf{v}^\top \rangle \leq \sum_{i \in [M]} \pi_i(q_i, v_i) \quad \forall \mathbf{v} \geq 0 \\ & \mathbf{Q} \succeq \mathbf{0}, \mathbf{q} \geq 0, \end{aligned} \quad (\text{EC.36})$$

which involves 2^M quadratic constraints by a complete expansion of the function $\sum_{i \in [M]} \pi_i(q_i, v_i)$, and is already known to be *intractable* due to the full covariance structure (Hanasusanto et al. 2015, Natarajan and Teo 2017). Clearly, the function $\Psi_i(\alpha, q_i, v_i)$ with the formulation (EC.35) is more complicated than the newsvendor profit function $\pi_i(q_i, v_i)$. Therefore, the misspecification-averse problem (EC.34), compared to (EC.36), can be even more challenging to solve.

Nevertheless, we can adapt the decision-rule approaches to solve the problem (EC.34) approximately. For instance, we can identify a pair of lower and upper bound of the problem (EC.34), by noting that for any $i \in [M]$, $q_i \geq 0$ and $v_i \geq 0$,

$$L_i(\alpha, q_i, v_i) = p_i \cdot \min \left\{ v_i - \frac{p_i}{4\alpha}, q_i \right\} - c_i q_i \leq \Psi_i(\alpha, q_i, v_i) \leq \min \{ \alpha v_i^2, p_i q_i \} - c_i q_i = U_i(\alpha, q_i, v_i).$$

Replacing $\Psi_i(\alpha, q_i, v_i)$ with $L_i(\alpha, q_i, v_i)$ (resp., $U_i(\alpha, q_i, v_i)$) in problem (EC.34), we then obtain a lower bound (resp., upper bound) of problem (EC.34). The resulting problems inherit a similar structure to problem (EC.36), and hence can be approximately solved via the quadratic decision rules or semi-definite programming relaxations (Hanasusanto et al. 2015, Natarajan and Teo 2017).

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